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CONTRACT NUMBER NAS8-21155  
 SAFE OPERATING AREA  
 DETERMINATION FOR PREVENTION  
 OF SECOND BREAKDOWN

CASE 5  
 DV

Performed for

NATIONAL AERONAUTICS & SPACE ADMINISTRATION  
 GEORGE C. MARSHALL SPACE FLIGHT CENTER  
 HUNTSVILLE, ALABAMA

By

THE BENDIX CORPORATION  
 THE BENDIX SEMICONDUCTOR DIVISION  
 HOLMDEL, NEW JERSEY

THE BENDIX CORPORATION  
BENDIX SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

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FOREWORD  
SAFE OPERATING AREA (SOAR)

The Bendix SOAR principle is a method of specifying the Safe Operating Area for a transistor in a given application. SOAR defines the region which encloses all of the points representing simultaneous values of the collector current and the collector-to-emitter voltage which a transistor can safely handle under specified conditions of base current, time, junction temperature and average power dissipation. With transistors specified under the Bendix SOAR technique, second breakdown is virtually eliminated.

This report characterizes the Safe Operating Area of specific power transistors. The use of these Safe Operating Areas by designers will help avoid transistor second breakdown through design and quality considerations.

## 1.0 INTRODUCTION

The purpose of this contract was to determine the true dynamic characteristics, Safe Operating Area (SOAR), of selected power transistors used in critical space applications.

Testing to determine device parameters was made in accordance with JEDEC "Suggested Standard 65" and similiar to MIL-STD-750A. Reference to the aforementioned documents is made, where applicable, in the specification section of this Final Report.

Copies of the JEDEC "Suggested Standard 65" are available from:

Electronic Industries Association  
2001 Eye Street, N.W.  
Washington, D.C. 20006

The MIL-STD-750A document may be obtained from:

Commanding Officer  
Naval Publications & Forms Center  
5801 Tabor Avenue  
Philadelphia, Pennsylvania 19120

## 2.0 CONCLUSIONS

The specifications and SOAR curves generated as a result of this Contract verifies the actual power handling capability for each type of transistor. This information will serve to:

1. Provide valid derating information to establish necessary safety margins;
2. Provide guidelines for circuit analysis;
3. Provide documented Reliability Data;
4. Provide a means to improve the overall quality of devices now used by MSFC.

The individual reports contain a detailed analysis of Safe Operating Area for devices not previously characterized for SOAR. Highlights from each device are summarized here as a guide to design personnel.

2N1486 Manufacturer A. Suggest change of spec.  
 $(\theta_{J-C} = 3^{\circ}\text{C/W})$  to extend DC power rating. 33W at  $T_C = 100^{\circ}\text{C}$  provides safety margin for continuous operation. High energy device ideal for switching inductive loads.

2N1724 Manufacturer B. Device can sustain the rated power for all operating conditions.

2N1016D Manufacturer C. Device is capable of handling the manufacturers power rating.

2N1514 Manufacturer H. Marginal  $h_{FE}$  at 6A. Review circuits.

2N2102 Manufacturers D & J. Composite SOAR curves indicate that devices may vary from lot to lot by different manufacturers.

2N2034A Manufacturer E. Good energy dissipating capability.

2N2126 Manufacturer C.  $I_{CEO}$  should be part of specification to insure forward biased condition at high  $V_{CE}$  and low collector current.

2N657A Manufacturer E. A small device, heats up quickly causing failure at lower than published parameters.

2N697 Manufacturers G & E. Composite SOAR curves indicates a specification review of manufacturers E's device.

2N2880 Manufacturer H. Suggest continuous maximum DC rating be reduced from 5A to 3A. ( $I_E = 5.5A$  discolors leads.)

The following devices have recently been registered by Bendix and are not specifically covered by this Contract, however the results and data are included without charge, as additional information for NASA personnel. The format used in the presentation of this data was recently developed for the registration of transistor specifications.

SOAR Characteristics:

	T <sub>STG</sub> max	T <sub>STG</sub> min	T <sub>J</sub>	V <sub>CEX</sub>	V <sub>EBO</sub>	V <sub>CBO</sub>	I <sub>C</sub>	P <sub>T</sub>
2N5559	+200	-65°C	200°C	100V	7V	150V	10A	100W
2N5560	+200	-65°C	200°C	120V	8V	175V	30A	150W

The information obtained by this contract provides invaluable assistance to all concerned with the application, selection, performance, and most important, reliability of semiconductor devices in critical NASA systems.

The effect of SOAR evaluation is far-reaching, and should be a mandatory requirement for all power semiconductors being used by NASA in its Aeronautical and Space programs.

The Bendix Semiconductor Division hereby proposes that NASA continue this program with Bendix to further assist NASA in achieving the highest levels of Reliability in their programs.

**Silicon Power Transistor  
Type 2N1486**

**SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN**

**-- Manufacturer A --**

**Performed for**

**NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA**

**Contract No. NAS8-21155**

**THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY**

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
1.0.0 <u>General Description</u>		
1.1.0      Type -- NPN		
1.2.0      Material -- Silicon		
2.0.0 <u>Mechanical Data</u>		
2.1.0      Outline -- T0-8		
2.2.0      Terminal Designation		
	1 -- Emitter	
	2 -- Base	
	3 -- Collector	
	case -- Collector	
3.0.0 <u>Maximum Ratings</u>		
3.1.0      Temperature		
3.1.1 $T_{STG(max)} = +200^{\circ}\text{C}$	<u>JS-6-T1.2</u>	
3.1.1 $T_{STG(min)} = -65^{\circ}\text{C}$	<u>JS-6-T1.1</u>	
3.1.2 $T_J = 200^{\circ}\text{C}$	<u>JS-6-T2</u>	
		$T_C = 100^{\circ}\text{C}, V_{CB} = 55\text{V}, P_T = 14.3\text{W}$
3.2.0      Voltage		
3.2.1 $V_{CBO} = 100\text{V}$	<u>JS-6-T3</u>	or MIL-STD-750, method 3001.1
3.2.2 $V_{EBO} = 12\text{V}$	<u>JS-6-T4</u>	or MIL-STD-750A method 3026.1
3.2.3 $V_{CEX} = 100\text{V}$	<u>JS-6-T5-2.1</u>	
		$I_C = 3.0\text{A}, V_{CC} = 100\text{V}, R_L = 33\Omega,$
		$L = 1\text{mH}^*, CR -- 1N1204, V_{BB1} = 12\text{V},$
		$R_{BB1} = 10\Omega, V_{BB2} = 3\text{V}, R_{BB2} = 10\Omega$
		Duty Cycle = 2%, $t_p = 1.65 \text{ ms.}$
		*Miller No. 7871 in series with Miller No. 7825-3
3.3.0      Current		
3.3.1 $I_C = 3\text{A}$	<u>JS-6-T6</u> , $I_B = 300\text{mA}, T_C = 25^{\circ}\text{C}$	

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.3.2	<u>JS-6-T8</u> $T_C = 25^\circ C$
3.3.3 $I_C = -3.5A$	<u>JS-6-T10</u> $I_B = 500mA, T_C = 25^\circ C$
3.4.0      Power	
3.4.1 $P_T = 14.3W$	<u>JS-6-T12</u> $T_C = 100^\circ C, V_{CB} = 55V, I_C = .26A$ Derating Factor = $.143 \text{ W}/^\circ C$
3.4.2 $P_{TM} = I_C V_{CC} = 150W$	<u>JS-6-T13</u> $T_C = 100^\circ C, V_{CC} = 50V, V_{BB} = 3V$ $R_{BB} = 10\Omega, I_C = 3A, \text{ Pulse Width} = 5ms,$ Duty Cycle = 5%, $t_r \leq 50\mu s,$ $t_f \leq 50\mu s$
3.5.0      Maximum Operating Condition	
3.5.1      Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> (See Figure 1) <u>Test Point</u> (See 3.4.1)
3.5.2      Pulsed Forward Biased SOAR	<u>JS-6-T-14</u> (See Figure 2) <u>Test Points:</u> $T_C = 100^\circ C, V_{BB} = 3V, R_{BB} = 10\Omega,$ $t_r \leq 50\mu s, t_f \leq 50\mu s, I_C = 3A,$ Duty Cycle $\leq 1\%, R_S = 0.1\Omega$ 1. For $t_p = 50ms: V_{CC} = 10V$ 2. For $t_p = 20ms: V_{CC} = 25V$

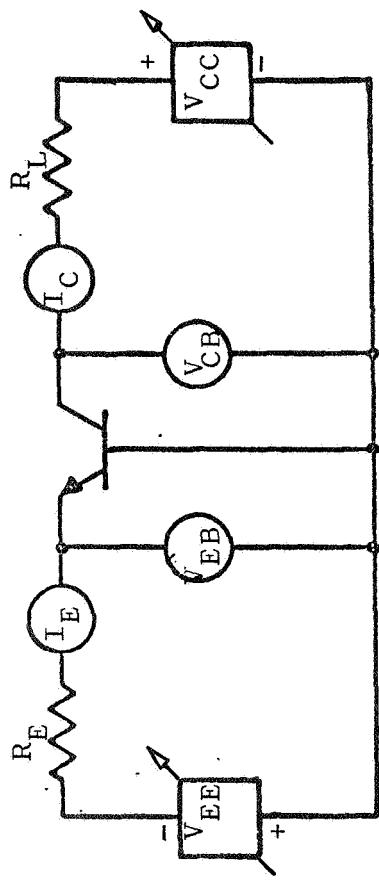
<u>Item</u>		<u>Test Methods and Test Conditions</u>
3.5.2	Pulsed Biased (Cont'd) Continuous DC SOAR	3. For $t_p = 10\text{ms}$ , $V_{CC} = 40\text{V}$ 4. For $t_p = 5\text{ms}$ , $V_{CC} = 50\text{V}$
3.6.0	SOAR Switching between Saturation and Cutoff	
3.6.1	Resistive Load	<u>JS-6-T5-2.1</u> with $L = 0$ and CR disconnected. See (Figure 3)
		<u>Test Points:</u>
		$R_{BB1} = 10\Omega$ , $R_{BB2} = 10\Omega$ , $V_{BB1} = 12\text{V}$ , $V_{BB2} = 3\text{V}$ , $T_C = 100^\circ\text{C}$ , $t_f \leq 50\mu\text{s}$ (Coll. Current); $t_r \leq 50\mu\text{s}$ (Coll. Current), $R_S = 0.1\Omega$ , $I_C = 3\text{A}$ , $V_{CC} = 100\text{V}$
3.6.2	Clamped Inductive Load	<u>JS-6-T5.1</u> (See Figure 4) Test Points: (See 3.2.3)
3.6.3	Unclamped Inductive Load	<u>JS-6-T5.1</u> and CR disconnected (See Figure 5)
		<u>Test Points:</u>
		1. $V_{BB1} = 12\text{V}$ , $L = 20\text{mH}^*$ $R_{BB1} = 10\Omega$ , $R_L = 4.1\Omega$ $V_{BB2} = 3\text{V}$ , $V_{CC} = 12.5\text{V}$ $R_{BB2} = 10\Omega$ , $f = 10\text{Hz}$ $R_S = 0.1\Omega$ , $d = 15\%$ .

\*Series Stancor C-2688

<u>Item</u>	<u>Test Methods and Test Conditions</u>			
3.7.0	Shorted Class B SOAR	(See Figure 6)		
<u>Test Points:</u>				
$I_C(\text{peak}) = .75A$ , $V_{CC} = 55V$ , $R_S = 0.1\Omega$				
$R_{BB1} = 10\Omega$ , $R_{BB2} = 10\Omega$ , $f = 20\text{Hz}$ ,				
$T_C = 100^\circ\text{C}$				
4.0.0	<u>Electrical Characteristics</u>			
Maximum Limits unless other otherwise noted.				
Technique:				
DC = continuous operation				
C.T. = Curve Tracer				
P = $300\mu\text{s}$ Pulse, 2% Duty Cycle				
4.1.0	Static			
4.1.1	$I_{CEV} = 10\mu\text{A}$	$V_{CEV} = 100V$ , $V_{EB} = 1.5V$ , Technique = C.T.		
4.1.2	$I_{CBO} = 15\mu\text{A}$	$V_{CB} = 30V$ , Technique = C.T. .		
4.1.3	$I_{CBO} = 750\mu\text{A}$	$V_{CB} = 30V$ , $T_C = 150^\circ\text{C}$ , Technique = C.T.		
4.1.4	$I_{EBO} = 15\mu\text{A}$	$V_{EB} = 12V$ , technique = C.T.		
4.1.5	$I_{CEO} = 50\mu\text{A}$	$V_{CEO} = 50V$ , technique = C.T.		
4.1.6	$V_{CEO} = 55V$ min.	$I_{CEO} = 100mA$ , technique = C.T.		
4.1.7	$V_{CEV} = 100V$	$I_C = 100mA$ , $V_{EB} = 1.5V$ , technique = C.T.		
4.1.8	$h_{FE} = 35$ min. $h_{FE} = 100$ max.	$V_{CE} = 4V$ , $I_C = 750mA$ , technique = C.T.		
4.1.9	$V_{CE[\text{SAT}]} = .75V$	$I_C = 0.75A$ , $I_B = .04A$ , technique = C.T.		

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
4.1.10 $V_{CE}[\text{SAT}] = 2.5V$		$I_C = 3A, I_B = 300mA$ , technique = C.T.
4.1.11 $V_{BE}[\text{SAT}] = 3.0V$		$I_C = 3A, I_B = 300mA$ , technique = C.T.
4.1.12 $V_{BE} = 2.5V$		$I_C = 750mA, V_{CE} = 4V$ , technique = C.T.
4.2.0      Dynamic		
4.2.1 $f_{hfb} = 1\text{MHz min.}$	$I_C = 5mA, V_{CE} = 28V$	
	$f_{hfb} = 10 \text{ MHz max.}$	
4.2.2 $C_{obo} = 175\text{pF}$		$V_{CB} = 40V$ , MIL-STD -750 method 3236
5.0.0      Thermal Characteristics		
5.1.0 $\Upsilon_J = 40mS \text{ min.}$	$I_C = 1A, V_{CE} = 10V, T_C = 25^\circ\text{C}$	MIL-STD -750 method 3146.1
5.2.0 $\Theta_{J-C} = 7.0^\circ\text{C/W}$	$I_C = 1A, V_{CE} = 10V, T_C = 25^\circ\text{C}$	MIL-STD -750 method 3136
5.3.0 $\Theta_{J-A} = 100^\circ\text{C/W}$	$I_C = .5A, V_{CE} = 3.5V$	MIL-STD -750 method 3151

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CEO}$

Test Circuit: JS-6-T12

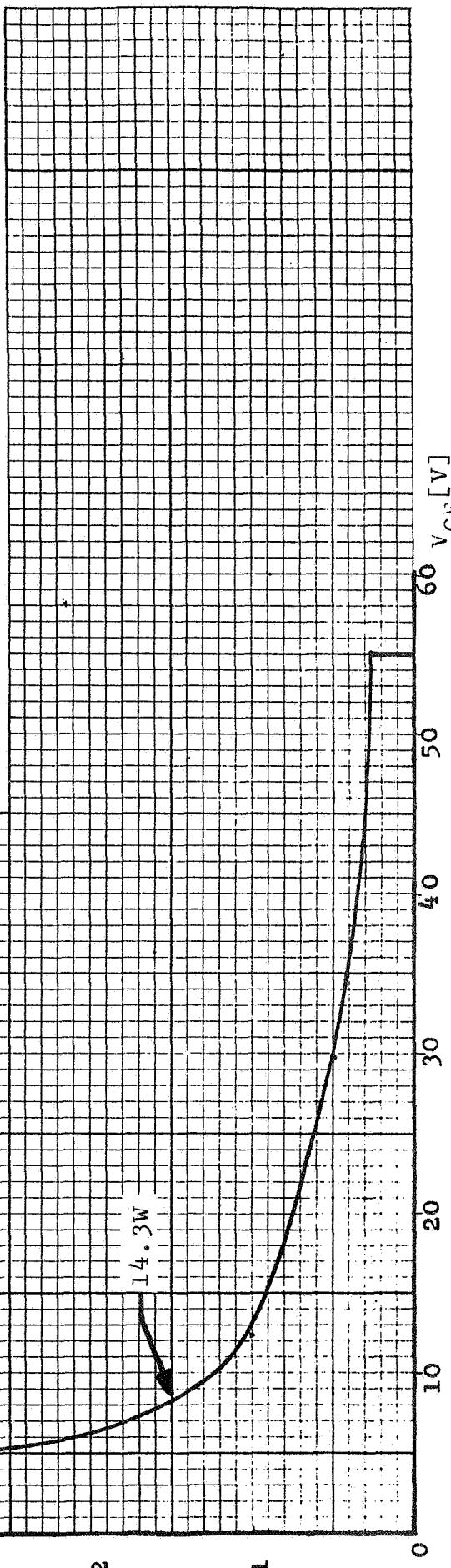
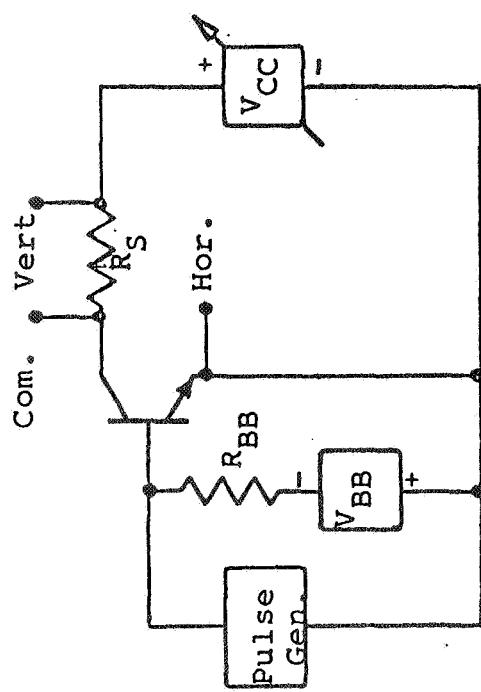


Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

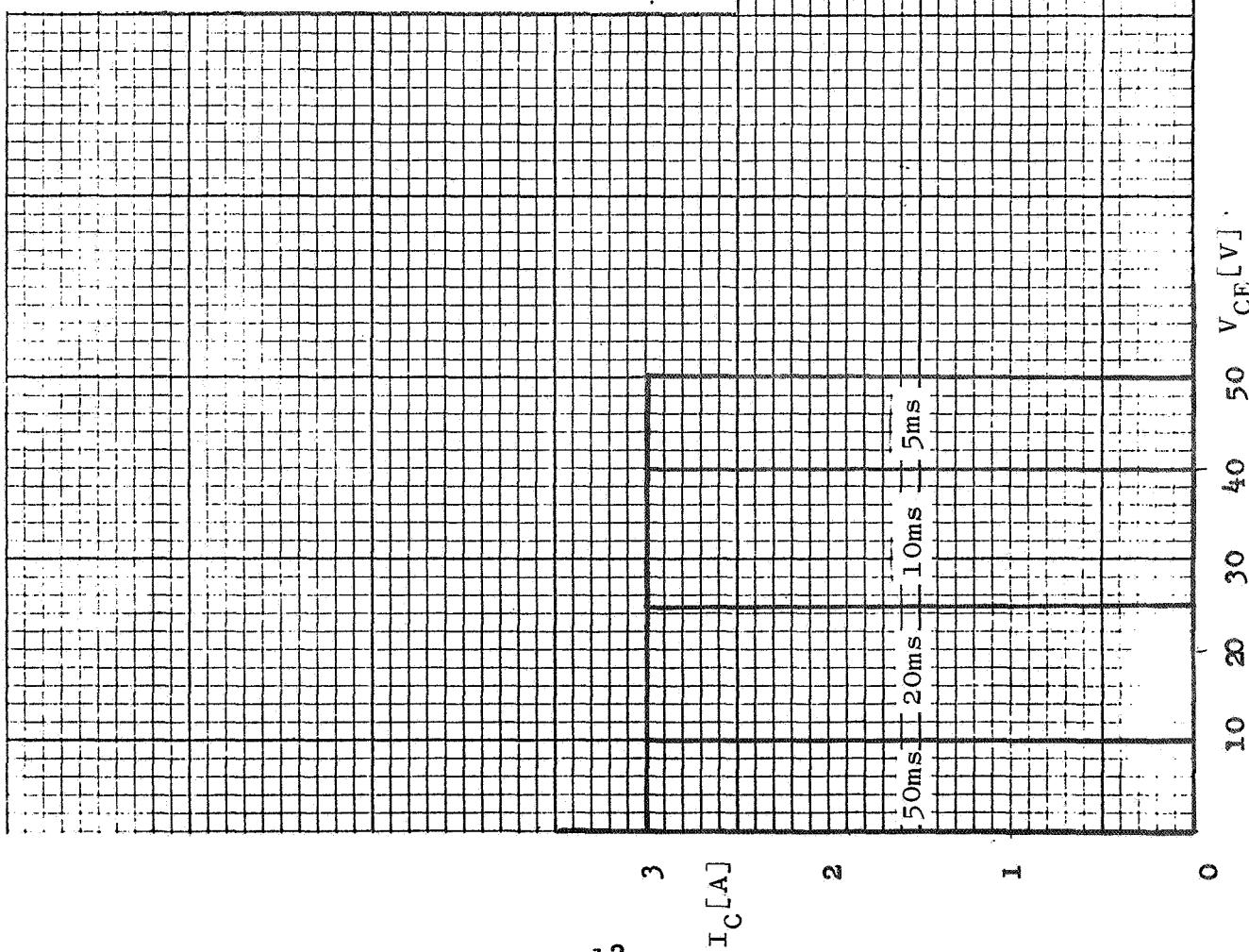
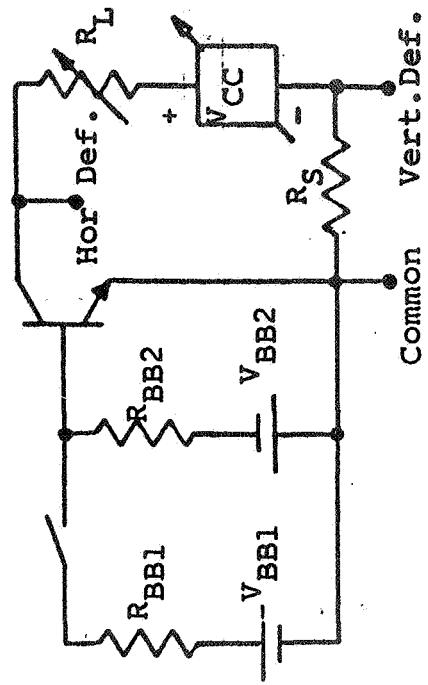


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

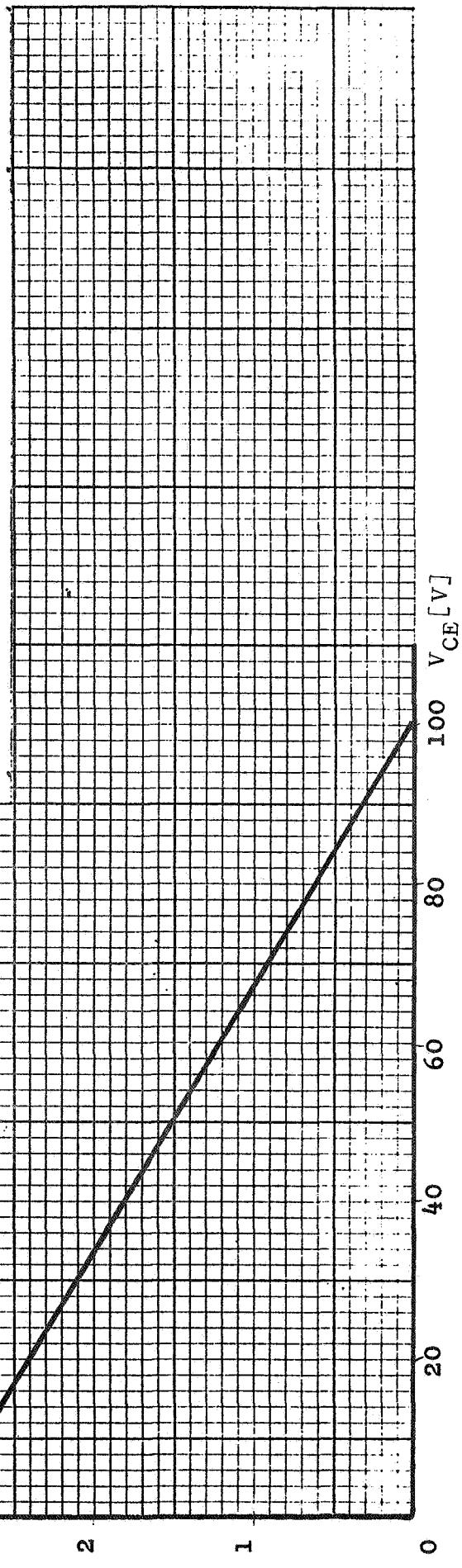
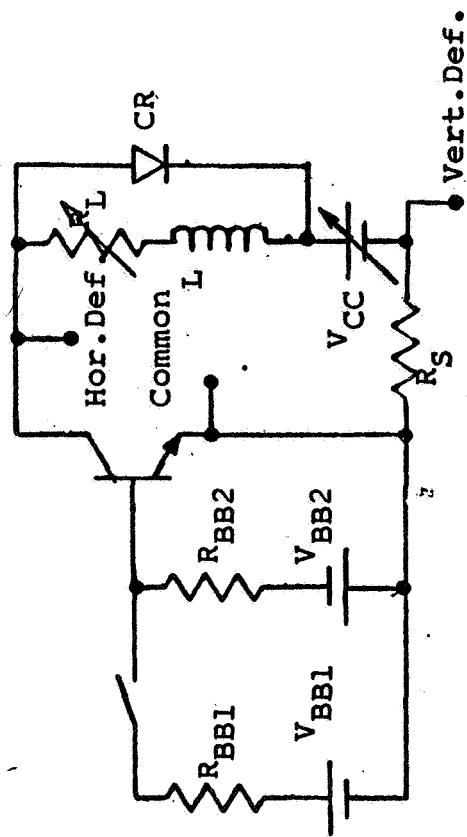
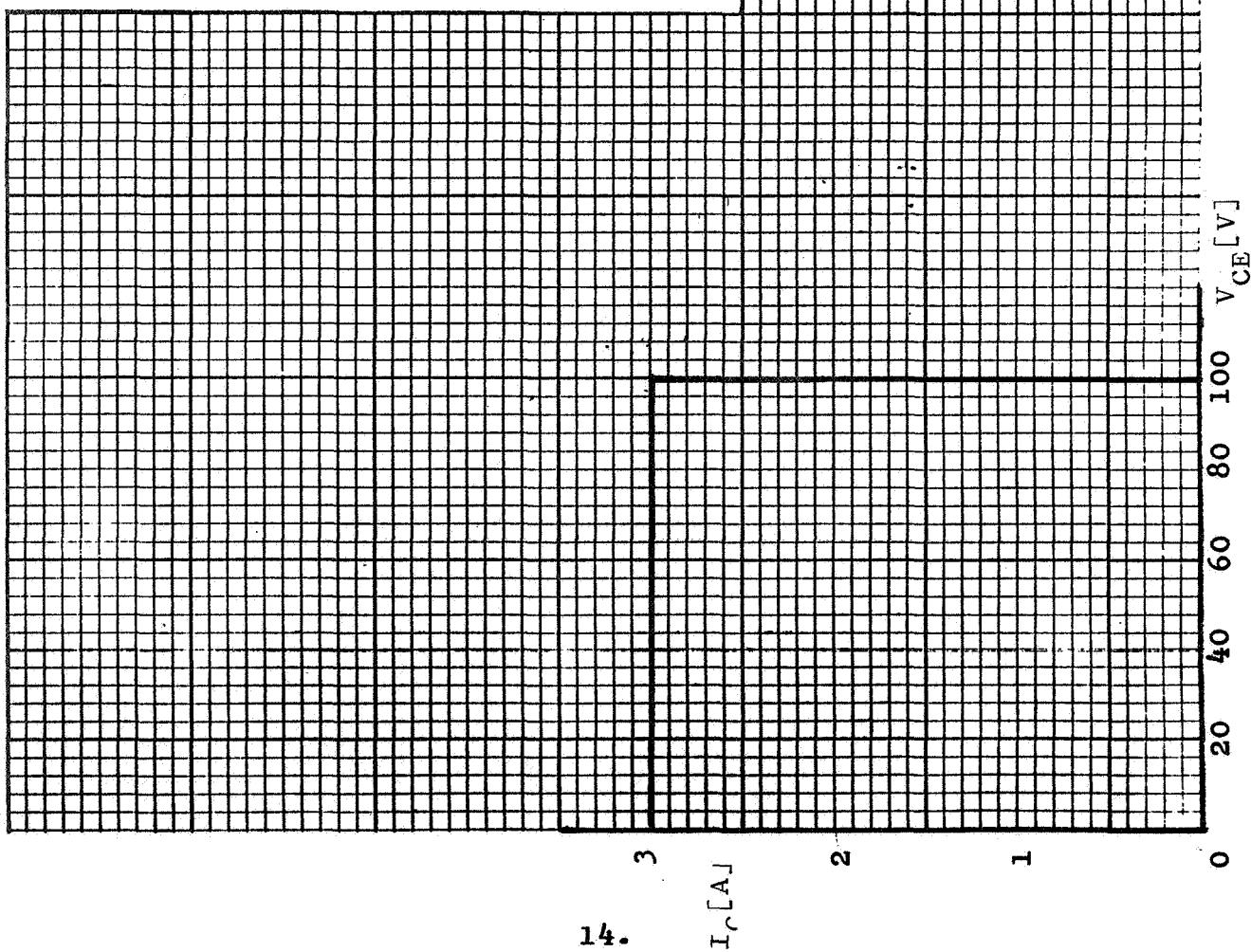


Figure 3

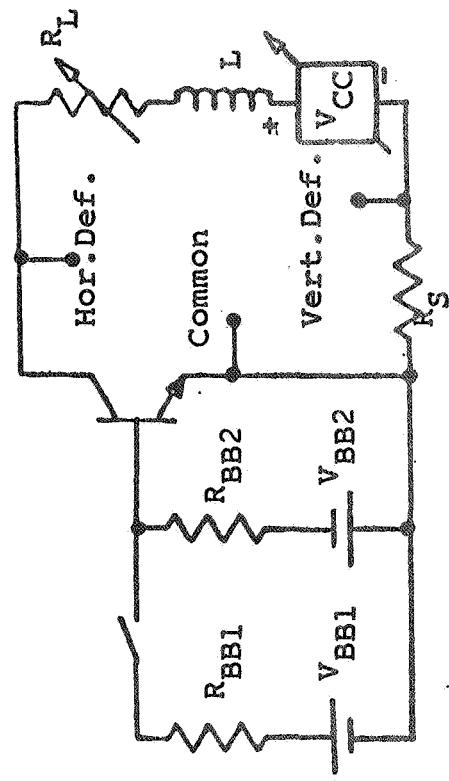
SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1



SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

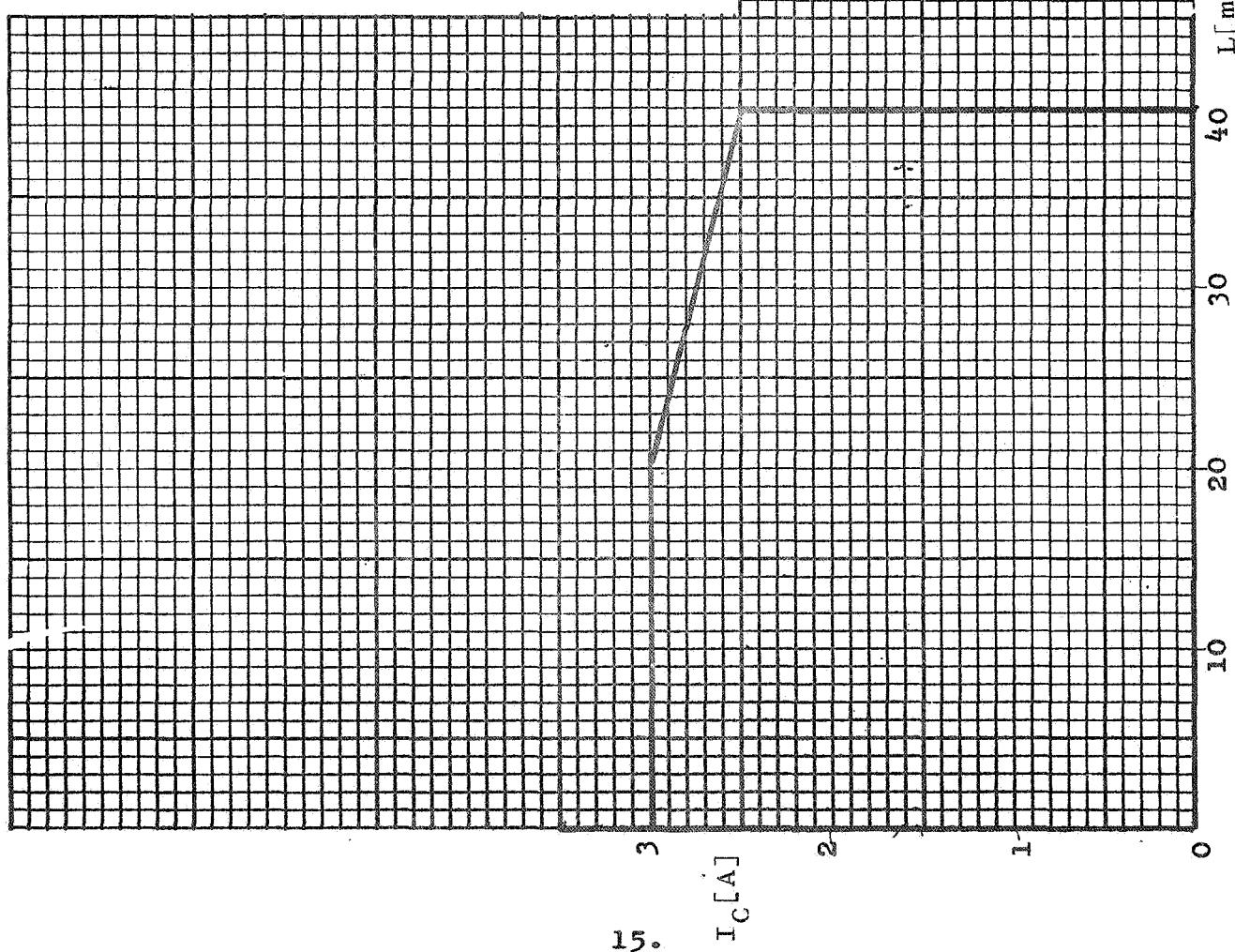


Figure 5

SHORTED CLASS B SOAR

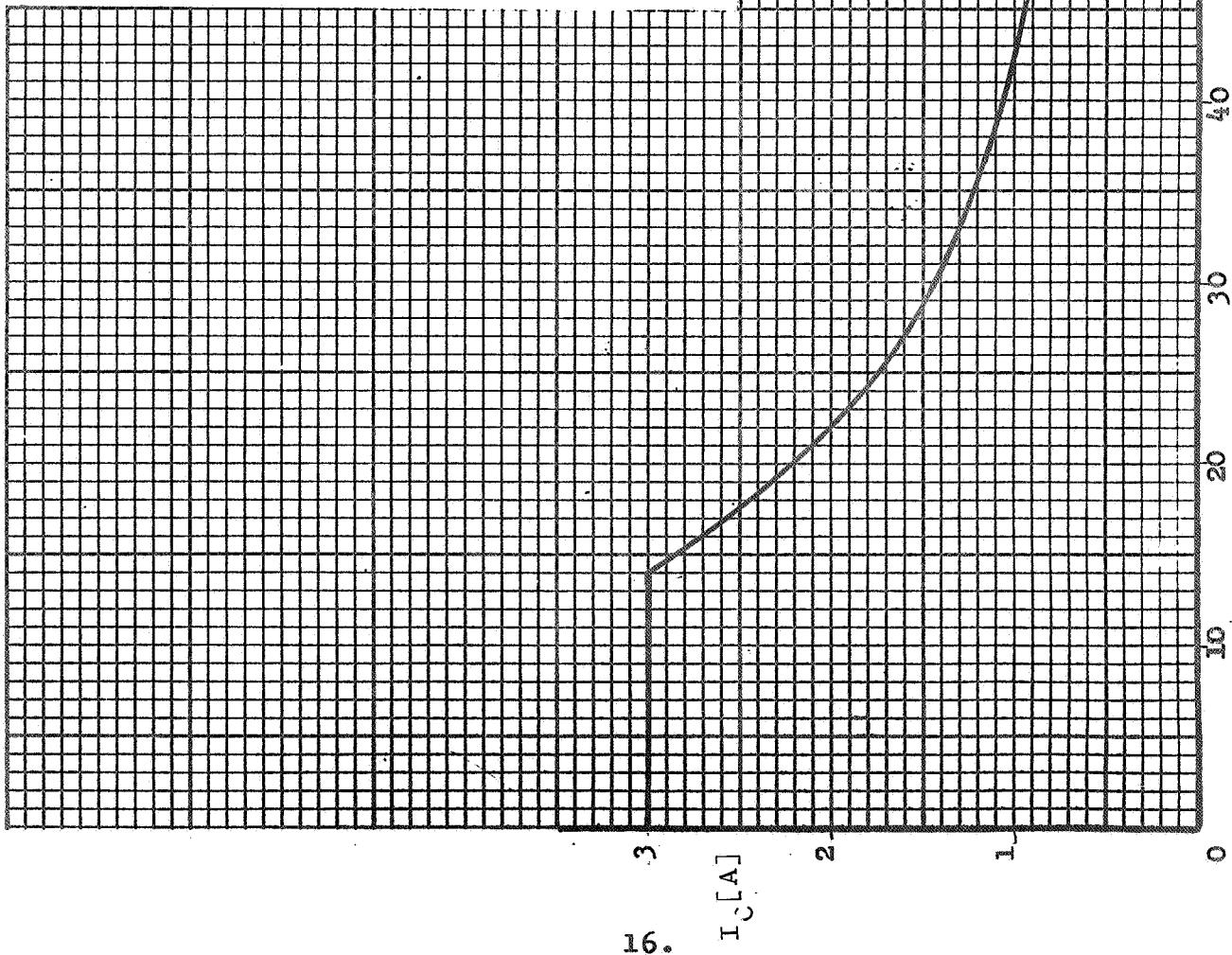
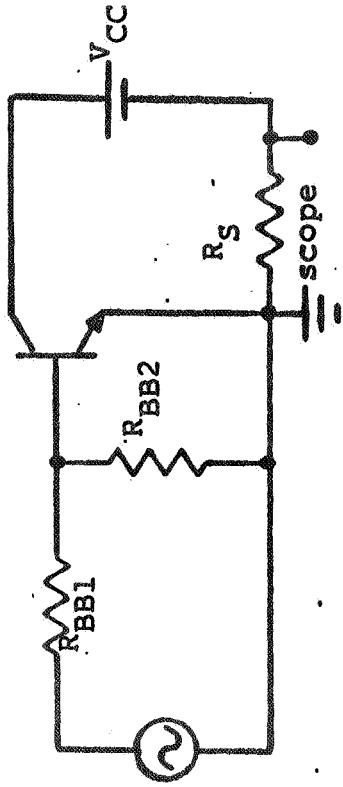


Figure 6

SILICON POWER TRANSISTOR

< Type 2N1724 >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer B --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Method and Test Conditions</u>	
1.0.0	<u>General Description</u>	
1.1.0	Type -- NPN	
1.2.0	Material -- Silicon	
2.0.0	<u>Mechanical Data</u>	
2.1.0	Outline -- TO-61	
2.2.0	Terminal Designation 1 -- Emitter 2 -- Base 3 -- Collector case -- Collector	
2.2.1	Maximum Stud Torque -- 30 in. lb.	
3.0.0	<u>Maximum Ratings</u>	
3.1.0	Temperature	
3.1.1	$T_{STG(max)} = +200^{\circ}\text{C}$	<u>JS-6-T1.1</u> (JEDEC Suggested Standard: "Test Procedures for
	$T_{STG(min)} = -65^{\circ}\text{C}$	<u>JS-6-T1.2</u> Verifications of Maximum Ratings")
3.1.2	$T_J(max) = +175^{\circ}\text{C}$	<u>JS-6-T2</u> $T_C = 100^{\circ}\text{C}$ , $V_{CB} = 10\text{V}$ , $I_C = 5\text{A}$
3.1.3	$T(\text{Lead}) = 230^{\circ}\text{C}$	Distance from case = $\frac{1}{4}$ in. Time = 10s
3.2.0	Voltage	$T_C = 25^{\circ}\text{C}$
3.2.1	$V_{CBO} = 120\text{V}$	<u>JS-6-T3</u> or MIL-STD-750A Method 3001.1
3.2.2	$V_{EBO} = 10\text{V}$	<u>JS-6-T4</u> or MIL-STD-750A Method 3026.1

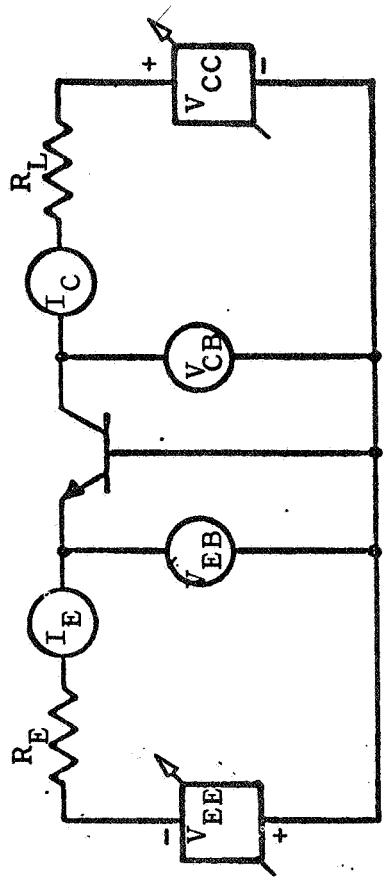
<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.2.3 $V_{CEV} = 80V$	<u>JS-6-T5-2.1</u> $I_C (V_{CE} = V_{CEX}) = 7.5A$ $V_{CC} = 80V, R_L = 10.3\Omega, L = 1mH,$ $(Miller \#7870), CR = 1N1204, V_{BB1} = 15V,$ $R_{BB1} = 5\Omega, V_{BB2} = 5V, R_{BB2} = 10\Omega,$ $Pulse width = 10ms, Duty Cycle = 10\%,$ $R_S = 0.1\Omega$
3.3.0      Current	
3.3.1 $I_C = 5A$	<u>JS-6-T6</u> $I_B = 1A, T_C = 25^{\circ}C$
3.3.2 $I_{CM} = 7.5A$	<u>JS-6-T7</u> $T_C = 25^{\circ}C, R_S = 0.1\Omega, V_{BB} = 5V,$ $R_{BB} = 10\Omega$ $Pulse Amplitude = 5.3V, R source = 1\Omega$ $Pulse Width = 20ms, Duty Cycle = 20\%$ $t_r \leq 50\mu s, t_f \leq 50\mu s$
3.3.3 $I_B = 2A$	<u>JS-6-T8</u> $T_C = 25^{\circ}C$
3.3.4 $I_E = 6A$	<u>JS-6-T10</u> $I_B = 1A, T_C = 25^{\circ}C$
3.4.0      Power	
3.4.1 $P_T = 50W$	<u>JS-6-T12</u> $T_C = 100^{\circ}C, V_{CB} = 80V, I_C = 625mA$ Derating factor = $0.667W/^{\circ}C$

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.4.2 $P_{TM} = 600W$	<u>JS-6-T13</u> $T_C = 100^\circ C$ , $V_{CC} = 80V$ , $I_C = 7.5A$ $V_{BB} = 5V$ , $R_{BB} = 10\Omega$ , Pulse Width = 1ms, Duty Cycle = 2%, $t_r \leq 50\mu s$ , $t_f \leq 50\mu s$
3.5.0      Maximum Operating Conditions	
3.5.1      Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> (See Figure 1) <u>Test Point:</u> (See 3.4.1)
3.5.2      Pulsed Forward Biased SOAR	<u>JS-6-T14</u> (See Figure 2) <u>Test Point:</u> $T_C = 100^\circ C$ , $V_{BB} = 5V$ , $R_{BB} = 10\Omega$ , $I_C = 7.5A$ , $R_S = 0.1\Omega$ , $t_r \leq 50\mu s$ , $t_f \leq 50\mu s$ , Duty Cycle $\leq 5\%$ 1. For $t_p = 3ms$ : $V_{CC} = 55V$ 2. For $t_p = 2ms$ : $V_{CC} = 65V$ 3. For $t_p = 1ms$ : $V_{CC} = 80V$
3.6.0      SOAR Switching between Saturation and Cutoff	
3.6.1      Resistive Load	<u>JS-6-T5-2.1</u> with $L = 0$ and CR Disconnected (See Figure 3) <u>Test Points:</u> $T_C = 100^\circ C$ , Duty Cycle = 10%, Coll. Current, $t_r \leq 50\mu s$ , $t_f \leq 50\mu s$ $R_{BB1} = 5\Omega$ , $R_{BB2} = 10\Omega$ , $V_{BB1} = 15V$ , $V_{BB2} = 5V$ , $I_C = 7.5A$ , $V_{CC} = 120V$ , $R_L = 15.6\Omega$ , $R_S = 0.1\Omega$

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.6.2      Clamped Inductive Load	<u>JS-6-T5-2.1</u> (See Figure 4) <u>Test Point:</u> (See 3.2.3)
3.6.3      Unclamped Inductive Load	<u>JS-6-T5-2.1</u> and CR disconnected (See Figure 5) <u>Test Point:</u> [1.] $R_{BB1} = 5\Omega$ , $R_{BB2} = 10\Omega$ , $V_{BB1} = 15V$ , $V_{BB2} = 5V$ , $L = 5mH$ , $0.03\Omega$ (Stancor #C-2689) $I_C = 7.5A$ , $V_{CC} = 18V$ , $R_L = 2\Omega$ , $R_S = 0.1\Omega$ , $d \leq 10\%$ , $T_C = 25^\circ C$ , $t_p = 10ms$ [2.] $R_{BB1} = 5\Omega$ , $R_{BB2} = 10\Omega$ , $V_{BB1} = 8V$ , $V_{BB2} = 5V$ , $L = 20mH$ , $0.22\Omega$ (two in series Stancor #C-2688)
3.7.0      Shorted Class B SOAR (See Figure 6)	$I_C = 2.5A$ , $V_{CC} = 13.5V$ , $R_L = 5\Omega$ , $R_S = 0.1\Omega$ , $T_C = 25^\circ C$ , $d \leq 10\%$ , $t_p = 10ms$
4.0.0 <u>Electrical Characteristics</u>	<u>Test Point:</u> $I_C$ peak = $1.88A$ , $V_{CC} = 80V$ , $R_S = 0.1\Omega$ , $R_{BB1} = 1\Omega$ , $R_{BB2} = 10\Omega$ , $f=20Hz$ , $T_C = 100^\circ C$ $T_C = 25^\circ C$ (unless otherwise noted) Maximum limits unless otherwise noted <u>Technique:</u> DC - Continuous Operation C.T. - Curve Tracer P - $300\mu s$ Pulse, 2% Duty Cycle

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
4.1.0      Static		
4.1.1 $I_{CBO} = 0.5\text{mA}$	$V_{CB} = 3\text{V}$ Technique - C.T.	
4.1.2 $V_{EBF} = 10\text{V}$	$V_{CB} = 80\text{V}$ Technique - C.T.	
4.1.3 $I_{CES} = 1.0\text{mA}$	$V_{CE} = 60\text{V}$ Technique - C.T.	
4.1.4 $I_{CES} = 2.0\text{mA}$	$T_C = 150^\circ\text{C}$ , $V_{CE} = 60\text{V}$ Technique - C.T.	
4.1.5 $I_{CES} = 10\text{mA}$	$T_C = 150^\circ\text{C}$ , $V_{CE} = 120\text{V}$ Technique - C.T.	
4.1.6 $I_{CEO} = 10\text{mA}$	$T_C = 25^\circ\text{C}$ , $V_{CE} = 80\text{V}$ Technique - C.T.	
4.1.7 $I_{EBO} = 10\text{mA}$	$V_{EB} = 10\text{V}$ Technique - C.T.	
4.1.8 $V_{CEO} = 80\text{V}$ min.	$I_C = 0.2\text{A}$ Technique - C.T.	
4.1.9 $h_{FE} = 20$ min	$V_{CE} = 15\text{V}$ , $I_C = 0.1\text{A}$ Technique - C.T.	
4.1.10 $h_{FE} = 20$ min, 90 max	$V_{CE} = 15\text{V}$ , $I_C = 2\text{A}$ Technique - P	
4.1.11 $h_{FE} = 10$ min	$V_{CE} = 2\text{V}$ , $I_C = 5\text{A}$ Technique - P	
4.1.12 $V_{CE(\text{sat})} = 1\text{V}$	$I_C = 2\text{A}$ , $I_B = 0.2\text{A}$ , Technique - C.T.	
4.1.13 $V_{CE(\text{sat})} = 2\text{V}$	$I_C = 7.5\text{A}$ , $I_B = 1.5\text{A}$ Technique - P	
4.1.14 $V_{BE(\text{sat})} = 2\text{V}$	$I_C = 2\text{A}$ , $I_B = 0.2\text{A}$ , Technique - C.T.	
4.1.15 $V_{BE(\text{sat})} = 2.5\text{V}$	$I_C = 7.5\text{A}$ , $I_B = 1.5\text{A}$ Technique - P	
4.2.0      Dynamic		
4.2.1 $h_{fe} = 2.0$ min = 10.0 max	$V_{CE} = 15\text{V}$ , $I_C = 0.5\text{A}$ , $f = 5\text{ MHz}$	
4.2.2 $C_{obo} = 550\text{ pF}$ max	$V_{CB} = 15\text{V}$ , $f = 1\text{MHz}$	
5.0.0      Thermal Characteristics		
5.1.0 $\tau_J \text{ min} = 10\text{ms}$	$V_{CE} = 10\text{V}$ , $I_C = 2\text{A}$ , $T_C = 25^\circ\text{C}$ , MIL-STD-750, Method 3146.1	
5.2.0 $\theta_{JC} = 1.5^\circ\text{C/W}$	$V_{CE} = 10\text{V}$ , $I_C = 2\text{A}$ , $T_C = 25^\circ\text{C}$ MIL-STD-750, Method 3136	

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CEO}$

Test Circuit: JS-6-T12

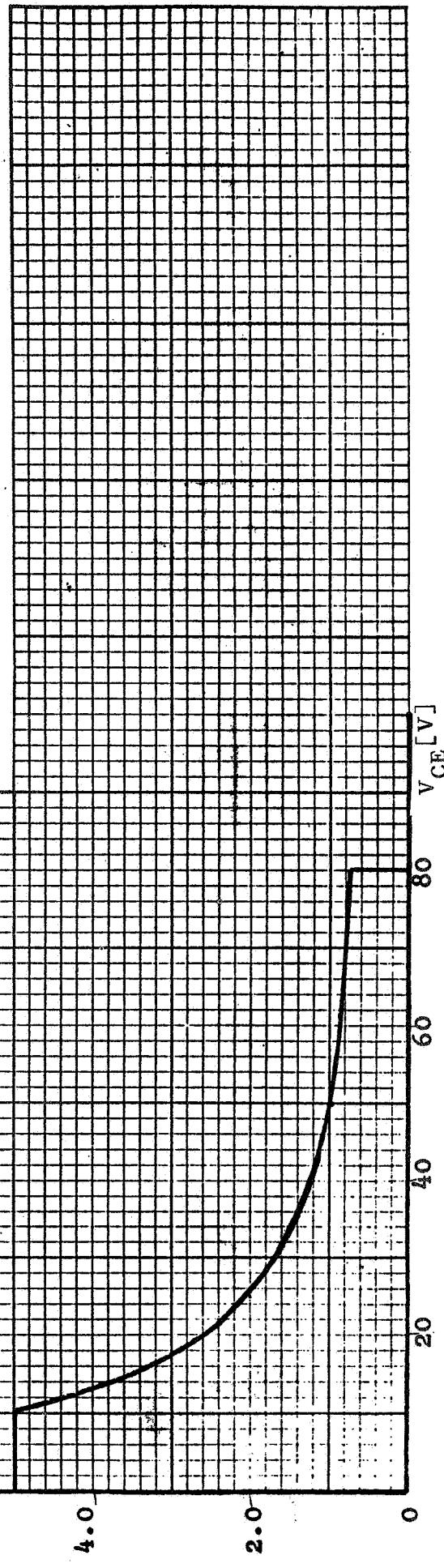
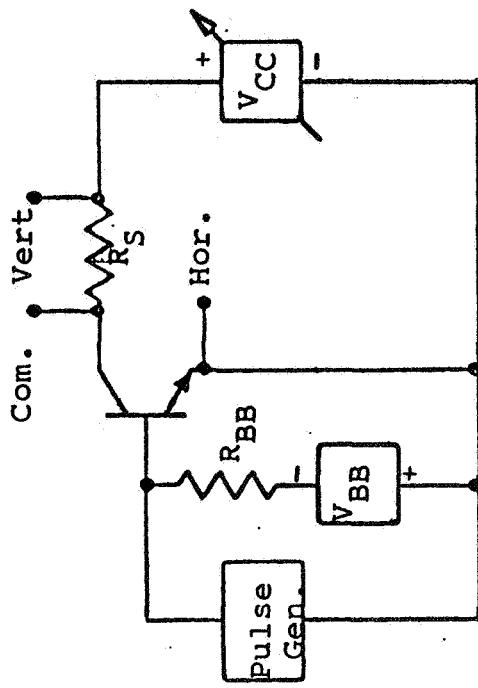


Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

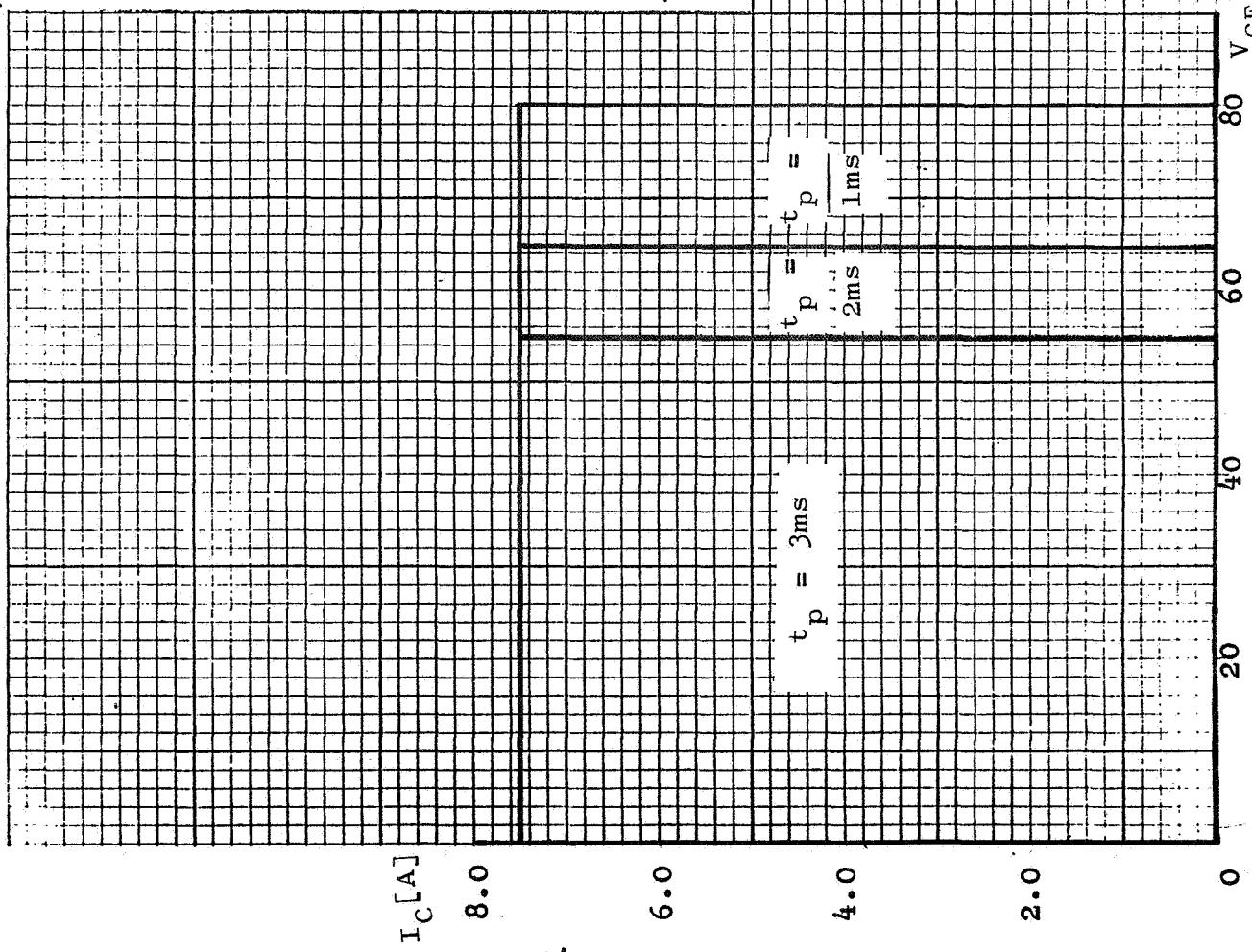
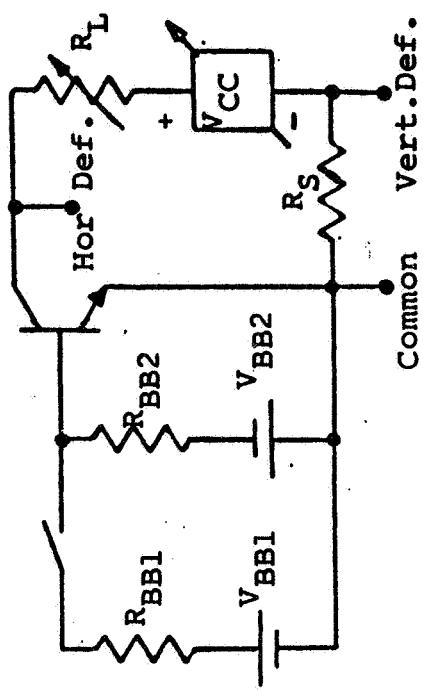


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

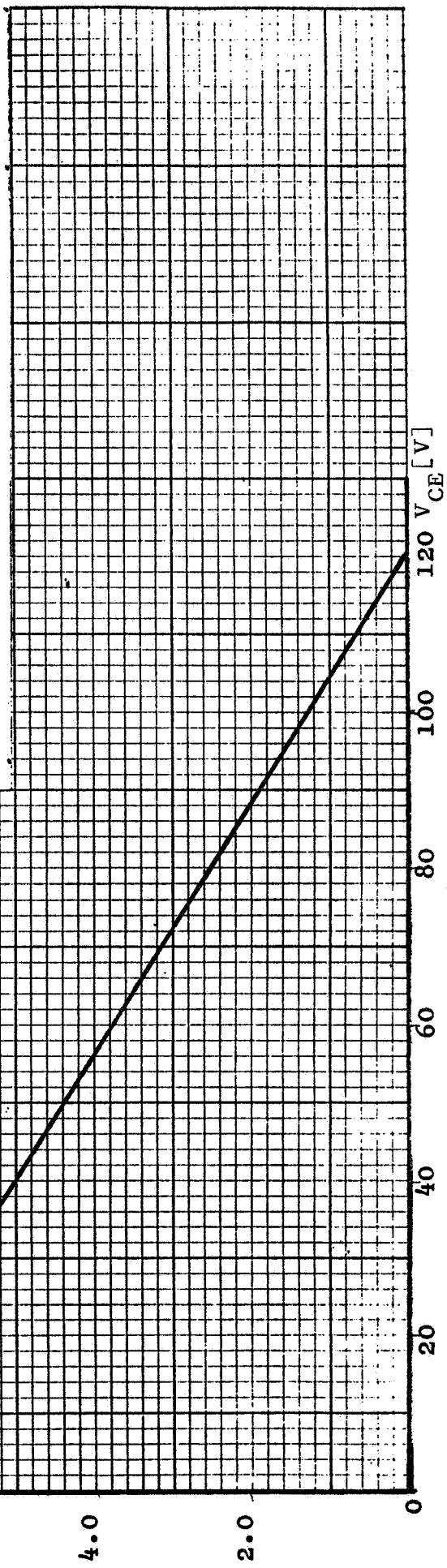
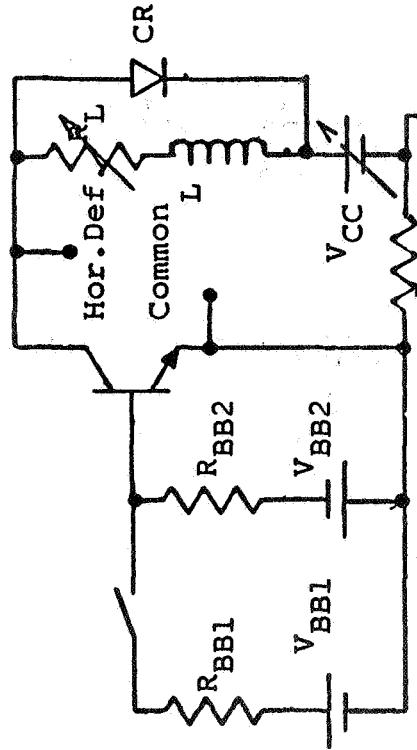


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

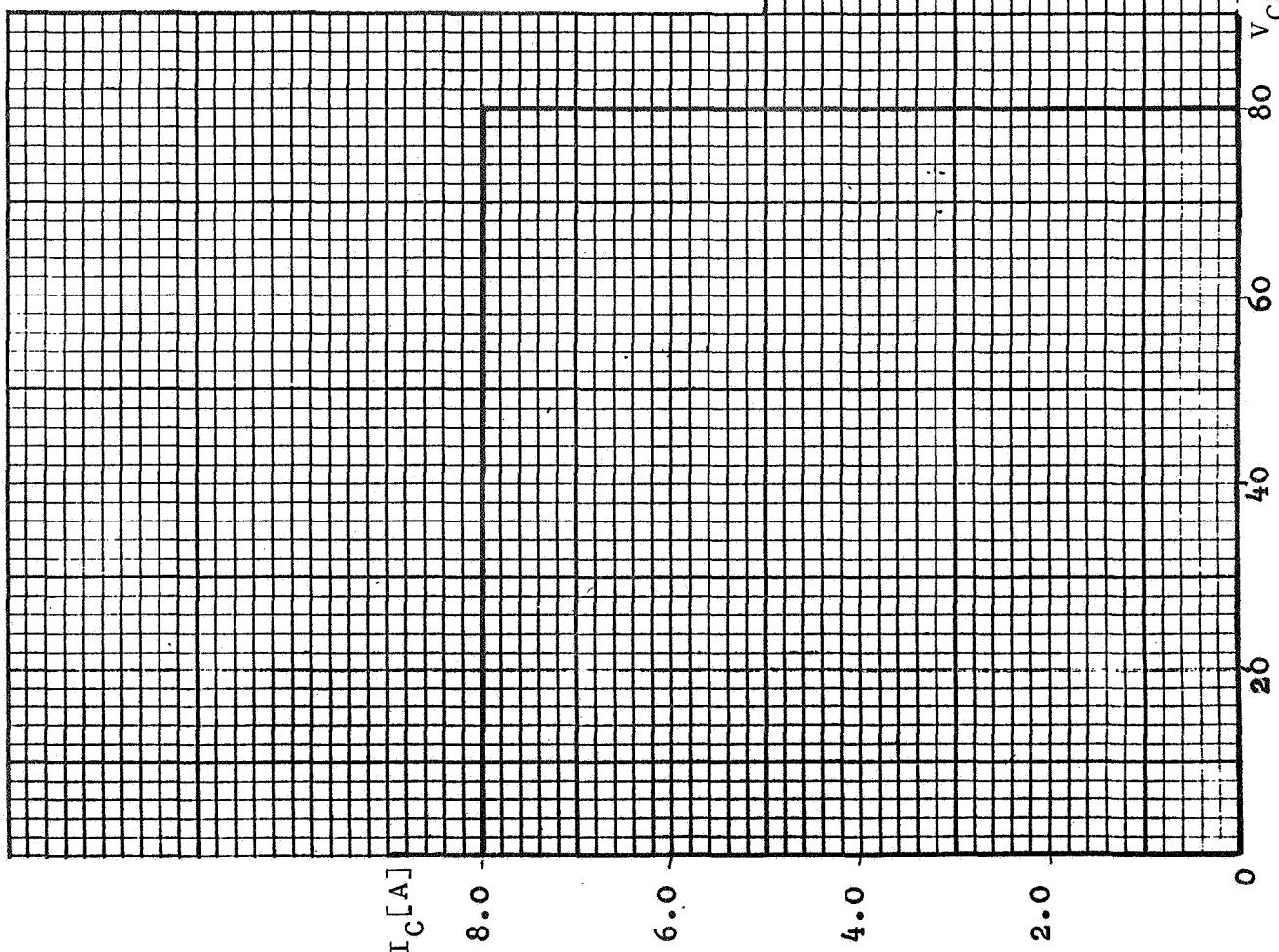
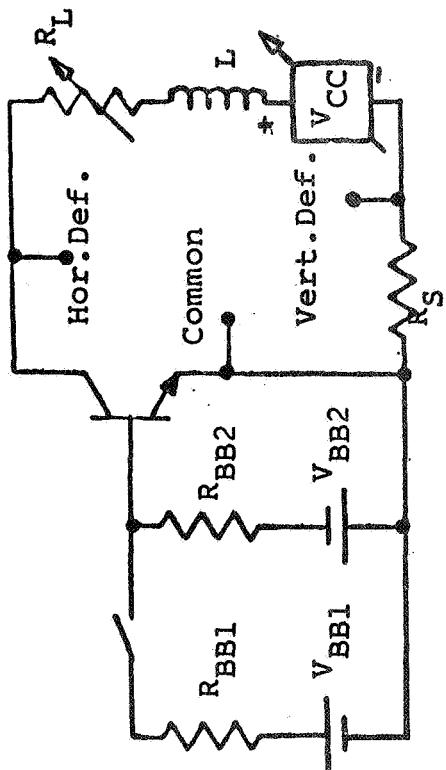


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

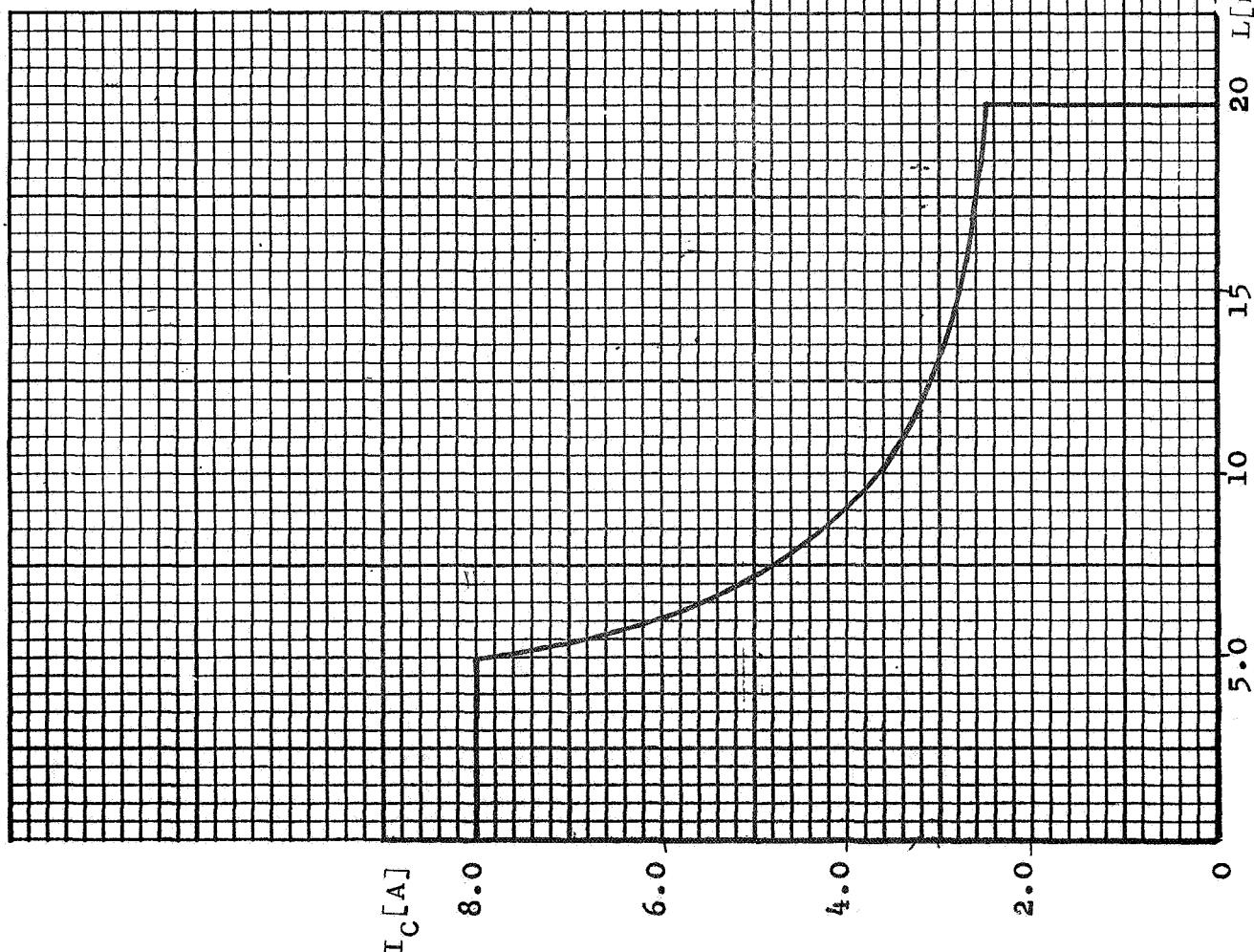


Figure 5

SHORTED CLASS B SOAR

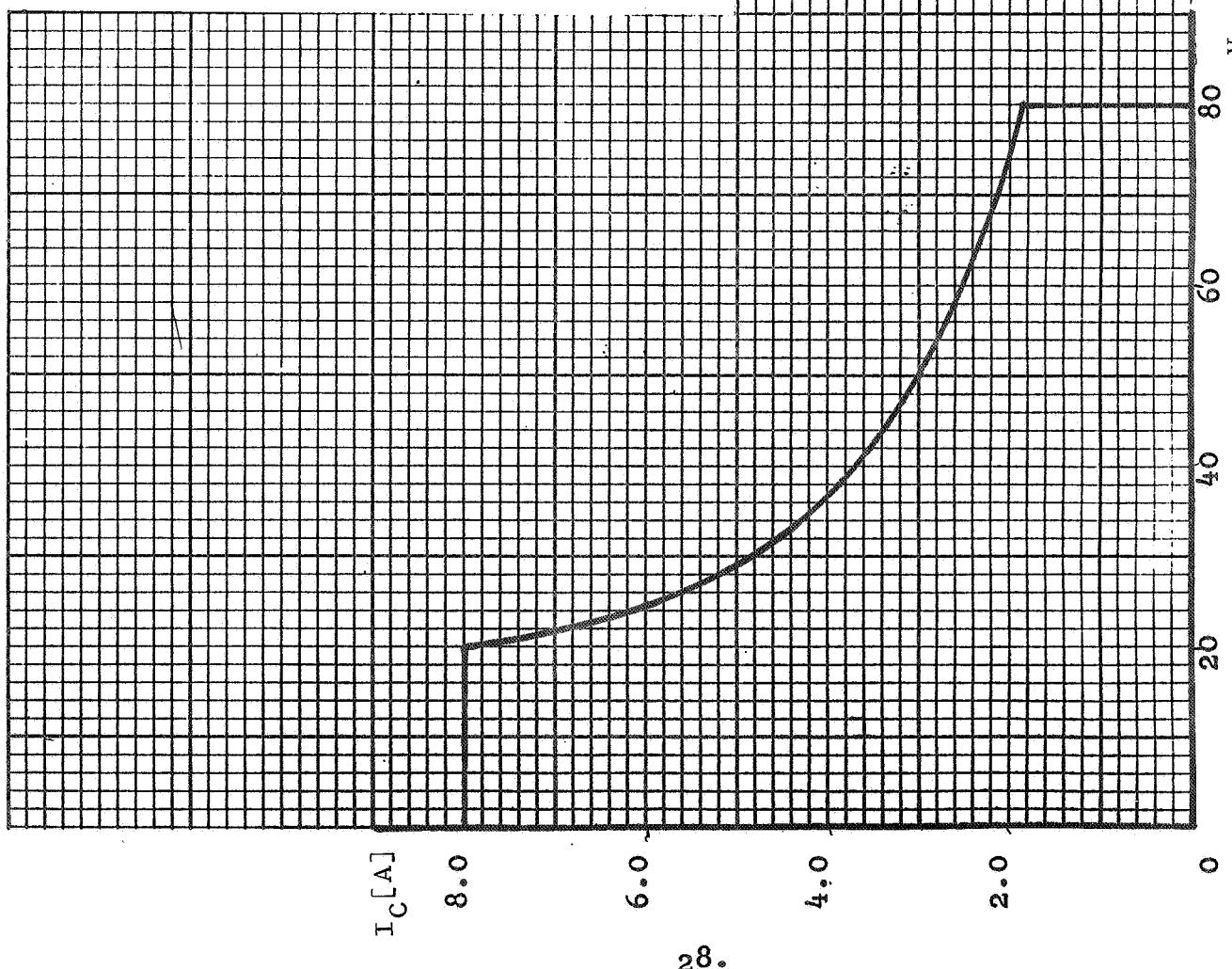
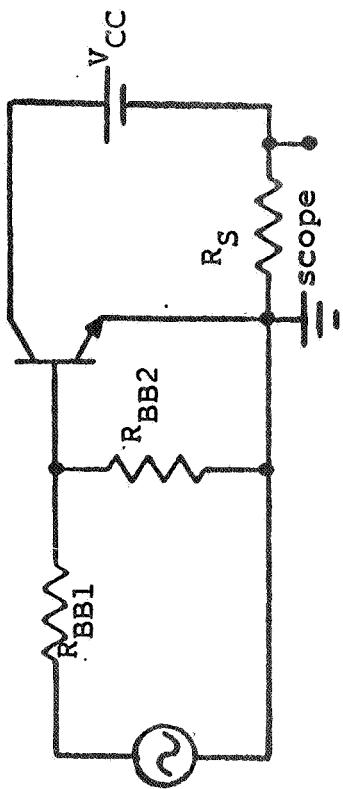


Figure 6

SILICON POWER TRANSISTOR

< Type 2N1016D >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer C --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
1.0.0	<u>General Description</u>	
1.1.0	Type -- NPN	
1.2.0	Material -- Silicon	
2.0.0	<u>Mechanical Data</u>	
2.1.0	Outline -- TO-82	
2.2.0	Terminal Designation  1 -- Base  2 -- Emitter  3 -- Collector  Case -- Collector	
2.2.1	Maximum Stud Torque -- 50 in lbs.  Minimum Stud Torque -- 40 in lbs.	
3.0.0	<u>Maximum Ratings</u>	
3.1.0	Temperature	
3.1.1	$T_{STG(max)} = +150^{\circ}\text{C}$	<u>JS-6-T1.1</u> (JEDEC Suggested Standard: "Test Procedures for Verifications of Maximum Ratings")
	$T_{STG(min)} = -65^{\circ}\text{C}$	<u>JS-6-T1.2</u>
3.1.2	$T_J = 150^{\circ}\text{C}$	<u>JS-6-T2</u>  $T_C = 100^{\circ}\text{C}$ , $V_{CB} = 100\text{V}$ , $I_C = 0.71\text{A}$
3.1.3	$T(\text{Lead}) = 230^{\circ}\text{C}$	Distance from case = 1/4 in., Time = 10s
3.2.0	Voltage	
3.2.1	$V_{CBO} = 200\text{V}$	<u>JS-6-T3</u> or MIL-STD-750A Method 3001.1
3.2.2	$V_{EBO} = 25\text{V}$	<u>JS-6-T4</u> or MIL-STD-750A Method 3026.1
3.2.3	$V_{CEX} = 200\text{V}$	<u>JS-6-T5-2.1</u>  $I_C$ ( $V_{CE} = V_{CEX}$ ) = 7.5A, $V_{CC} = 200\text{V}$ $R_L = 26.6\Omega$ , $L = 1\text{mH}^*$ , CR - 1N1204.
	*Miller No. 7871 in series with Miller No. 7825-3	

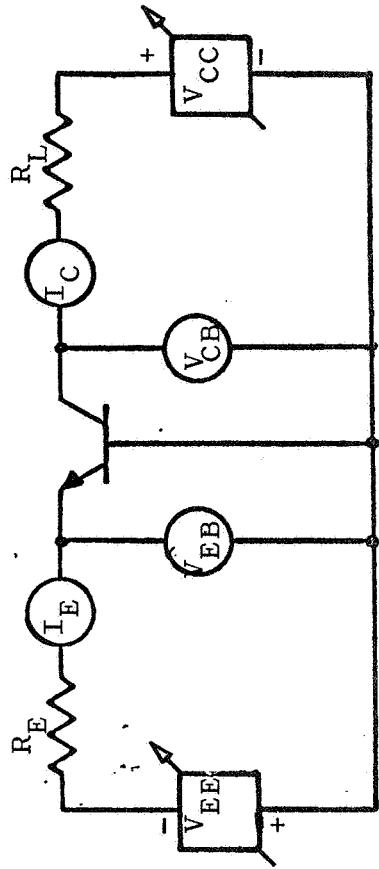
<u>Item</u>		<u>Test Methods and Test Conditions</u>
3.2.3	continued .....	$V_{BB1} = 12.5V$ , $R_{BB1} = 3\Omega$ , $V_{BB2} = 3V$ , $R_{BB2} = 3\Omega$ Duty Cycle = 1%, $t_p = 1 \text{ ms}$ , $R_s = 0.1\Omega$
3.3.0	Current	
3.3.1	$I_C = 7.5A$	<u>JS-6-T6</u> $I_B = 1.5A$ , $T_C = 25^\circ C$
3.3.2	$I_B = 5A$	<u>JS-6-T8</u> $T_C = 25^\circ C$
3.3.3	$I_E = 9.0A$	<u>JS-6-T10</u> $I_B = 1.5A$ , $T_C = 25^\circ C$
3.4.0	Power	
3.4.1	$P_T = 71.4W$	<u>JS-6-T12</u> $T_C = 100^\circ C$ , $V_{CB} = 200V$ , $I_C = 0.355A$ Derating factor = 1.43 W/ $^\circ C$
3.4.2	$P_{TM} = I_C V_{CC} = 1125W$	<u>JS-6-T13</u> $T_C = 100^\circ C$ , $V_{CC} = 150V$ , $V_{BB} = 3V$ $R_{BB} = 3\Omega$ , $I_C = 7.5A$ , Pulse Width 1ms Duty Cycle = 1%, $t_r \leq 50\mu s$ , $t_f \leq 50\mu s$ of Collector Current
3.5.0	Maximum Operating Conditions	
3.5.1	Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> (See Figure 1) Test Point: (See 3.4.1)
3.5.2	Pulsed Forward Biased SOAR	<u>JS-6-T14</u> (See Figure 2) <u>Test Points:</u> $T_C = 100^\circ C$ , $V_{BB} = 3V$ , $R_{BB} = 3\Omega$ , Coll. Cu $t_r \leq 50\mu s$ , $t_f \leq 50\mu s$ , $I_C = 7.5A$ Duty Cycle $\leq 1\%$ , $R_S = 0.1\Omega$

<u>Item</u>		<u>Test Methods and Test Conditions</u>
3.5.2	Continued .....	<ol style="list-style-type: none"> <li>1. For <math>t_p = 20\text{ms}</math>: <math>V_{CC} = 90\text{V}</math></li> <li>2. For <math>t_p = 10\text{ms}</math>: <math>V_{CC} = 110\text{V}</math></li> <li>3. For <math>t_p = 5\text{ms}</math>: <math>V_{CC} = 125\text{V}</math></li> <li>4. For <math>t_p = 1\text{ms}</math>: <math>V_{CC} = 150\text{V}</math></li> </ol>
3.6.0	SOAR Switching between Saturation and Cutoff	
3.6.1	Resistive Load	<u>JS-6-T5.1</u> with $L = 0$ and CR disconnected (See Figure 3) <p><u>Test Points:</u></p> <p><math>R_{BB1} = 3\Omega</math>, <math>R_{BB2} = 3\Omega</math>, <math>V_{BB1} = 12.5\text{V}</math>  <math>V_{BB2} = 3\text{V}</math>, <math>T_C = 100^\circ\text{C}</math>, <math>t_f \leq 50\text{us Coll.}</math>        Current, <math>t_r \leq 50\text{us Coll. Current}</math>,  <math>R_S = 0.1\Omega</math>, <math>I_C = 7.5\text{A}</math>, <math>V_{CC} = 200\text{V}</math></p>
3.6.2	Clamped Inductive Load	<u>JS-6-T5.1</u> (See Figure 4) <p><u>Test Points:</u> (See 3.2.3)</p>
3.6.3	Unclamped Inductive Load	<u>JS-6-T5-2.1</u> and CR disconnected (See Figure 5) <p><u>Test Points:</u></p> <ol style="list-style-type: none"> <li>1. <math>V_{BB_1} = 12.5\text{V}</math>      <math>L = 1.4\text{mH}^*</math>  <math>R_{BB_1} = 3\Omega</math>      <math>R_L = 3\Omega</math>  <math>V_{BB_2} = 3\text{V}</math>      <math>V_{CC} = 25\text{V}</math>  <math>R_{BB_2} = 3\Omega</math>      <math>f = 60\text{Hz}</math>  <math>R_S = 0.1\Omega</math>      <math>d = 10\%</math></li> <li>2. <math>V_{BB_1} = 3.0\text{V}</math>      <math>L = 10\text{mH}^{**}</math>  <math>R_{BB_1} = 10\Omega</math>      <math>R_L = 7.5\Omega</math>  <math>V_{BB_2} = 1.5\text{V}</math>      <math>V_{CC} = 25.0\text{V}</math>  <math>R_{BB_2} = 30\Omega</math>      <math>f = 60\text{Hz}</math>  <math>R_S = 0.1\Omega</math>      <math>d = 30\%</math></li> </ol> <p>*Miller #7871 in series with Miller #7825-3   **Series Stancor C-2688</p>

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
3.7.0      Shorted Class B SOAR	(See Figure 6)	
	<u>Test Points:</u>	
	$I_C \text{ peak} = 1.1A, V_{CC} = 200V, R_S = 0.1\Omega$ $R_{BB_1} = 5\Omega, R_{BB_2} = 10\Omega, f = 20Hz,$ $T_C = 100^\circ C$	
4.0.0 <u>Electrical Characteristics</u>	$T_C = 25^\circ C$ (unless otherwise noted)	
	Maximum limits unless otherwise noted	
	<u>Technique:</u>	
	DC - Continuous Operation	
	C.T. - Curve Tracer	
	P - $300\mu s$ Pulse, 2% Duty Cycle	
4.1.0      Static		
4.1.1 $I_{CEX} = 20mA$	$V_{CEX} = 200V, V_{BE} = -1.5V,$ Technique - C.T., $T_C = 150^\circ C$	
	$I_{CES} = 100\mu A$ $V_{CE} = 240V$ Technique - C.T.	
4.1.2 $I_{CEO} = 10mA$	$V_{CEO} = 200V$ , Technique - C.T.	
4.1.3 $I_{EBO} = 20mA$	$V_{EBO} = 25V$ , Technique - C.T. $T_C = 150^\circ C$	
4.1.4 $V_{CEO} = 200V \text{ min}$	<u>JS-6-T5-2.1</u> and CR disconnected $I_C = 1A, R_{BB_1} = 3\Omega, V_{BB_1} = 3V,$ $R_{BB_2} = \infty\Omega, d = 50\%, f = 60Hz$ $L = 10mH, R_L = 0.1\Omega, R_S = 0.1\Omega$ Adjust $V_{CC}$ for specified $I_C$ .	

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
4.1.5	$h_{FE} = 10 \text{ min}$	$V_{CE} = 4V, I_C = 5A, \text{ Technique - C.T.}$
	$h_{FE} = 7.5 \text{ min}$	$V_{CE} = 4V, I_C = 7.5A \text{ Technique - C.T.}$
4.1.6	$V_{CE(sat)} = 2.5V$	$I_C = 5A, I_B = .75A, \text{ Technique - C.T.}$
4.2.0	Dynamic	
4.2.1	$f_{hfe} = 10\text{KHz min, } 40\text{KHz max}$	$I_C = 1A, V_{CE} = 5V$
5.0.0	Thermal Characteristics	
5.1.0	$T_J \text{ min} = 70ms$	$I_C = 2A, V_{CE} = 10V, T_C = 25^\circ C$ MIL-STD-750 Method 3146.1
5.2.0	$\theta_{JC} = 0.7^\circ C/W$	$I_C = 2A, V_{CE} = 10V, T_C = 25^\circ C$ MIL-STD-750 Method 3136

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CEO}$

Test Circuit: JS-6-T12

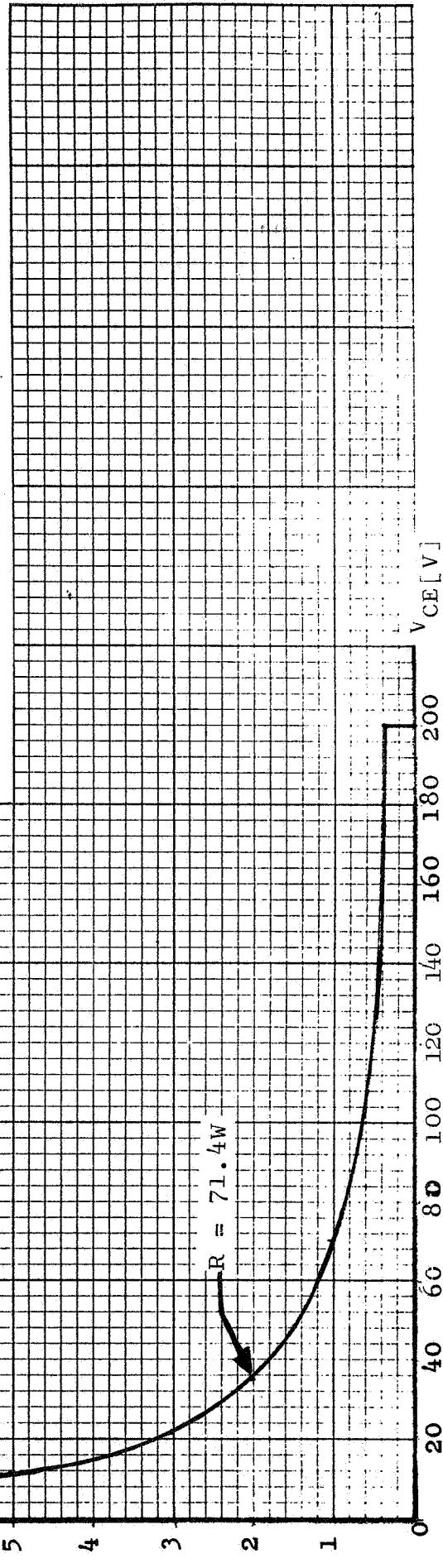
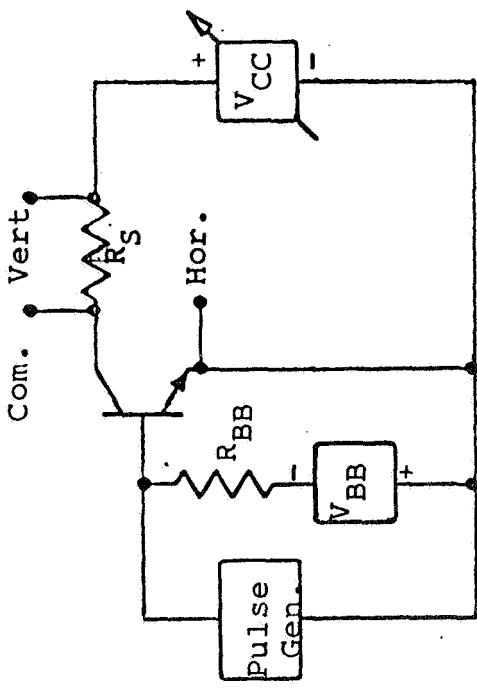
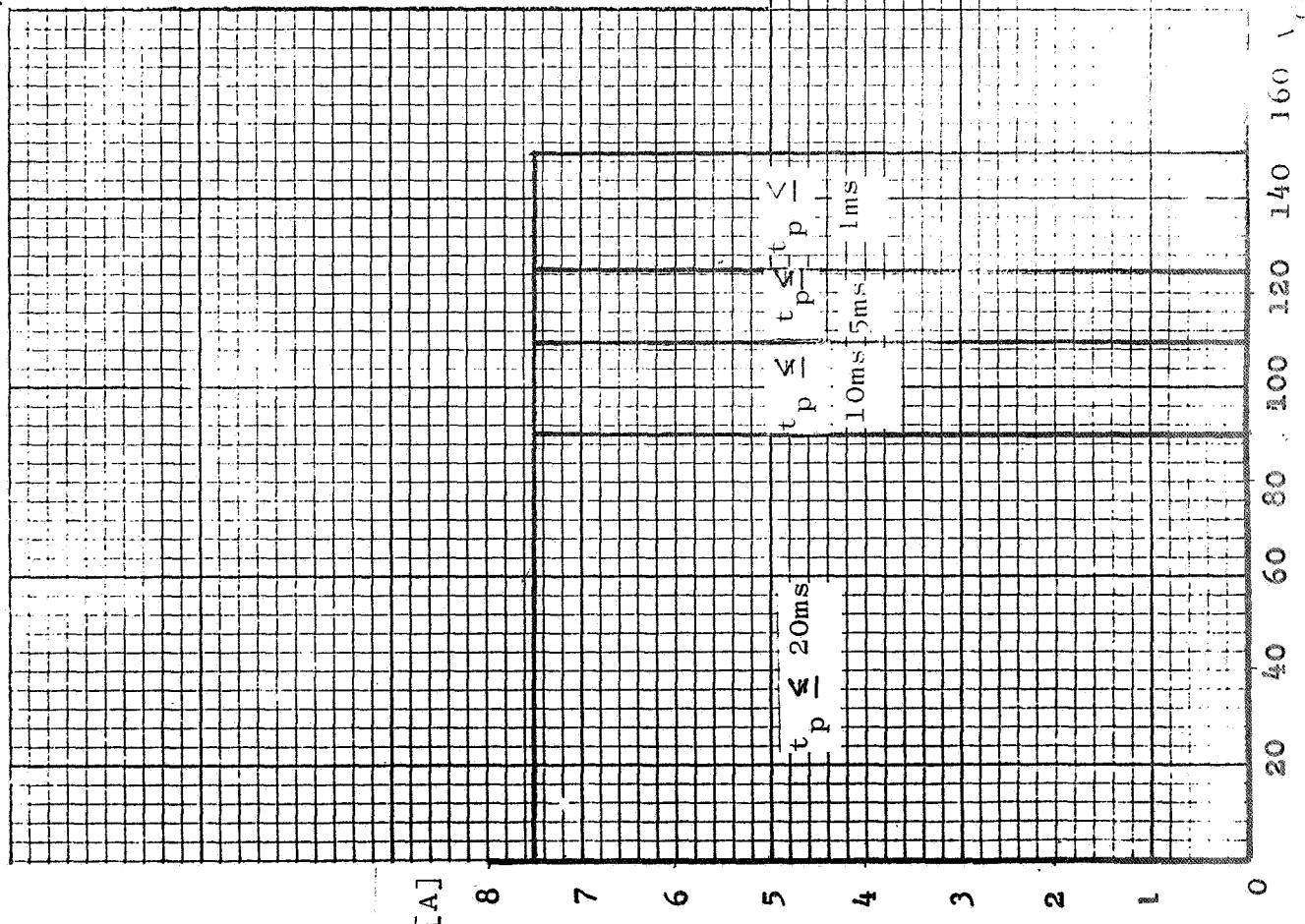


Figure 1

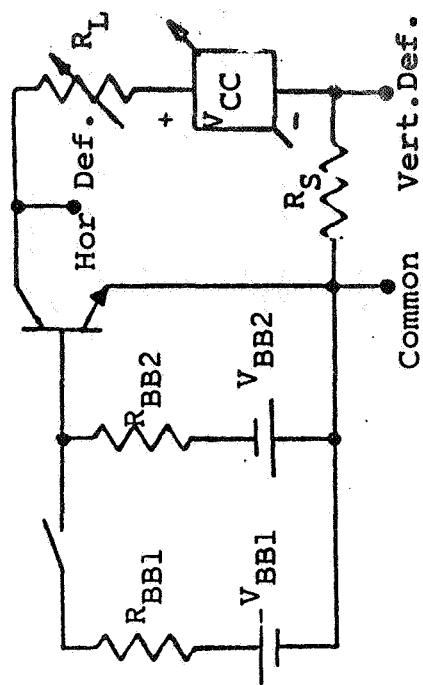
PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14



SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

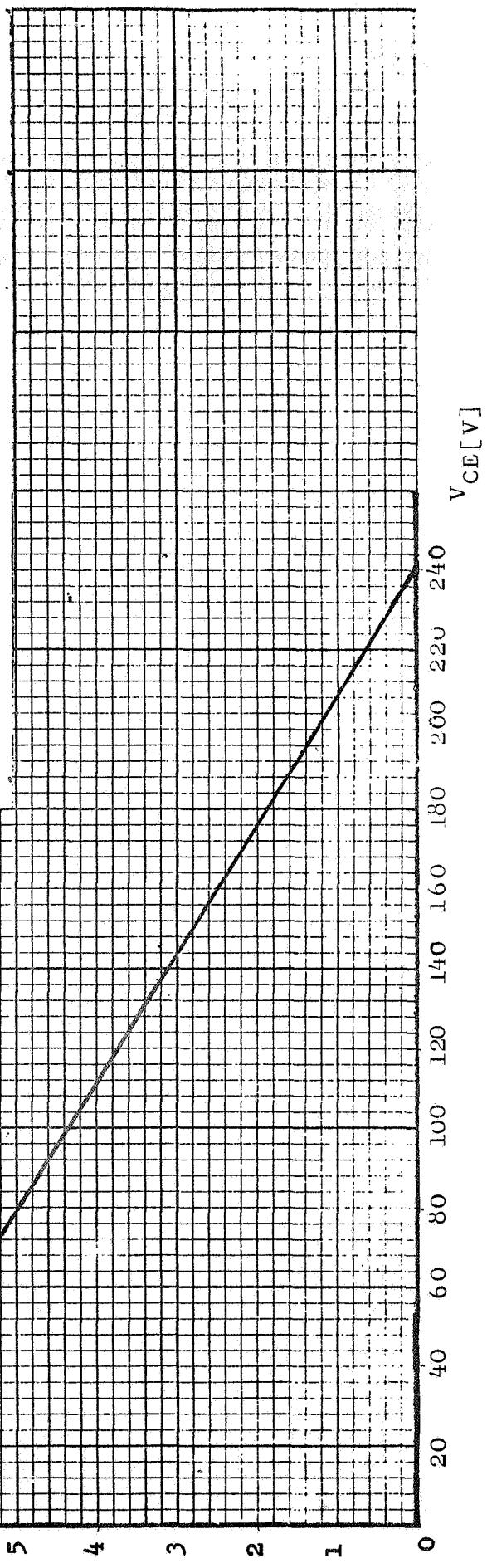
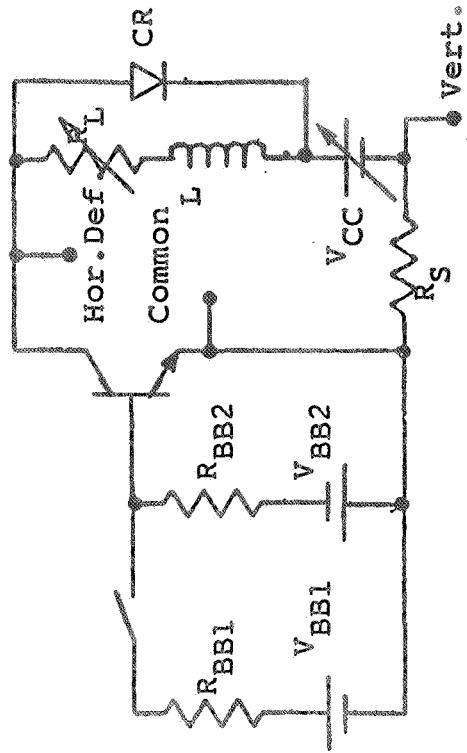


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

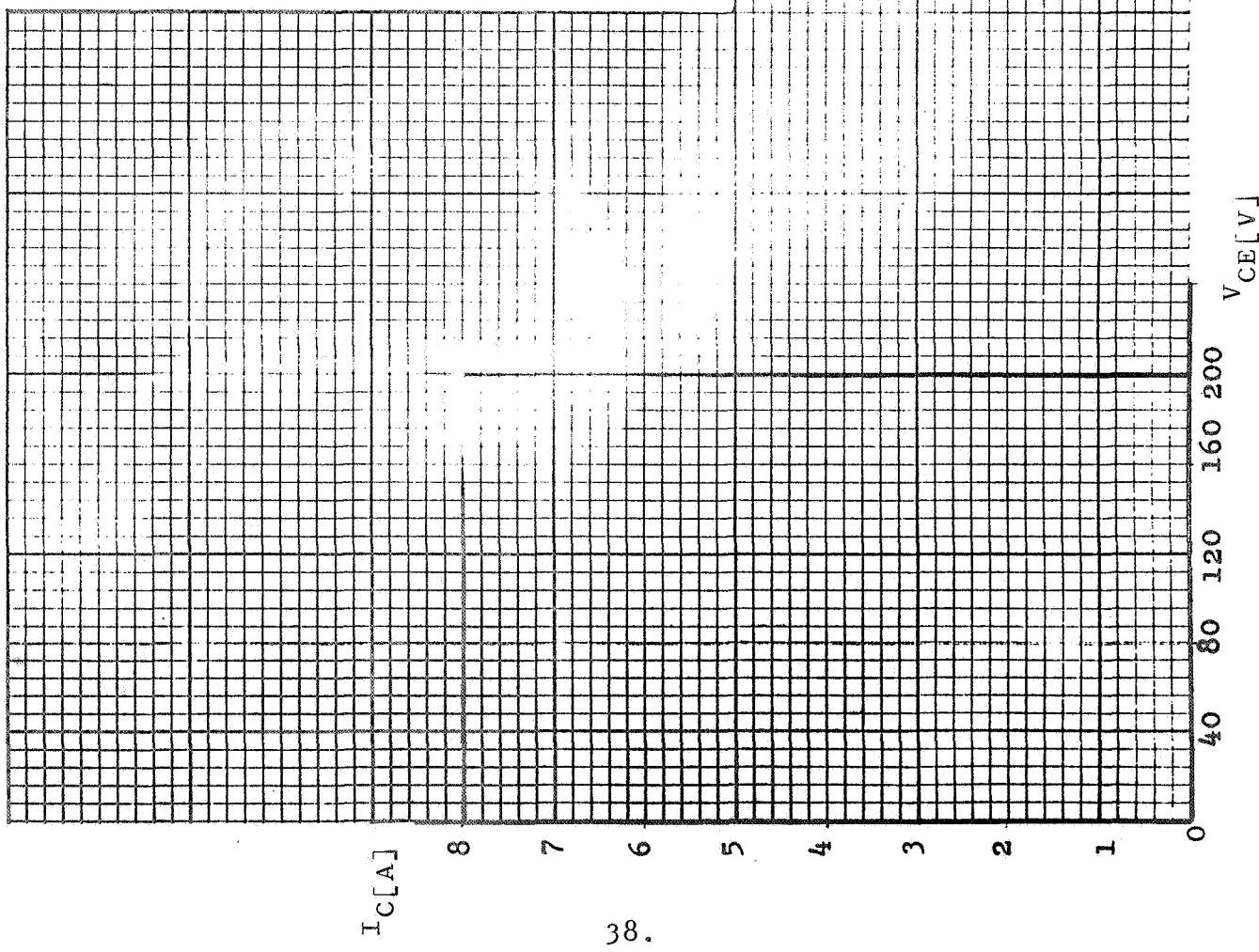
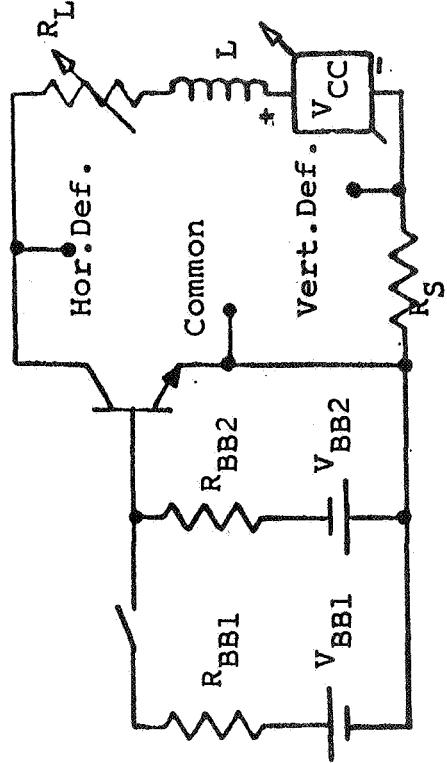


Figure 1

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

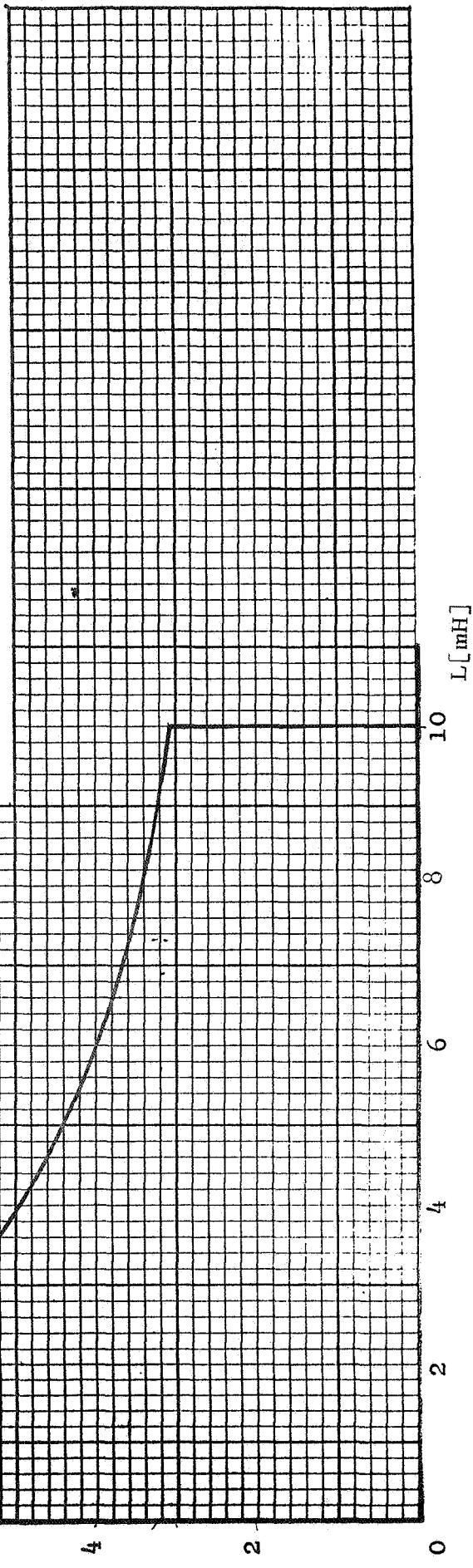


Figure 5

SHORTED CLASS B SOAR

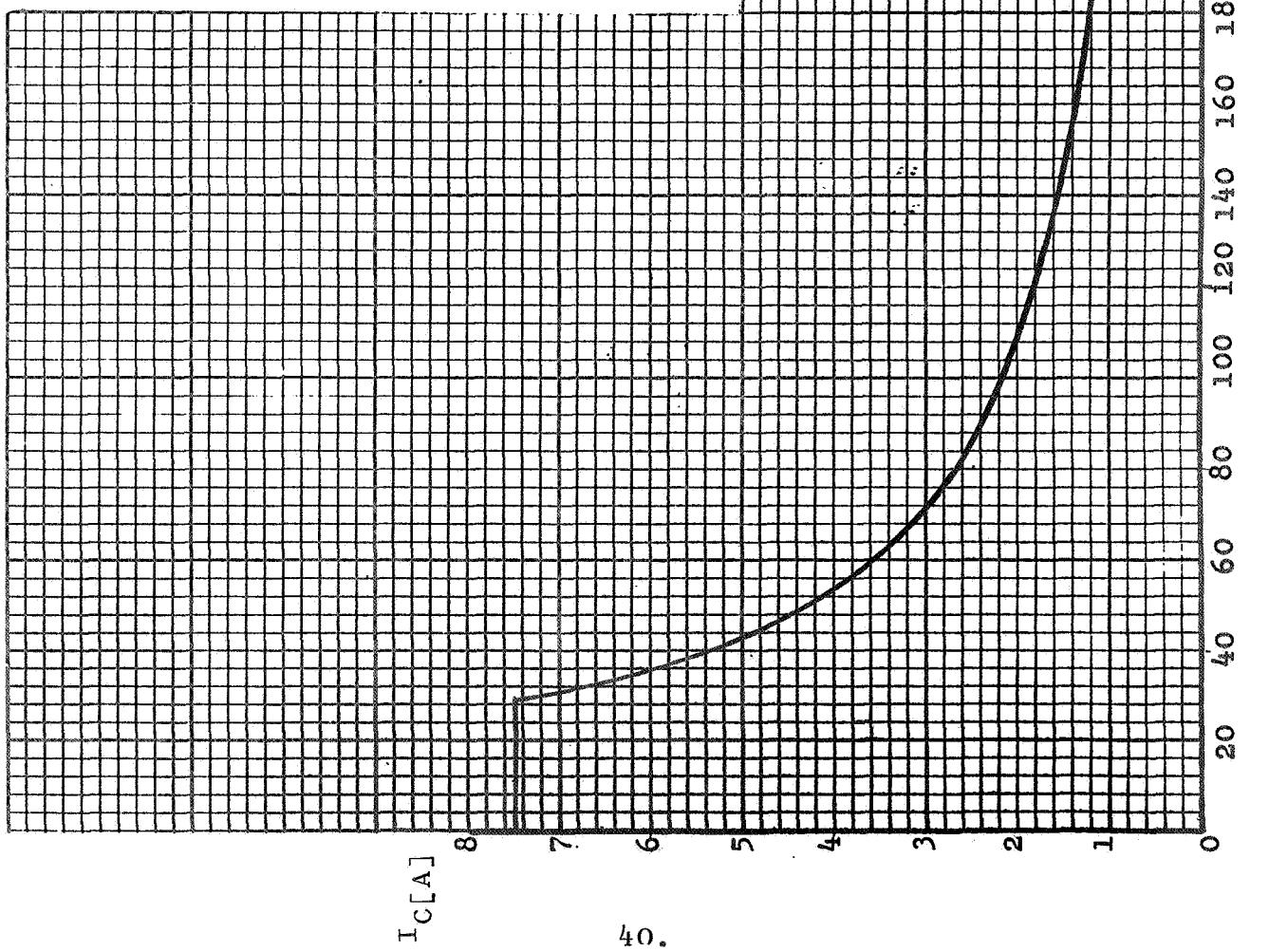
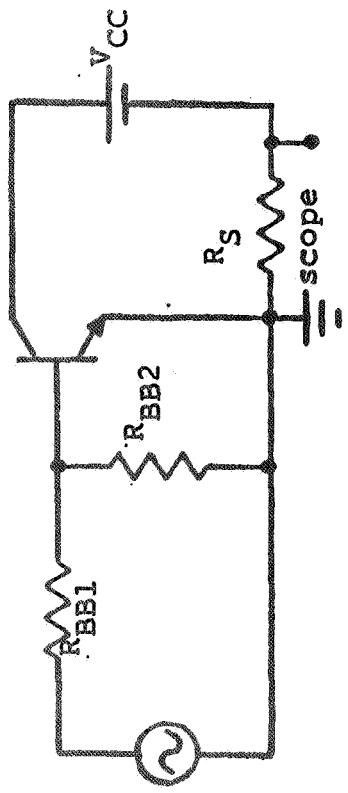


Figure 6

**Silicon Power Transistor**  
**< Type 2N1514 >**

**SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN**

**-- Manufacturer H --**

**Performed for**  
**NATIONAL AERONAUTICS AND SPACE ADMINISTRATION**  
**GEORGE C. MARSHALL SPACE FLIGHT CENTER**  
**HUNTSVILLE, ALABAMA**

**Contract No. NAS8-21155**

**THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY**

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
1.0.0	<u>General Description</u>	
1.1.0	Type NPN	
1.2.0	Material -- Silicon	
2.0.0	<u>Mechanical Data</u>	
2.1.0	Outline -- TO-36	
2.2.0	Terminal Designation	
	1 -- Base	
	2 -- Emitter	
	3 -- Collector	
	case -- Collector	
3.0.0	<u>Maximum Ratings</u>	
3.1.0	Temperature	
3.1.1	$T_{STG(max)} = +200^{\circ}\text{C}$	<u>JS-6-T1.1</u> (JEDEC suggested Standard: "Test Procedures for Verification of Maximum Ratings.")
	$T_{STG(min)} = -65^{\circ}\text{C}$	<u>JS-6-T1.2</u>
3.1.2	$T_J(max) = 200^{\circ}\text{C}$	<u>JS-6-T2</u> $T_C = 100^{\circ}\text{C}$ $V_{CB} = 10\text{V}, I_C = 4.3\text{A}$
3.1.3	$T(\text{Lead}) = 230^{\circ}\text{C}$	Distance from case - 0.25 in Time - 10s
3.2.0	Voltage	$T_C = 25^{\circ}\text{C}$
3.2.1	$V_{CBO} = 100\text{V}$	<u>JS-6-T3</u> or MIL-STD-750A Method 3001.1

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.2.2 $V_{EBO} = 10V$	<u>JS-6-T4</u> or <u>MIL-STD-750A</u> <u>Method 3026.1</u>
3.2.3 $V_{CEX} = 70V$	<u>JS-6-T5.1</u>  $I_C (V_{CE} = V_{CEX}) = 6A$ $V_{CC} = 100V, R_L = 16.0\Omega$ $L = 1mH^*, CR = 1N1204$ $V_{BB1} = 7.5V, R_{BB1} = 1\Omega$ $V_{BB2} 8V, R_{BB2} = 5\Omega$ $R_S = 0.1\Omega$ $t_p = 1ms, \text{ Duty Cycle} \leq 1\%$
	*Miller No. 7871 in series with Miller No. 7825-3
3.3.0      Current	
3.3.1 $I_C = 6A$	<u>JS-6-T6</u>  $I_B = 2A, T_C = 25^\circ C$
3.3.2 $I_B = 3A$	<u>JS-6-T8</u>  $T_C = 25^\circ C$
3.3.3 $I_E = 8A$	<u>JS-6-T10</u>  $I_B = 2A, T_C = 25^\circ C$
3.4.0      Power	
3.4.1 $P_T = 43W$	<u>JS-6-T12</u>  $T_C = 100^\circ C$ $V_{CB} = 10V, I_C = 4.3A$ Derating factor - $0.43W/\text{ }^\circ C$

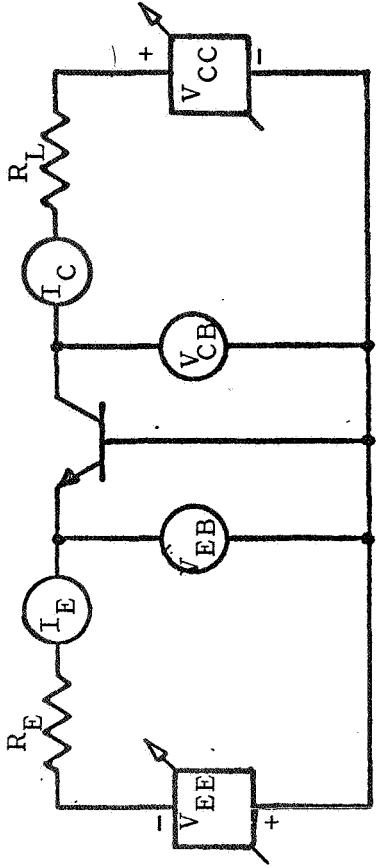
<u>Item</u>		<u>Test Methods and Test Conditions</u>
3.4.2	$P_{TM} = I_C V_{CC} = 330W$	<u>JS-6-T13</u> $T_C = 100^\circ C$ $V_{CC} = 55V, I_C = 6A$ $V_{BB} = 8V, R_{BB} = 5\Omega$ <u>Input Pulse Characteristics</u> Pulse Width = 10 ms Duty Cycle $\leq 1\%$ $t_r \leq 50\mu s, t_f \leq 50\mu s$ Coll. Current
3.5.0	Maximum Operating Conditions	,
3.5.1	Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> (See Figure 1) Test Point: (See 3.4.1)
3.5.2	Pulsed Forward Biased SOAR	<u>JS-6-T14</u> (See Figure 2) <u>Test Points:</u> $T_C = 100^\circ C, V_{BB} = 8V; R_{BB} = 5\Omega$ $t_r \leq 50\mu s, t_f \leq 50\mu s, I_C = 6A$ Duty Cycle $\leq 1\%, R_S = 0.1\Omega$ 1. For $t_p = 20ms; V_{CC} = 30V$ 2. For $t_p = 10ms; V_{CC} = 55V$
3.6.0	SOAR	
	Switching between Saturation and Cutoff	
3.6.1	Resistive Load	<u>JS-6-T5-2.1</u> with $L = 0$ and CR disconnected (See Figure 3)

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.6.1 Resistive Load (Cont'd)	<p><u>Test Point:</u></p> $I_C = 6A, V_{CC} = 100V, R_{BB1} = 1\Omega,$ $R_{BB2} = 5\Omega, R_S = 0.1\Omega, V_{BB1} = 7.5V,$ $V_{BB2} = 8V, T_C = 100^\circ C, \text{ (Coll. Current)}$ $t_r \leq 50\mu s, t_f \leq 50\mu s$
3.6.2 Clamped Inductive Load	<u>JS-6-T5-2.1</u> (See Figure 4) <u>Test Point:</u> (See 3.2.3)
3.6.3 Uclamped Inductive Load	<u>JS-6-T5-2.1</u> and CR disconnected (See Figure 5)
3.7.0 Shorted Class B SOAR	<p><u>Test Points:</u></p> $R_{BB1} = 1\Omega, R_{BB2} = 5\Omega, R_S = 0.1\Omega,$ $V_{BB1} = 7.5V, V_{BB2} = 8V, T_C = 25^\circ C,$ $f = 60Hz, d = 10\%$ <ol style="list-style-type: none"> <li>1. <math>I_C = 6A, V_{CC} = 18V, R_L = 2\Omega, L=10mH^*</math></li> <li>2. <math>I_C = 2.5A, V_{CC} = 28V, R_L = 10\Omega, L=40mH</math></li> </ol> <p>*Stancor - C-2688 **Series Stancor-C-2688</p> <p>(See Figure 6)</p> <p><u>Test Point:</u></p> $I_C \text{ peak} = 2.6A, V_{CC} = 55V, R_S = 0.1\Omega,$ $R_{BB1} = 1\Omega, R_{BB2} = 3\Omega, f = 20Hz,$ $T_C = 100^\circ C$

<u>Item</u>		<u>Test Methods and Test Conditions</u>
4.0.0	Electrical Characteristics	$T_C = 25^\circ C$ [unless otherwise noted]
	Maximum limits unless otherwise noted	
	Technique:	
	DC - Continuous Operation	
	C.T. - Curve Tracer	
	P - $300\mu s$ Pulse, 2% Duty Cycle	
4.1.0	Static	
4.1.1	$I_{CEO} = 100mA$	$V_{CE} = 55V$
		Technique - C.T.
4.1.2	$I_{CBO} = 2mA$	$V_{CB} = 30V, T_C = 200^\circ C$
		Technique - C.T.
4.1.3	$V_{EBF} = 1.5V$	$V_{CB} = 30V, T_C = 200^\circ C$
		Technique - C.T.
4.1.4	$I_{EBO} = 25\mu A$	$V_{EB} = 10V, \text{Technique - C.T.}$
4.1.5	$V_{(BR)CEO} = 55 \text{ minV}$	$I_C = 100mA$
		Technique - C.T.
4.1.6	$h_{FE} = 25 \text{ min}$ " = 75 max	$V_{CE} = 4V, I_C = 1.5A$
		Technique - C.T.
4.1.7	$h_{FE} = 7 \text{ min}$	$V_{CE} = 8V, I_C = 6A$
		Technique - P
4.1.8	$V_{CE(sat)} = 6 \text{ max V}$	$I_C = 6A, I_B = 2A$
		Technique - C.T.
4.1.9	$V_{BE} = 7.8 \text{ max V}$	$I_C = 6A, V_{CE} = 8V$
		Technique - P

<u>Item</u>	<u>Test Methods and Test Conditions</u>
5.0.0	Thermal Characteristics
5.1.0	$T_J \text{ min} = 5\text{ms}$ $I_C = 2\text{A}, V_{CE} = 10\text{V}, T_C = 25^\circ\text{C}$ MIL-STD-750 Method 3146.1
5.2.0	$\theta_{JC} \text{ max} = 2.33^\circ\text{C/W}$ $I_C = 2\text{A}, V_{CE} = 10\text{V}, T_C = 25^\circ\text{C}$ MIL-STD-750 Method 3136
6.0.0	$f_{hfe} = 10\text{KHz(min)}$ $I_C = 100\text{mA}, V_{CE} = 6\text{C}$ $40\text{KHz(max)}$ MIL-STD-750 Method

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ C$ ,  $I_C \geq I_{CEO}$

Test Circuit: JS-6-T12

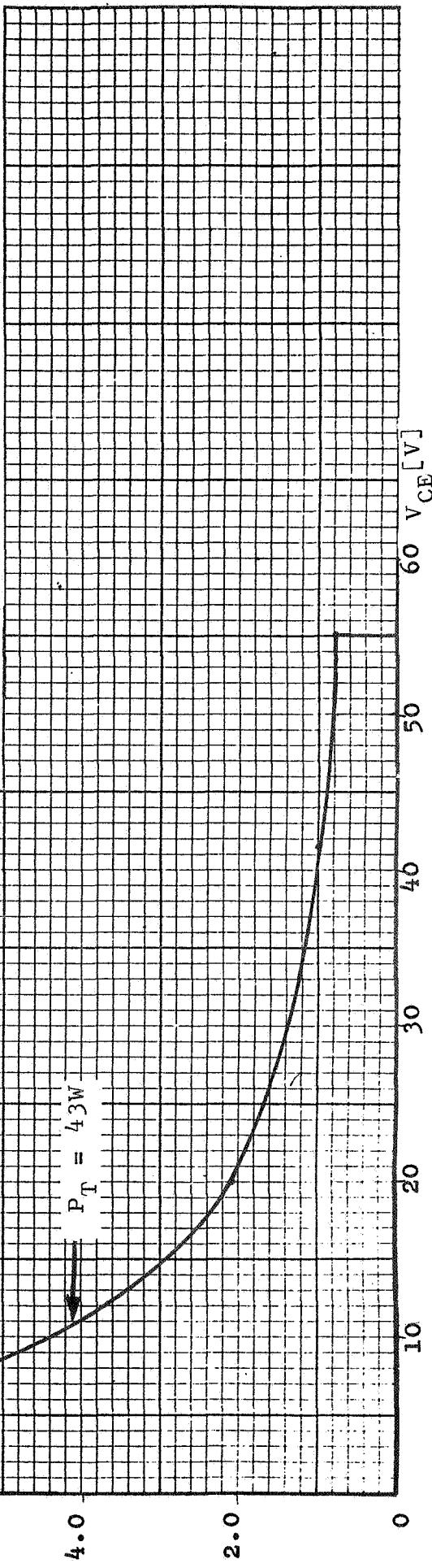
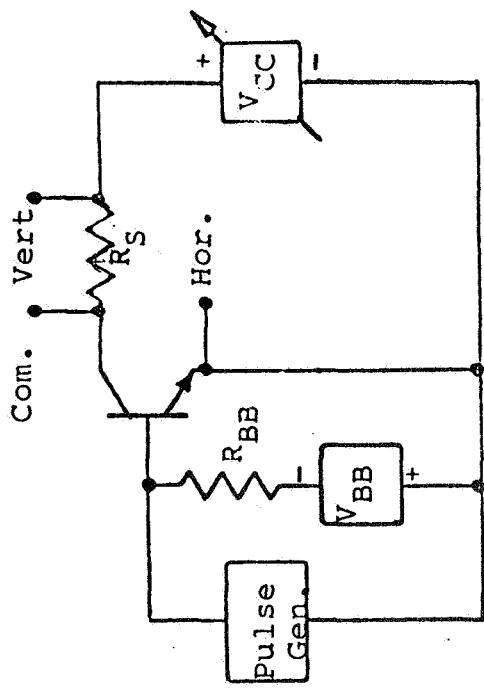
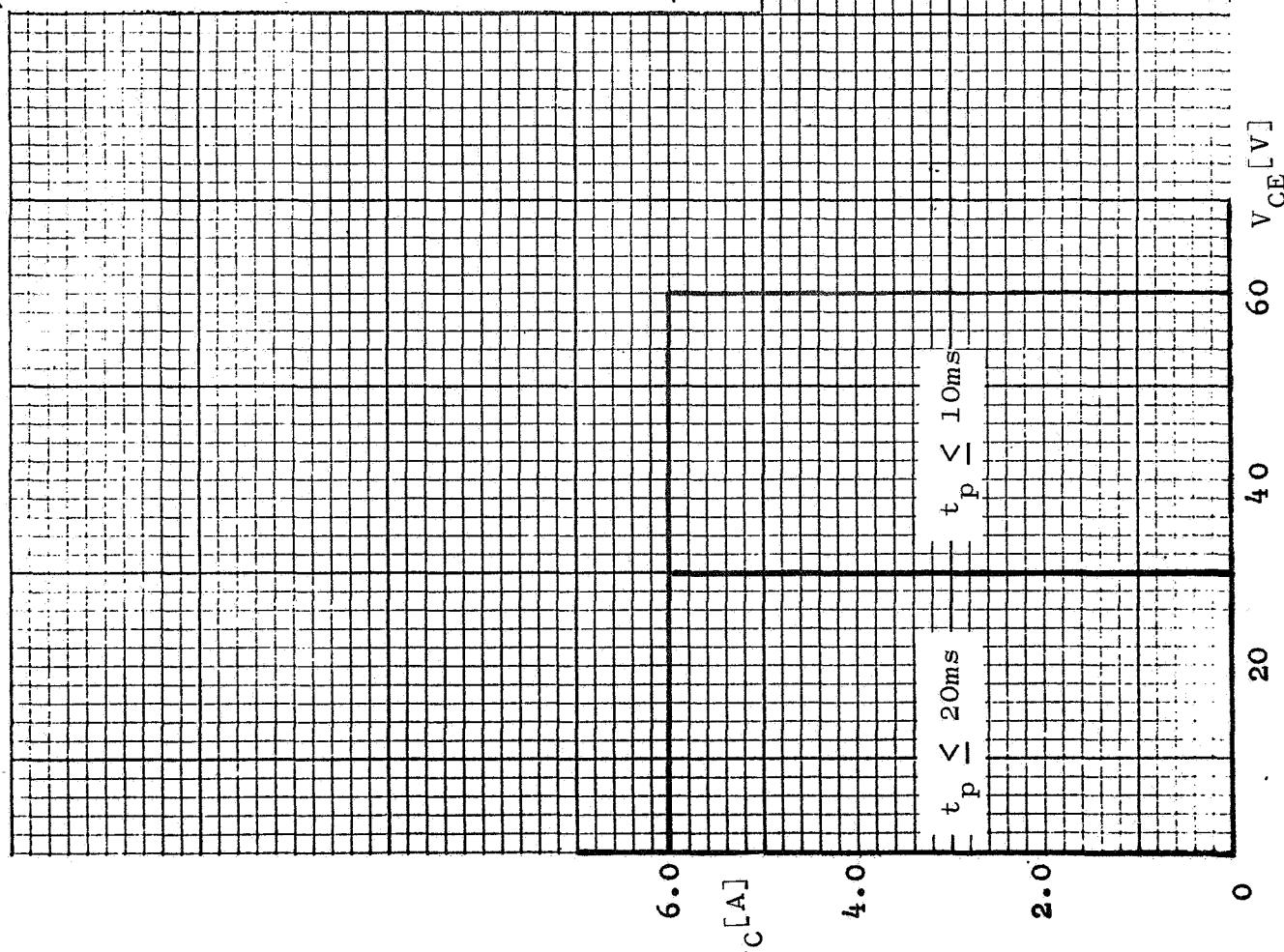


Figure 1

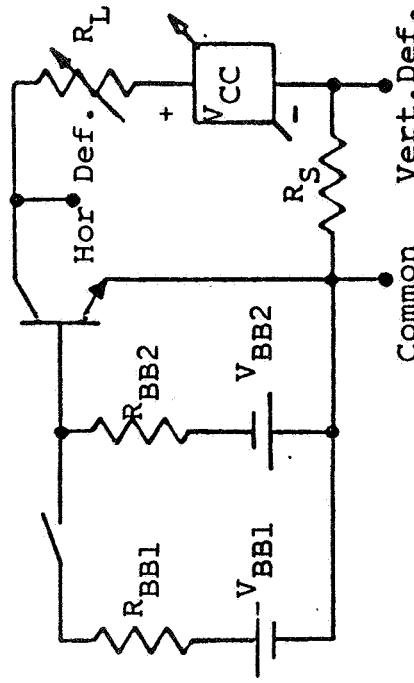
PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14



SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

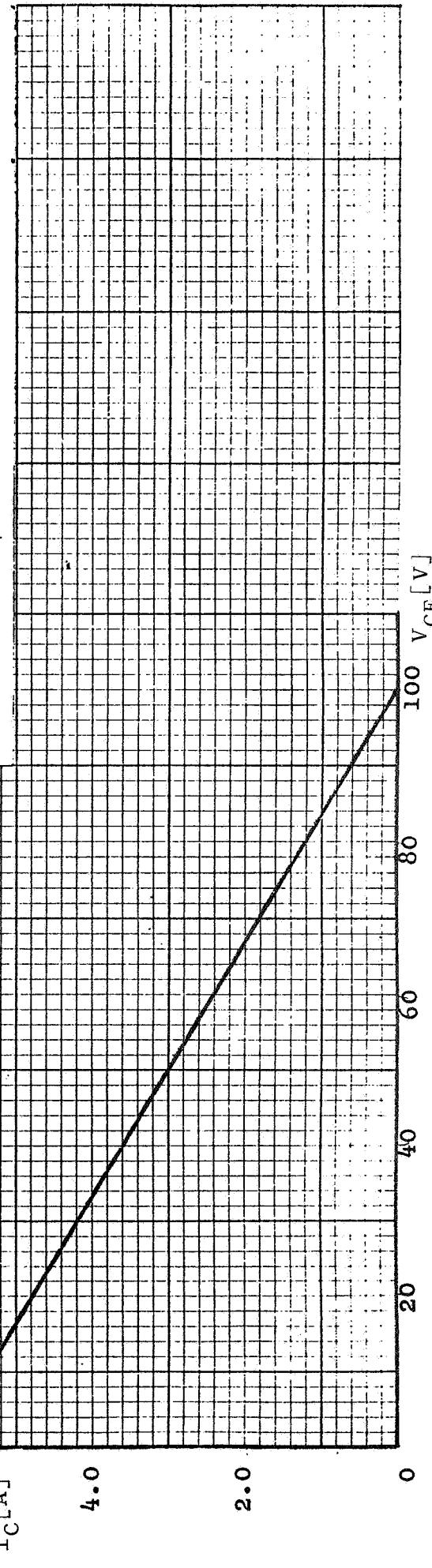
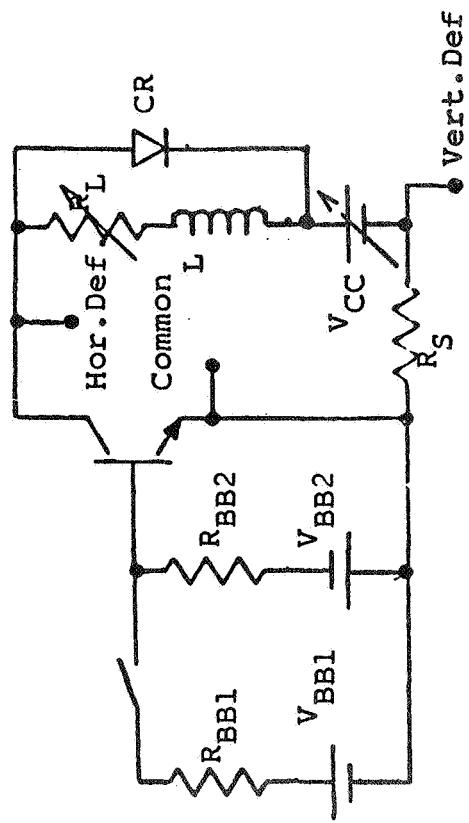
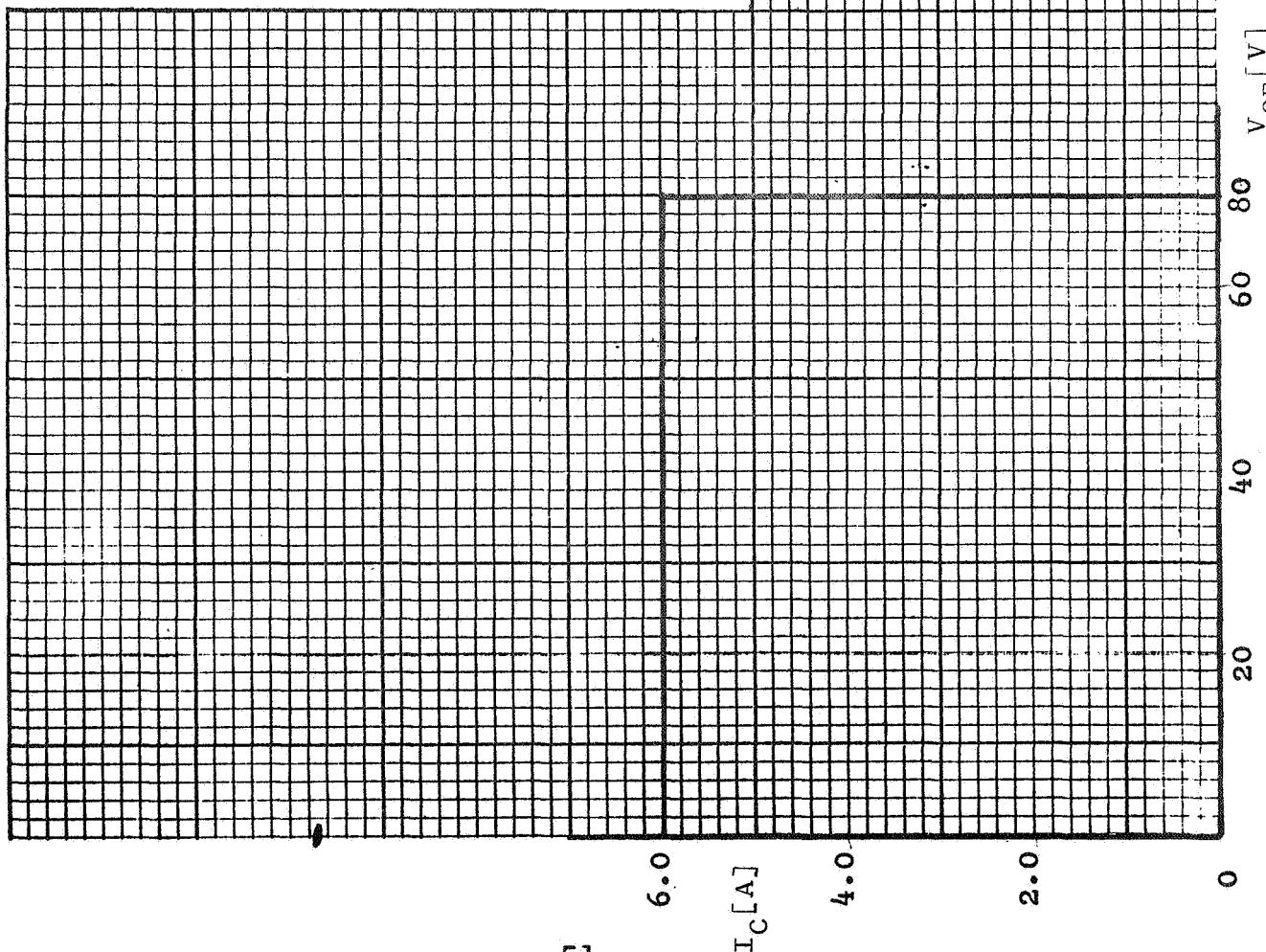


Figure 3

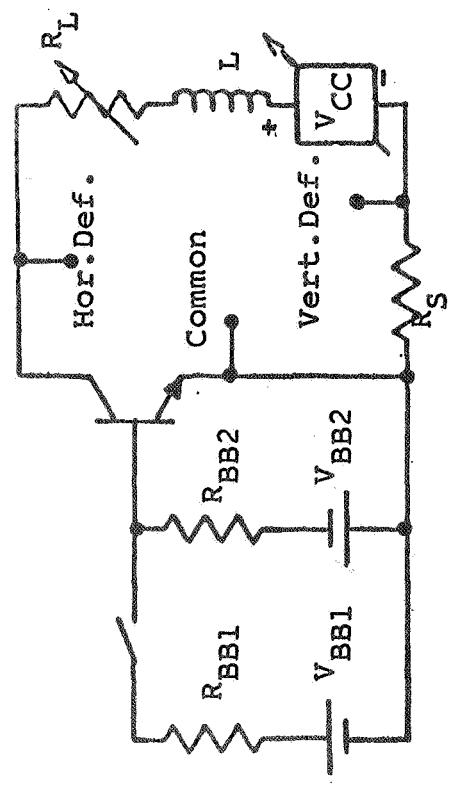
SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1



SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

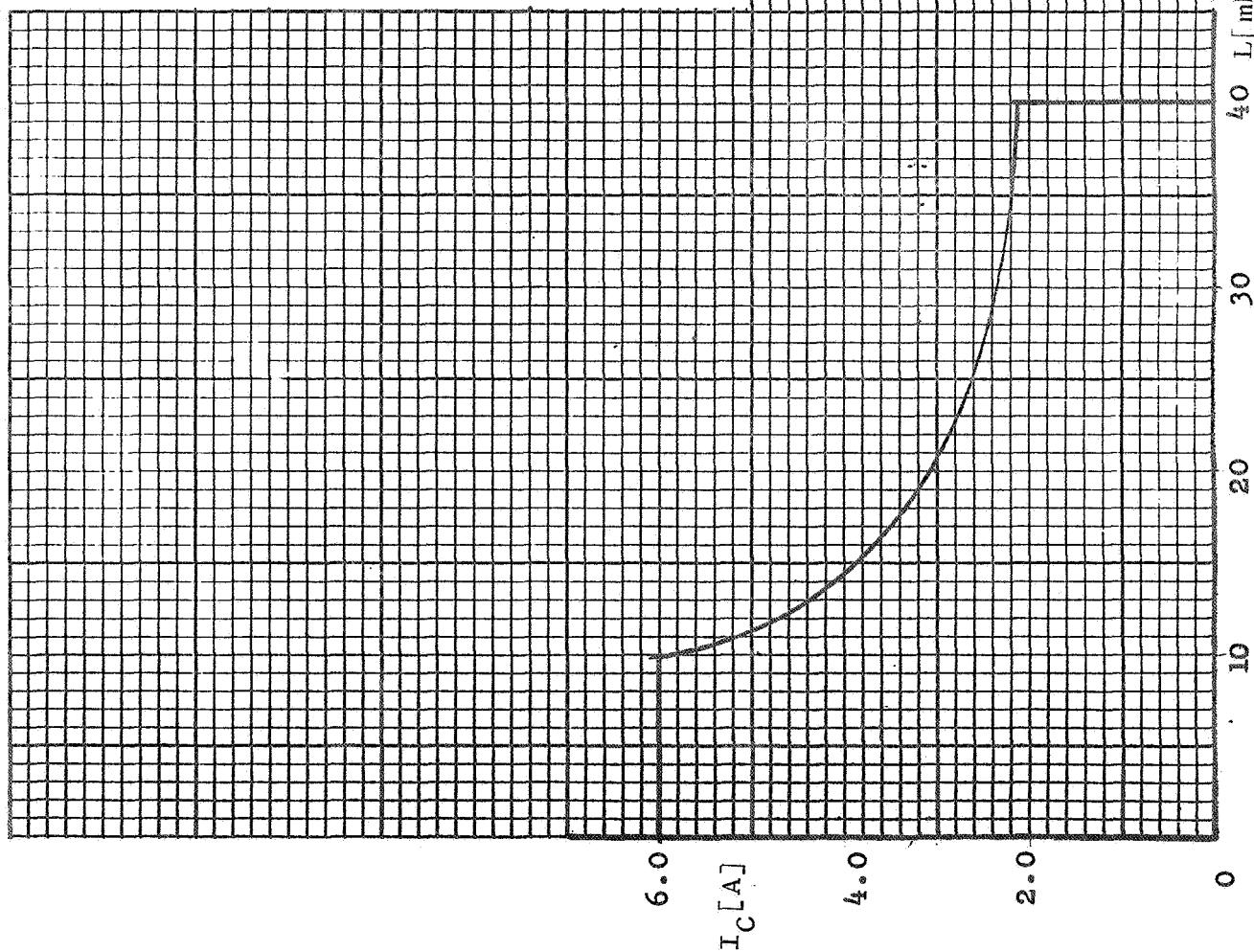


Figure 5

SHORTED CLASS B SOAR

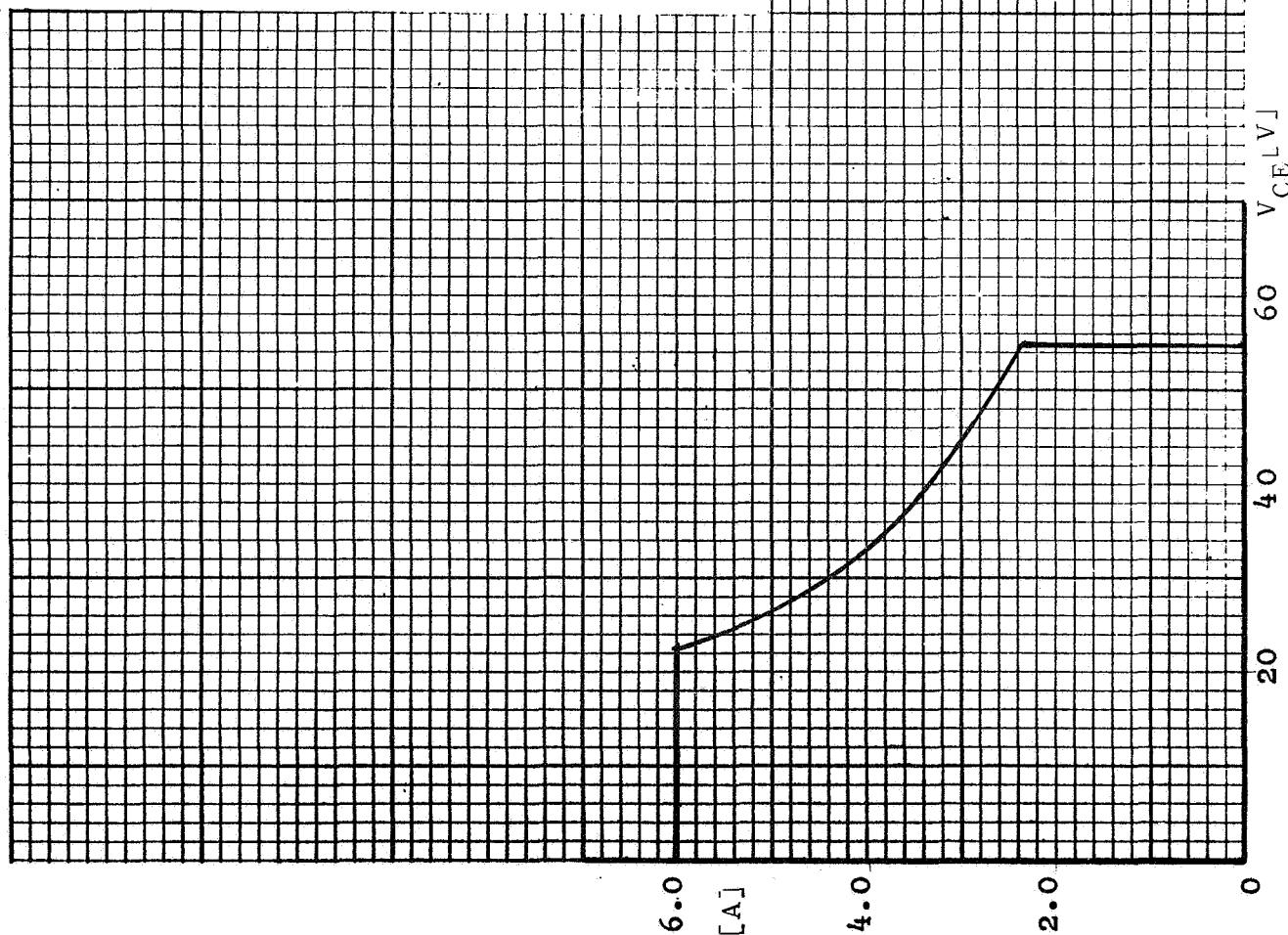
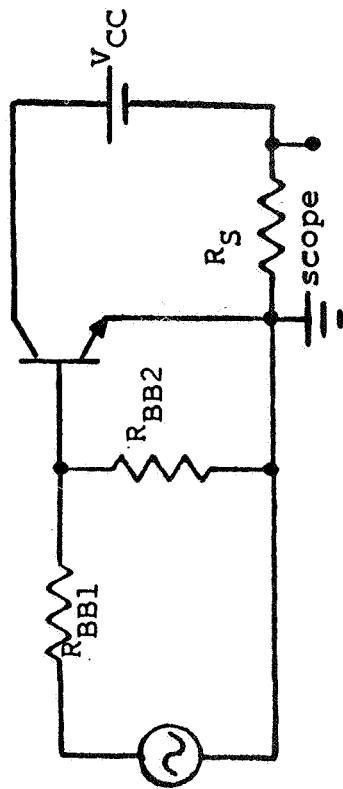


Figure 6

SILICON POWER TRANSISTOR

< Type 2N2102 >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturers D & J --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
1.0.0	<u>General Description</u>	
1.1.0	Type - NPN	
1.2.0	Material - Silicon	
2.0.0	<u>Mechanical Data</u>	
2.1.0	Outline - TO-5	
2.2.0	Terminal Designation 1 - Base 2 - Emitter 3 - Collector Case - Collector	
3.0.0	<u>Maximum Ratings</u>	
3.1.0	Temperature	
3.1.1	$T_{STG(min)} = -65^{\circ}\text{C}$	<u>JS-6-T1.1</u> [ JEDEC Suggested Standard: "Test Procedure for Verification of Maximum Ratings" JEDEC Publication No. 65]
	$T_{STG(max)} = +200^{\circ}\text{C}$	
3.1.2	$T_J(\text{max}) = 200^{\circ}\text{C}$	<u>JS-6-T2</u> $T_C = 100^{\circ}\text{C}$ , $P_T = 2.86\text{W}$ , $I_C = 55\text{mA}$ Distance from case $1/16"$ $\pm$ $1/32"$ Time = 10 sec (max)
3.1.3	$T(\text{Lead}) = 300^{\circ}\text{C}$	
3.2.0	Voltage	
3.2.1	$V_{(\text{BR})\text{CBO}} = 120\text{V}$	<u>JS-6-T3</u>
3.2.2	$V_{(\text{BR})\text{EBO}} = 7\text{V}$	<u>JS-6-T4</u>

<u>Item</u>		<u>Test Methods and Test Conditions</u>
3.2.3	$V_{(BR)CEO} = 65V$	<u>JS-6-T5.1</u> CR Disconnected $I_C = 0.1A, R_{BB1} = 25\Omega, V_{BB1} = 5V,$ $R_{BB2} = \infty\Omega, d = 50\%, f = 60Hz,$ $L^* = 5.0mH, R_L = 0, R_S = 1.0\Omega$ Adjust $V_{CC}$ for specified $I_C$ *Chicago Standard Transformer Corp. C-2689
3.3.0	Current	
3.3.1	$I_C = 1.0A$	<u>JS-6-T6</u> $I_B = 0.3A, T_C = 25^\circ C$
3.3.2	$I_B = 0.3A$	<u>JS-6-T8</u> $T_C = 25^\circ C$
3.3.3	$I_E = 1.3A$	<u>JS-6-T10</u> $I_B = 0.3A, T_C = 25^\circ C$
3.4.0	Power	
3.4.1	$P_T = 2.86W$	<u>JS-6-T12</u> Test Point: See 3.1.2
3.4.2	$P_{TM} = I_C V_{CC} = 80W$	<u>JS-6-T13</u> $T_C = 25^\circ C, V_{CC} = 80, V_{BB} = 5V,$ $R_{BB} = 25, I_C = 1.0A, \text{Pulse Width}=100\mu s$ Duty Cycle $\leq 2\%$ , $t_r \leq 5\mu s$ $t_f \leq 5\mu s$
3.5.0	Maximum Operating Conditions	

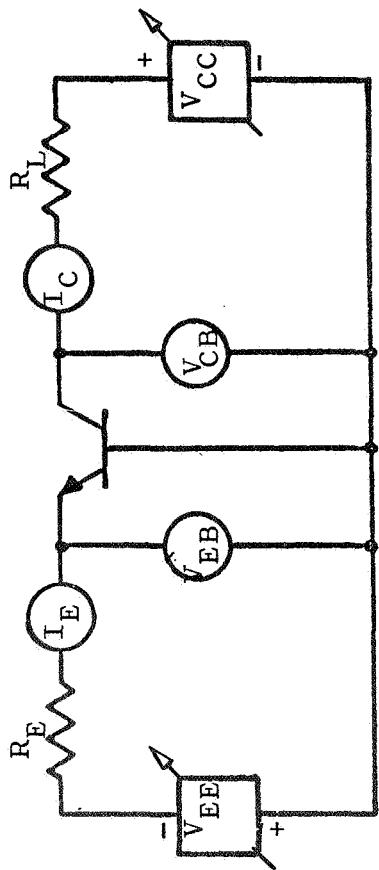
<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.5.1      Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> <u>Test Points:</u> See 3.1.2
3.5.2      Pulsed Forward Biased SOAR	<u>JS-6-T14</u> <u>Test Points:</u> $T_C = 100^\circ C$ , $V_{BB} = 5V$ , $R_{BB} = 20\Omega$ , $t_r \leq 5\mu s$ , $t_p \leq 5\mu s$ , $I_C = 1.0A$ , Duty Cycle $\leq 2\%$ , $R_S = 1.0\Omega$ 1. $t_p = 1ms$ : $V_{CC} = 35V$ 2. $t_p = 500\mu s$ : $V_{CC} = 45V$ 3. $t_p = 100\mu s$ : $V_{CC} = 80V$
3.6.0      SOAR Switching between Saturation and cutoff	
3.6.1      Resistive Load	<u>JS-6-T5.1</u> with $L = 0$ and CR disconnected <u>Test Points:</u> $R_{BB1} = 20\Omega$ , $R_{BB2} = 100\Omega$ , $V_{BB1} = 8.0V$ , $V_{BB2} = 5V$ , $T_C = 100^\circ C$ , $t_f \leq 5\mu s$ , $t_r \leq 5\mu s$ , $R_S = 1.0\Omega$ , $R_L = 78\Omega$ , $V_{CC} = 80V$ , $d = 10\%$
3.6.2      Clamped Inductive Load	<u>JS-6-T5.1</u> <u>Test Point:</u> $I_C \leq 1.0A$ , $V_{CE} = 80V$ , $R_{BB1} = 20\Omega$ , $R_{BB2} = 100\Omega$ , $V_{BB1} = 8V$ , $V_{BB2} = 5V$ , $R_L = 8\Omega$ , $L^* = 1.0mH$ , *J.W.Miller: 7871 in series with 7825-3

<u>Item</u>		<u>Test Methods and Test Conditions</u>
3.6.3	Unclamped Inductive Load	<u>JS-6-T5.1</u> and CR disconnected <u>Test Points:</u> 1. $V_{BB1} = 8.0V$ $L^* = 1.0mH$ $R_{BB1} = 20\Omega$ $R_L = 66.66\Omega$ $V_{BB2} = 5.0V$ $V_{CC} = 10V$ $R_{BB2} = 100\Omega$ $f = 60Hz$ $R_S = 1.0\Omega$ $d = 10\%$ *J.W. Miller: 7871 in series with 7825-3
		2. $V_{BB1} = 8.0V$ $L^* = 50\mu H$ $R_{BB1} = 20\Omega$ $R_L = 7\Omega$ $V_{BB2} = 5V$ $V_{CC} = 10V$ $R_{BB2} = 100\Omega$ $f = 60Hz$ $R_S = 1.0\Omega$ $d = 10\%$ *J.W. Miller: 7825-8
3.7.0	Shorted Class B SOAR	(See Figure 6)
		<u>Test Points:</u> $I_C \text{ peak} = 0.22A$ , $V_{CC} = 32.5V$ , $R_S = 1.0\Omega$ , $R_{BB1} = 20\Omega$ , $R_{BB2} = 100\Omega$ $f = 20Hz$ , $T_C = 100^\circ C$
4.0.0	<u>Electrical Characteristics</u>	$T_C = 25^\circ C$ (unless otherwise noted)  Maximum limits unless otherwise noted  Technique:  DC - Continuous Operation  C.T. - Curve Tracer  P - $300\mu s$ Pulse, 2% Duty Cycle

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
4.1.0	Static	
4.1.1	$I_{CBO} = 2.0\text{nA}$	$V_{CB} = 60\text{V}$ , Technique MIL-STD-3036-10
4.1.2	$I_{CBO} = 2.0\mu\text{A}$	$V_{CB} = 60\text{V}$ , $T_C = 150^\circ\text{C}$ , Technique MIL-STD-3036-D
4.1.3	$I_{EBO} = 2.0\text{nA}$	$V_{BE} = -5\text{V}$ , Technique MIL-STD-3061-D
4.1.4	$V_{(BR)CEO} = 65\text{V}$ min	<u>JS-6-T5.1</u> (See 3.2.3)
4.1.5	$V_{(BR)CER} = 80\text{V}$ min	<u>JS-6-T5.1</u> (See 3.2.3 except $R_{BB2} = 10\Omega$ , $V_{BB2} = 0$ )
4.1.6	$V_{(BR)CBO} = 120\text{V}$ min	$I_C = 1\text{mA}$ Technique C.T.
4.1.7	$V_{(BR)EBO} = 7\text{V}$ min	$I_E = 1\text{mA}$ Technique C.T.
4.1.8	$h_{FE} = 10$ min	$I_C = 1\text{A}$ , $V_{CE} = 10\text{V}$ , Technique - P
4.1.9	$h_{FE} = 25$ min	$I_C = 0.5\text{A}$ , $V_{CE} = 10\text{V}$ Technique P
4.1.10	$h_{FE} = 40$ min 120 max	$I_C = 150\text{mA}$ , $V_{CE} = 10\text{V}$ Technique P
4.1.11	$h_{FE} = 10$ min	$I_C = 10\text{mA}$ , $V_{CE} = 10\text{V}$ Technique C.T.
4.1.12	$h_{FE} = 20$ min	$I_C = 0.1\text{mA}$ , $V_{CE} = 10\text{V}$ Technique C.T.
4.1.13	$h_{FE} = 35$ max	$I_C = 10\text{mA}$ , $V_{CE} = 10\text{V}$ , $T_C = 55^\circ\text{C}$ Technique C.T.
4.1.14	$V_{CE(S)} = 2.0\text{V}$ max	$I_C = 1.0\text{A}$ , $I_B = 0.2\text{A}$ Technique C.T.
4.1.15	$V_{CE(S)} = 0.5\text{V}$ max	$I_C = 150\text{mA}$ , $I_B = 15\text{mA}$ Technique C.T.
4.1.16	$V_{BE(S)} = 2.5\text{V}$ max	$I_C = 1.0\text{A}$ , $I_B = 0.2\text{A}$ Technique C.T.
4.1.17	$V_{BE(S)} = 1.1\text{V}$ max	$I_C = 150\text{mA}$ , $I_B = 15\text{mA}$ Technique C.T.
4.1.18	$I_{CEO} = 1.0\mu\text{A}$ max	$V_{CEO} = 55\text{V}$ Technique D.C.
4.1.19	$V_{BEF} = 1.5\text{V}$ max	$V_{CB} = 120\text{V}$ Technique C.T.
4.2.0	Dynamic	
4.2.1	$t_d + t_r + t_f = 30\text{ns}$	Circuit specified with registered spec.

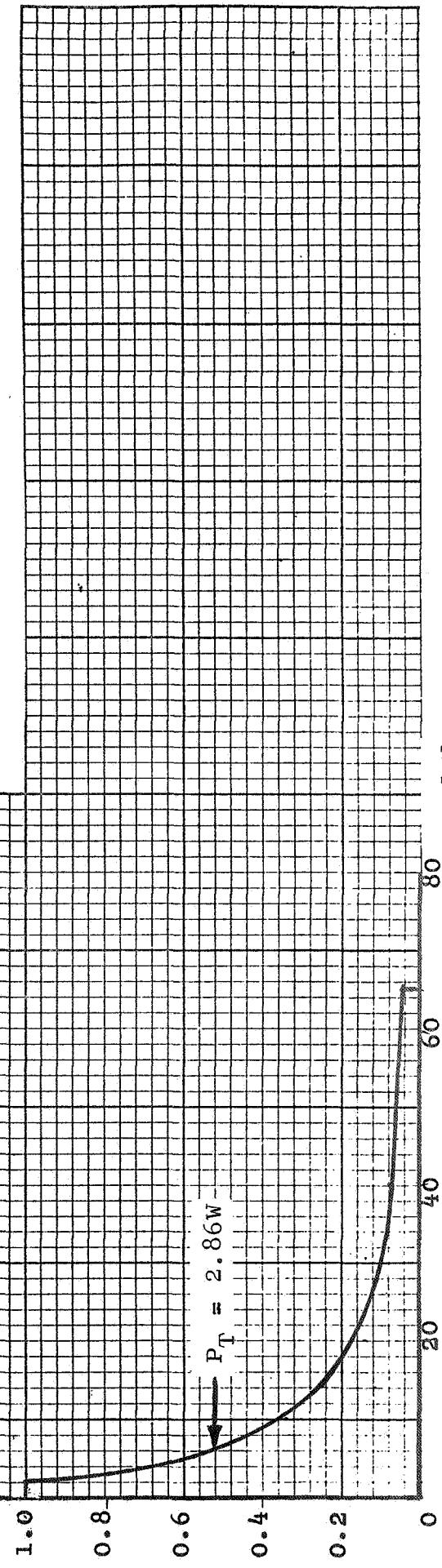
<u>Item</u>	<u>Test Methods and Test Conditions</u>	
4.2.2	$h_{fe} = 30 \text{ min, } 100 \text{ max}$	$I_C = 1.0\text{mA, } V_{CE} = 5V, f = 1.0\text{KHz}$
4.2.3	$h_{fe} = 35 \text{ min, } 150 \text{ max}$	$I_C = 5.0\text{mA, } V_{CE} = 10V, f = 1.0\text{KHz}$
4.2.4	$h_{fe} = 3 \text{ min, } 10 \text{ max}$	$I_C = 50\text{mA, } V_{CE} = 10V, f = 20\text{MHz}$
4.2.5	$NF = 6\text{db}$	$I_C = 0.3\text{mA, } V_{CE} = 10V, f = 1\text{KHz}$ $R = 1\text{K}\Omega \text{ circuit bandwidth } 1\text{Hz}$
4.2.6	$C_{obo} = 15\text{pf}$	$V_{CB} = 10V$
4.2.7	$C_{ibo} = 80\text{pF}$	$V_{BE} = 0.5V$
4.2.8	$h_{ob} = 0.1 \mu\text{mhos min}$	$I_C = 1.0\text{mA, } V_{CE} = 5V, f = 1\text{KHz}$
4.2.9	$h_{ob} = 0.1 \mu\text{mhos min}$ $1.0 \mu\text{mhos max}$	$I_C = 5.0\text{mA, } V_{CE} = 10V, f = 1\text{KHz}$
4.2.10	$h_{ib} = 24\Omega \text{ min, } 34\Omega \text{ max}$	$I_C = 1.0\text{mA, } V_{CE} = 5V, f = 1\text{KHz}$
4.2.11	$h_{ib} = 4\Omega \text{ min, } 8\Omega \text{ max}$	$I_C = 5.0\text{mA, } V_{CE} = 10V, f = 1\text{KHz}$
4.2.12	$h_{rb} = 3 \times 10^{-4}$	$I_C = 1.0\text{mA, } V_{CE} = 5.0V, f = 1\text{KHz}$
4.2.13	$h_{rb} = 3 \times 10^{-4}$	$I_C = 5.0\text{mA, } V_{CE} = 10V, f = 1\text{KHz}$
5.0.0	Thermal Characteristics	
5.1.0	$\tau_J = 75\text{ms min}$	
5.2.0	$\theta_{JC} = 35^{\circ}\text{C/W max}$	
5.2.1	$\theta_{JA} = 175^{\circ}\text{C/W max}$	

FORWARD BIASED CONTINUOUS SOAR

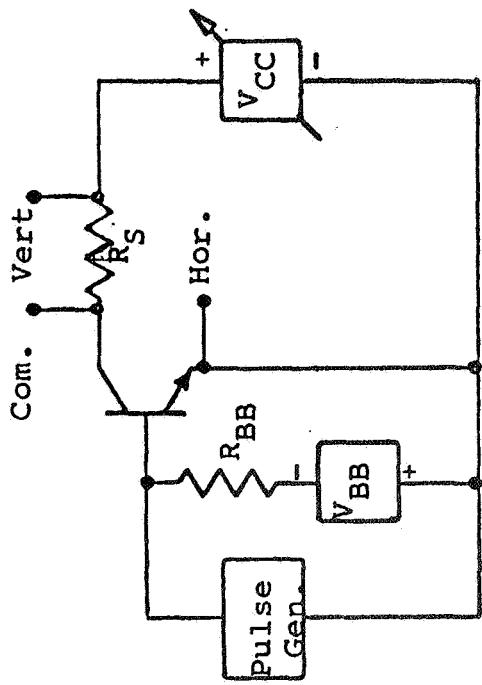


Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CEO}$

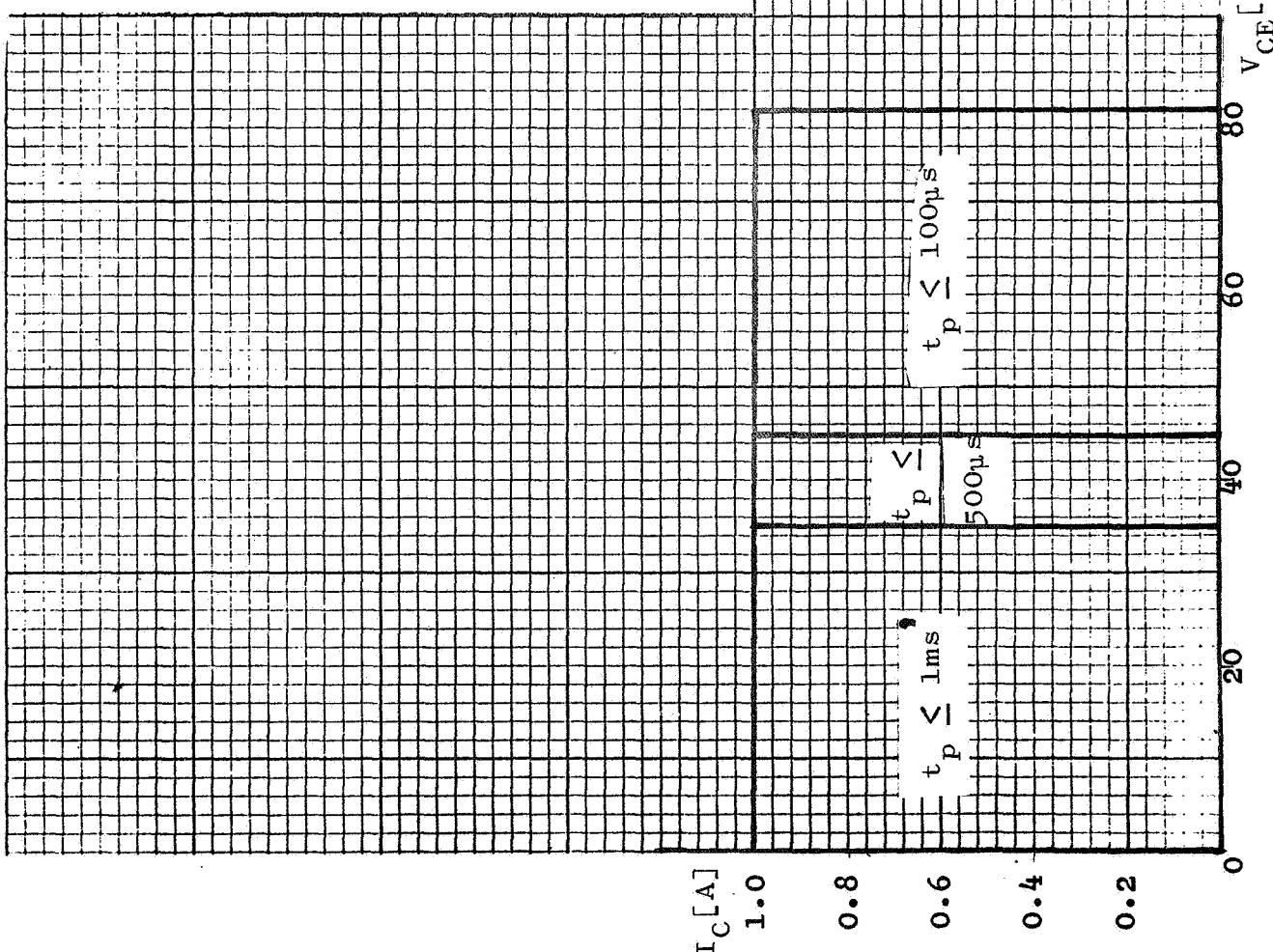
Test Circuit: JS-6-T12



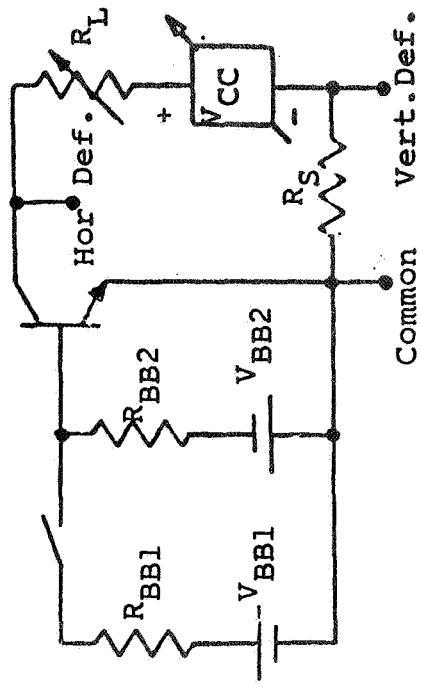
PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14



SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

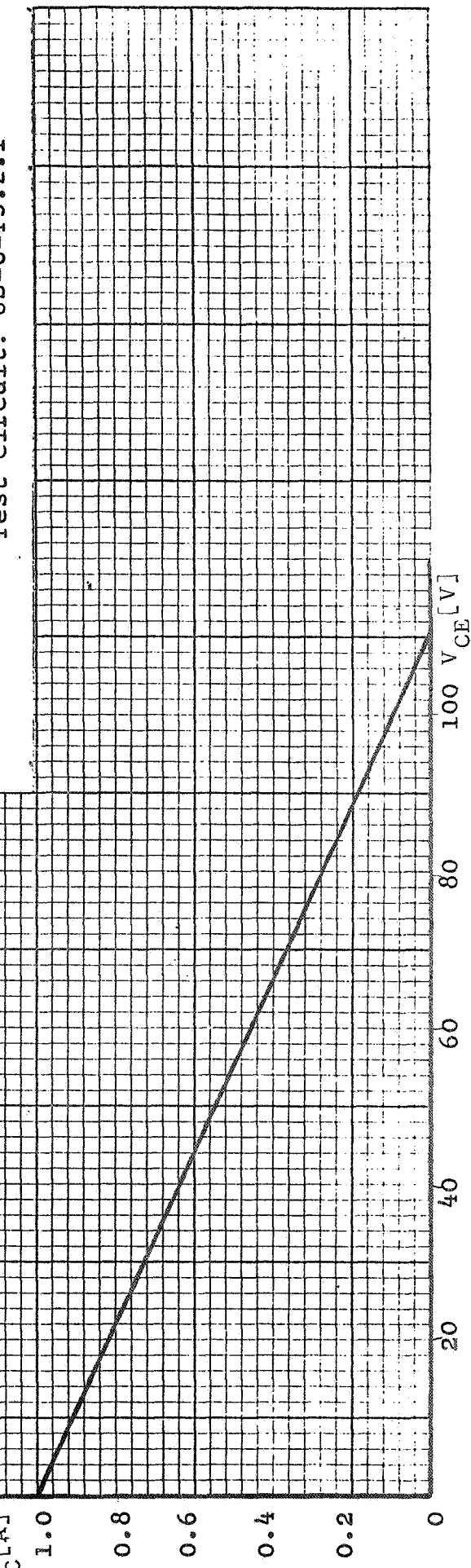
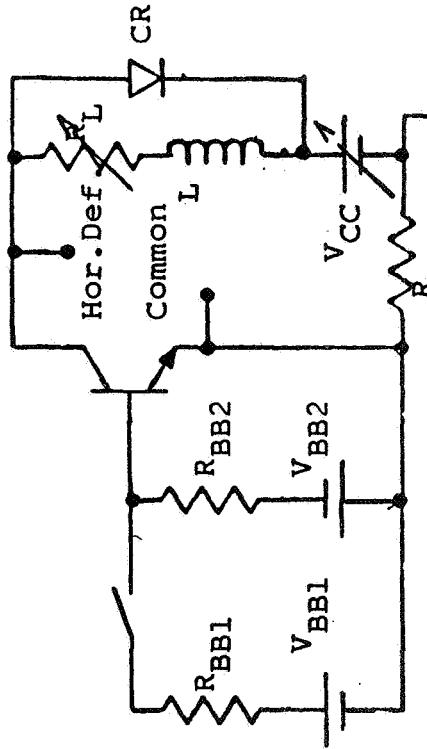


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

64.

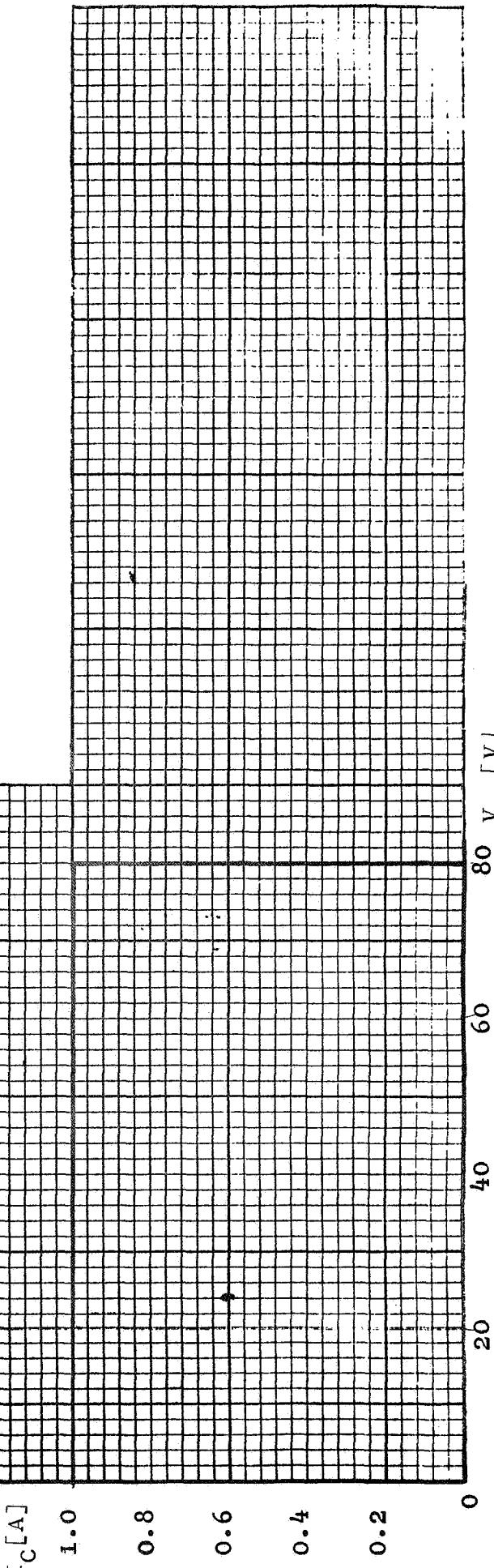
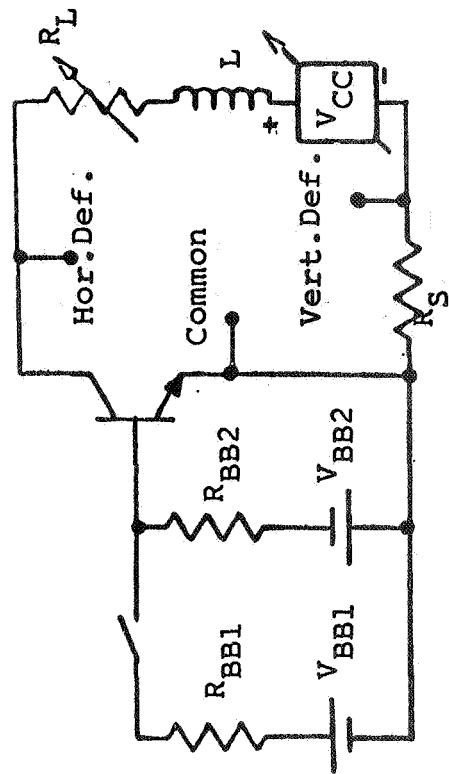
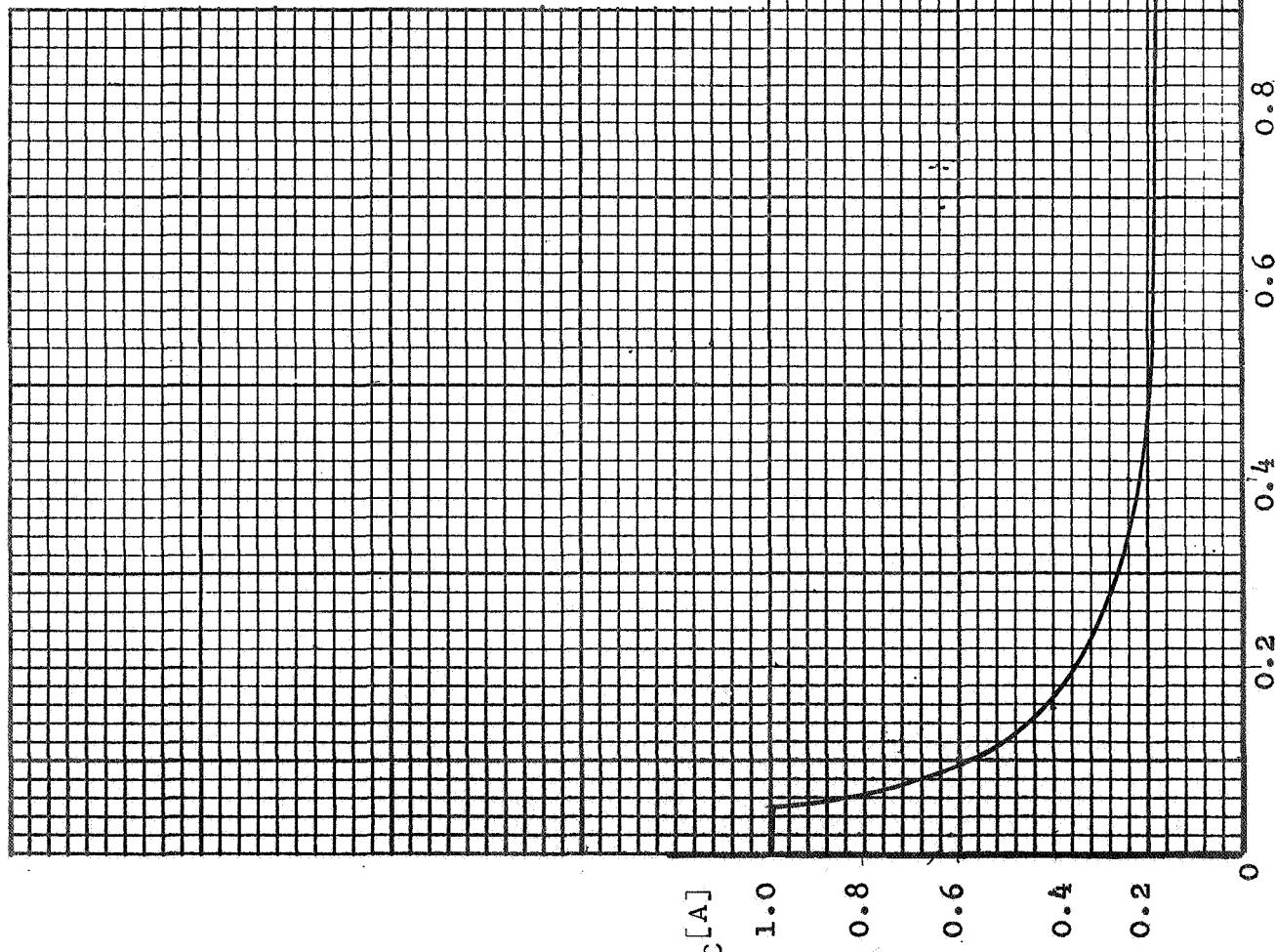


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1



SHORTED CLASS B SOAR

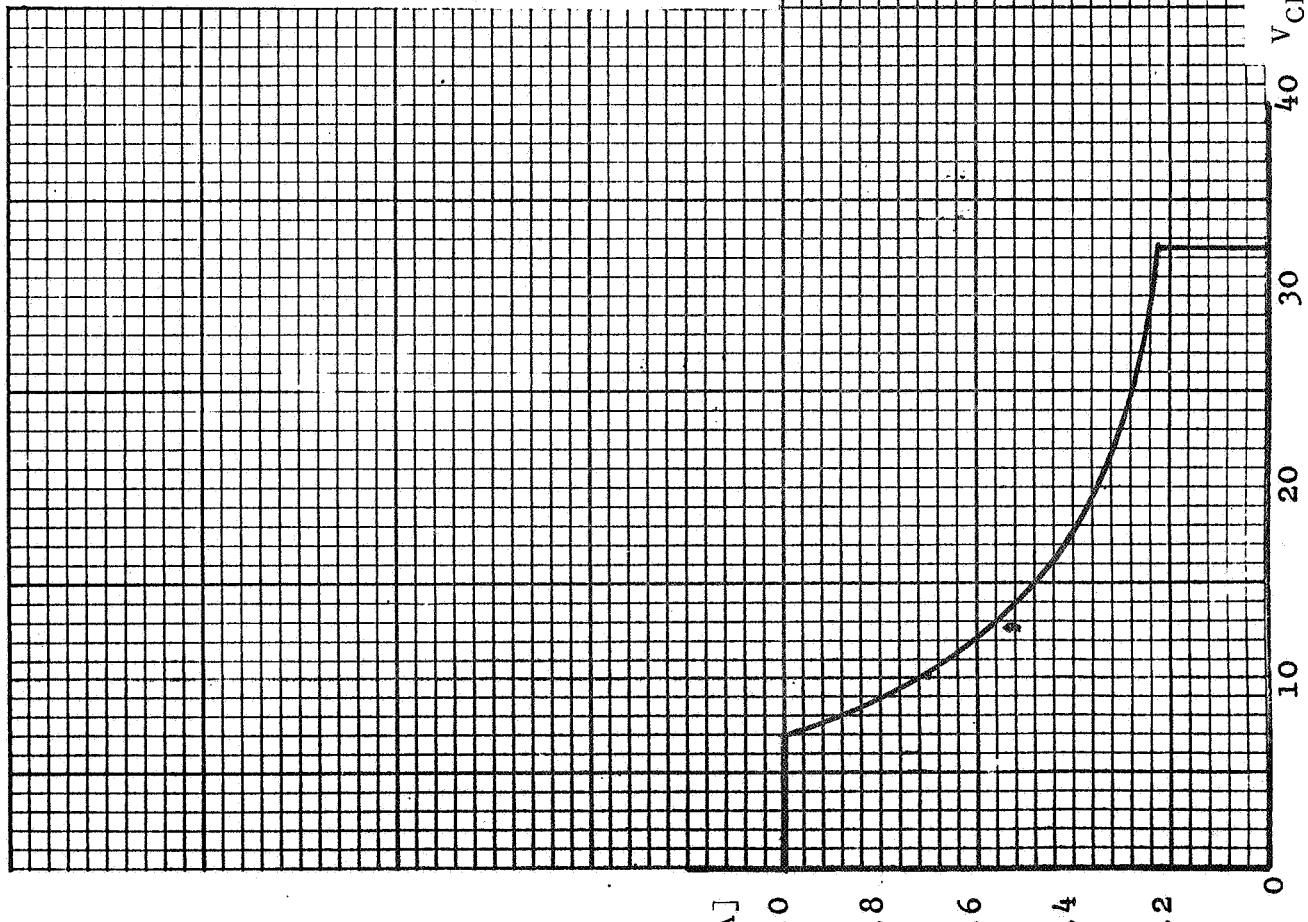
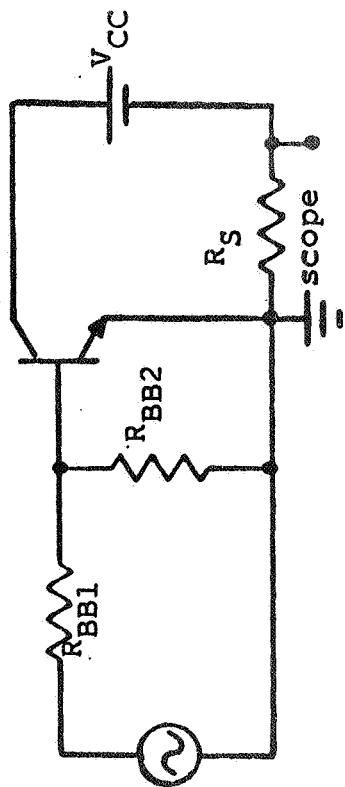


Figure 6

SILICON POWER TRANSISTOR

< S2N2034A >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer H --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Methods and Test Conditions</u>
1.0.0 <u>General Description</u>	
1.1.0      Type - NPN	
1.2.0      Material - Silicon	
2.0.0 <u>Mechanical Data</u>	
2.1.0      Outline = T05	
2.2.0      Terminal Designation	
	1. -- Emitter
	2. -- Base
	3. -- Collector
	case -- Collector
3.0.0 <u>Maximum Ratings</u>	
3.1.0      Temperature	
3.1.1 $T_{STG(max)} = +200^{\circ}\text{C}$	<u>JS-6-T1.2</u> [ JEDEC Publication No.65 "Test Procedures for
$T_{STG(min)} = -65^{\circ}\text{C}$	<u>JS-6-T1.1</u> Verification of Maximum Ratings.]
3.1.2 $T_J(max) = 200^{\circ}\text{C}$	<u>JS-6-T2</u> $T_C = 100^{\circ}\text{C}$ $V_{CB} = 60\text{V}$ , $I_C = 83\text{mA}$
3.1.3 $T$ (Lead) = $230^{\circ}\text{C}$	Distance from case - 1/16 in. Time = 3.0s
3.2.0      Voltage	$T_C = 25^{\circ}\text{C}$
3.2.1 $V_{CBO} = 80\text{V}$	<u>JS-6-T3</u> or MIL-STD-750A Method 3001.1

<u>Item</u>		<u>Test Method and Test Conditions</u>
3.2.2	$V_{EBO} = 10V$	<u>JS-6-T4 or MIL-STD-750A</u> <u>Method 3026.1</u>
3.2.3	$V_{CEX} = 60V$	<u>JS-6-T5.1</u> $I_C (V_{CE} = V_{CEX}) = 3A$ $V_{CC} = 60V, R_L = 19.6\Omega$ $L = 1.0mH^*, CR = 1N1202$ $V_{BB1} = 6V, R_{BB1} = 5\Omega$ $V_{BB2} = 1.5V, R_{BB2} = 5\Omega$ Pulse width = 1.0ms, Duty Cycle = 2% $R_S = 0.1\Omega, t_r \leq 50\mu s$ $t_f \leq 50 \mu s$ *Miller # 7871 in series with 7825-3
3.3.0	Current	
3.3.1	$I_C = 3A$	<u>JS-6-T6</u> $I_B = 0.6A, T_C = \leq 25^\circ C$
3.3.2	$I_B = 1A$	<u>JS-6-T8</u> $T_C = \leq 25^\circ C$
3.4.0	Power	
3.4.1	$P_T = 5W$	<u>JS-6-T12</u> $T_C = \leq 100^\circ C$ $V_{CB} = 60V, I_C = 83mA$ Derating Factor = 0.05 W/ $^\circ C$
3.4.2	$P_{TM} = I_C V_{CC} = 180W$	<u>JS-6-T13</u> $T_C = 100^\circ C, V_{CC} = 60V, V_{BB} = 1.5V,$ $R_{BB} = 5\Omega$

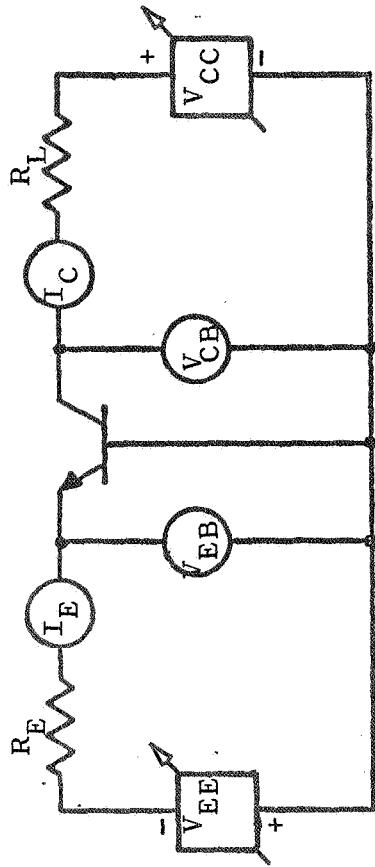
<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.4.2 (Cont'd)	Pulse width = 1ms, Duty Cycle = $\leq 1\%$ , $t_r \leq 50\mu s$ , $t_f = \leq 50\mu s$
3.5.0 Maximum Operating Conditions	
3.5.1 Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> [See Figure 1] <u>Test Point:</u> [See 3.4.1]
3.5.2 Pulsed Forward Biased SOAR	<u>JS-6-T14</u> [See Figure 2] <u>Test Points:</u> $T_C \leq 100^\circ C$ , $V_{BB} = 1.5V$ , $R_{BB} = 5\Omega$ $t_r \leq 50\mu s$ , $t_f \leq 50\mu s$ , $I_C = 3A$ Duty Cycle $\leq 1\%$ , $R_S = 0.1\Omega$ 1. For $t_p = 7.5ms$ ; $V_{CC} = 20V$ 2. For $t_p = 5.0ms$ ; $V_{CC} = 30V$ 3. For $t_p = 2.5ms$ ; $V_{CC} = 50V$ 4. For $t_p = 1ms$ ; $V_{CC} = 60V$
3.6.0 SOAR Switching between Saturation and Cutoff	
3.6.1 Resistive Load	<u>JS-6-T5-5.1</u> with $L=0$ and CR disconnected [See Figure 3] <u>Test Points:</u> $I_C = 3A$ , $V_{CC} = 90V$ , $R_{BB1} = 5\Omega$ $R_{BB2} = 5\Omega$ , $V_{BB1} = 6V$ , $V_{BB2} = 1.5V$ $T_C = 100^\circ C$ ; $t_f \leq 50\mu s$ , Collector Current

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.6.1 (Cont'd)	$t_r \leq 50\mu s$ Collector Current $R_S = .1\Omega$
3.6.2 Clamped Inductive Load	<u>JS-6-T5-5.1</u> [See Figure 4] <u>Test Points:</u> $I_C = 3A, V_{CC} = 60V, R_L = 19.6\Omega$ $L = 1mH^*, R_{BB1} = 5\Omega, R_{BB2} = 5\Omega$ $V_{BB1} = 6V, V_{BB2} = 1.5V, t_p = 1ms$ $CR = 1N1202, T_C = 25^\circ C, t_r \leq 50\mu s,$ $t_f \leq 50\mu s$ Duty Cycle = 2%, $R_S = 0.1\Omega$ *Miller # 7871 in series with 7825-3
3.6.3 Unclamped Inductive Load	<u>JS-6-T5-5.1</u> with CR disconnected [See Figure 5] <u>Test Points:</u> $R_{BB1} = 5\Omega, R_{BB2} = 5\Omega, R_S = .1\Omega$ $V_{BB1} = 6V, V_{BB2} = 1.5V, f = 20Hz$ $T_C = 25^\circ C, d = 10\%$ 1. $I_C = 3A, V_{CC} = 50V, R_L = 16.23\Omega$ $L = 15mH^*$ 2. $I_C = 0.9A, V_{CC} = 35V, R_L = 38.5\Omega$ $L = 60mH^{**}$ *Series Stancor C-2688 & C-2689 **Series 2 Stancor C-2686 & C-2688
3.7.0 Shorted Class B SOAR	[See Figure 6] <u>Test Point:</u> $I_{C(peak)} = 0.25A, V_{CC} = 60V, R_S = .1\Omega$ $R_{BB1} = 1\Omega, R_{BB2} = 3\Omega, f = 20Hz$ $T_C \leq 100^\circ C$

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
4.0.0	<u>Electrical Characteristic</u>	
	Maximum limits unless otherwise noted.	$T_C = 25^\circ C$ [unless otherwise noted]
	Technique:	
	DC - Continuous Operation	
	C.T. - Curve Tracer	
	P - $300\mu s$ Pulse 2% Duty Cycle	
4.1.0	Static	
4.1.1	$I_{CEX} = 750\mu A$	$V_{CE} = 80V, V_{BE} = -1.5V, T_C = 150^\circ C$ Technique - C.T.
4.1.2	$I_{CEX} = 150\mu A$	$V_{CE} = 80V, V_{BE} = -1.5V$ Technique - C.T.
4.1.3	$I_{CBO} = 150\mu A$	$V_{CB} = 80V$ Technique - C.T.
4.1.4	$I_{EBO} = 50\mu A$	$V_{EB} = 10V$ Technique - C.T.
4.1.5	$V_{[BR]CEO} = 60V$ min	$I_C = 50mA$ Technique - C.T.
4.1.6	$I_{CEO} = 100\mu A$	$V_{CE} = 45V$ Technique - C.T.
4.1.7	$h_{FE} = 20$ min $h_{FE} = 60$ max	$V_{CE} = 4V, I_C = 1A$ Technique - C.T.
4.1.8	$h_{FE} = 20$ min	$V_{CE} = 4V, I_C = 1A, T_C = -55^\circ C$ Technique - C.T.

<u>Item</u>		<u>Test Methods and Test Conditions</u>
4.1.9	$V_{CE[sat]} = 0.3V$	$I_C = 1A, I_B = 0.1A$ Technique - C.T.
4.1.10	$V_{BE} = 1.2V$	$V_{CE} = 4; I_C = 1A$ Technique - C.T.
4.1.11	$V_{CE[sat]} = 1V$	$I_C = 3A, I_B = 0.3A$
4.1.12	$V_{BE[sat]} = 1.5V$	$I_C = 3A, I_B = 0.3A$ Technique - C.T.
4.2.4	$t_{on} = 1.0\mu s$	$V_{CC} = 12V, I_C = 1.0A, I_{B1} = 100mA$
4.2.5	$t_{off} = 1.5\mu s$	$V_{CC} = 12V, I_C = 1.0A, I_{B1} = 100mA,$ $I_{B2} = -50mA$
4.2.7	$\left  h_{fe} \right _{min} = 1$ $\left  h_{fe} \right _{max} = 6$	$V_{CE} = 4V, I_C = 0.1A$ $f = 1.0MHz$
5.0.0		<u>Thermal Characteristics</u>
5.1.0	$\tau_J = 80ms \text{ min}$	$I_C = 1A, V_{CE} = 5V, T_C = 25^\circ C$ MIL-STD-750 Method 3146.1
5.2.0	$\theta_{J-C} = 20^\circ C/W$	$I_C = 1A, V_{CE} = 5V$ MIL-STD-750A Method 3136

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CEO}$

Test Circuit: JS-6-T12

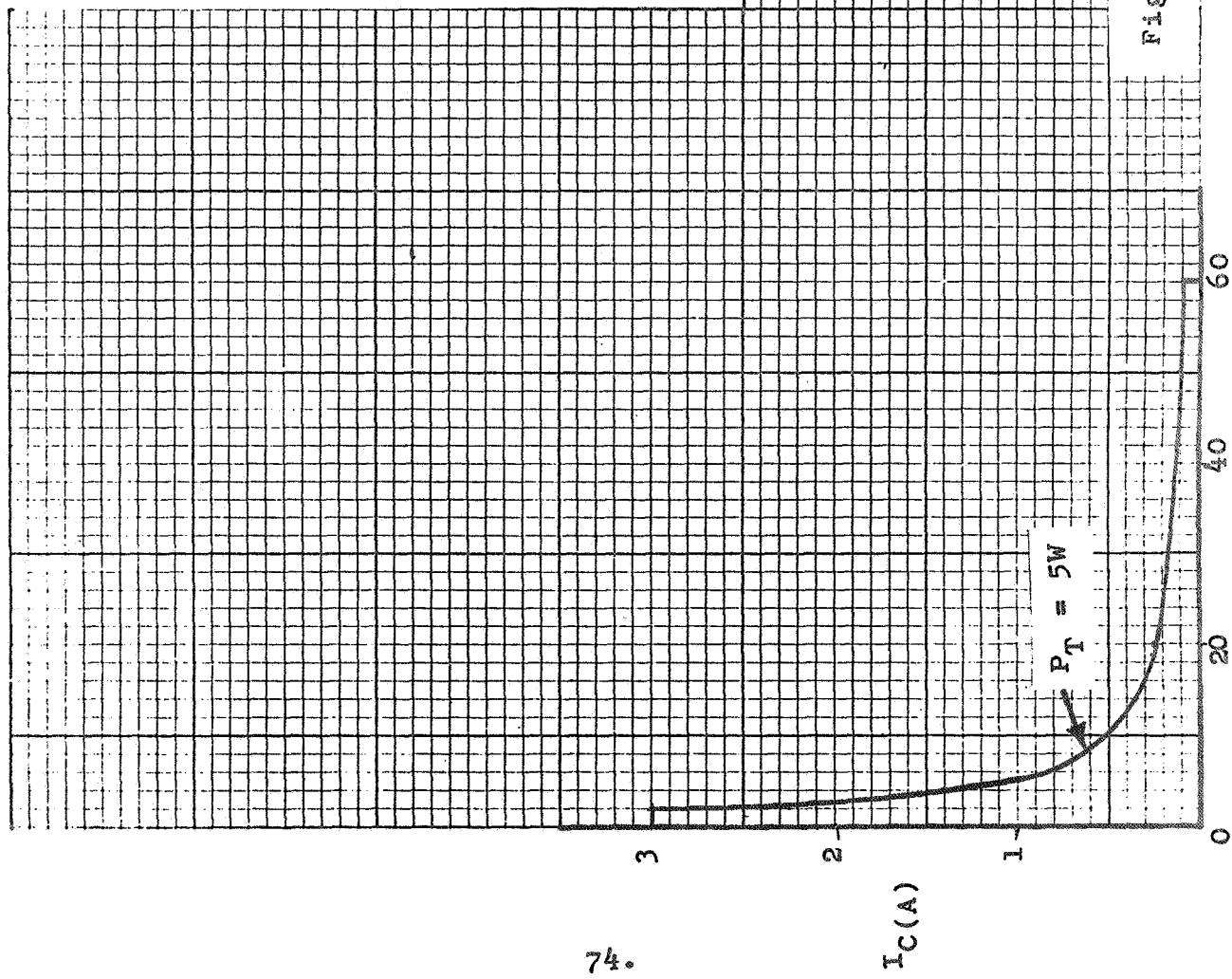
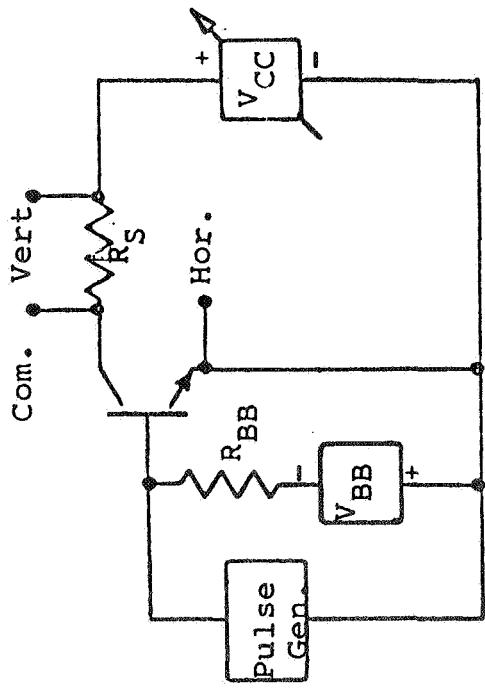


Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

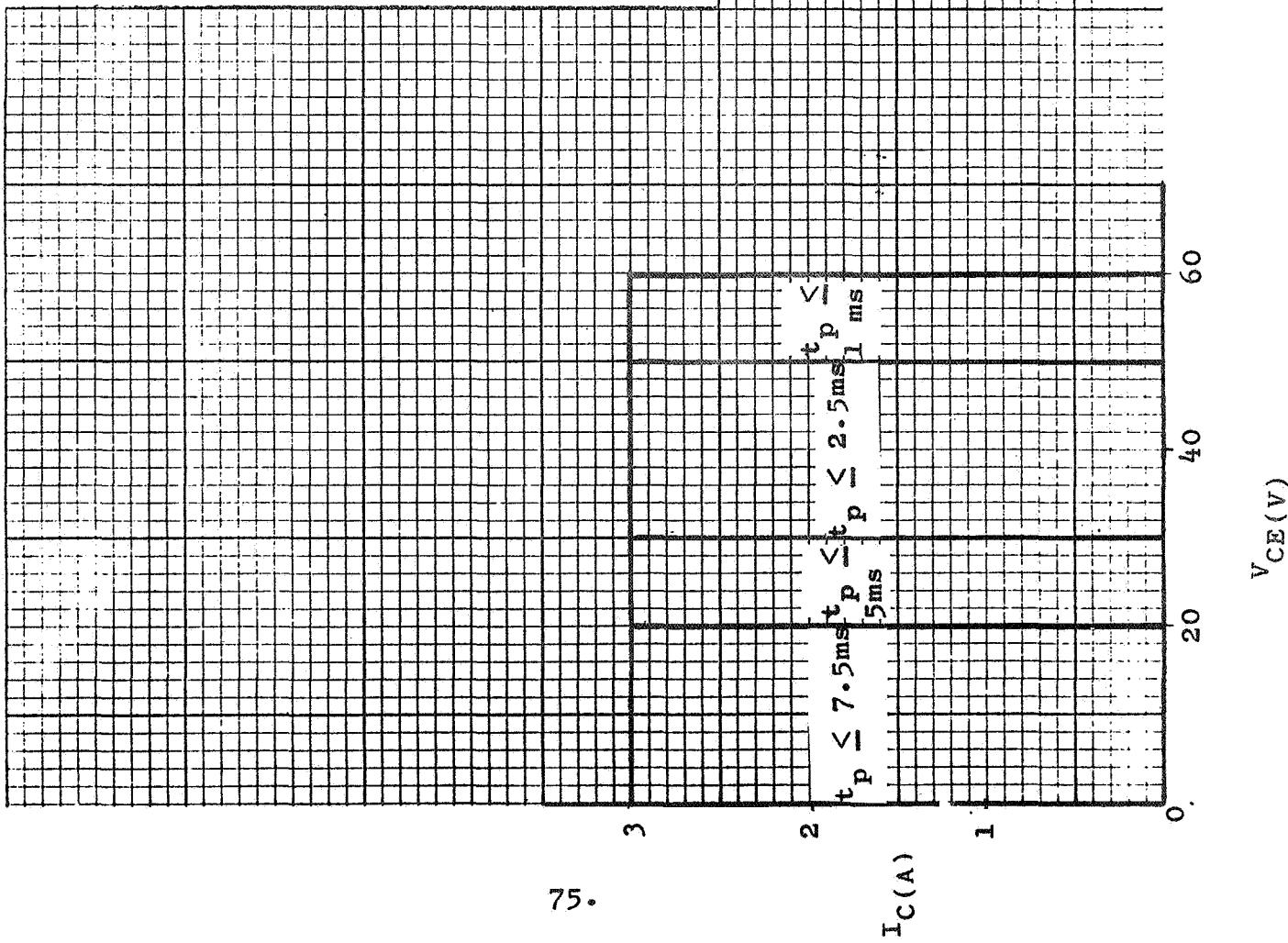
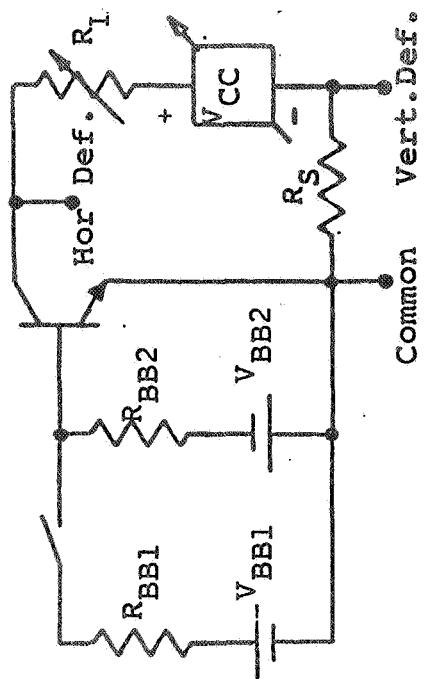


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

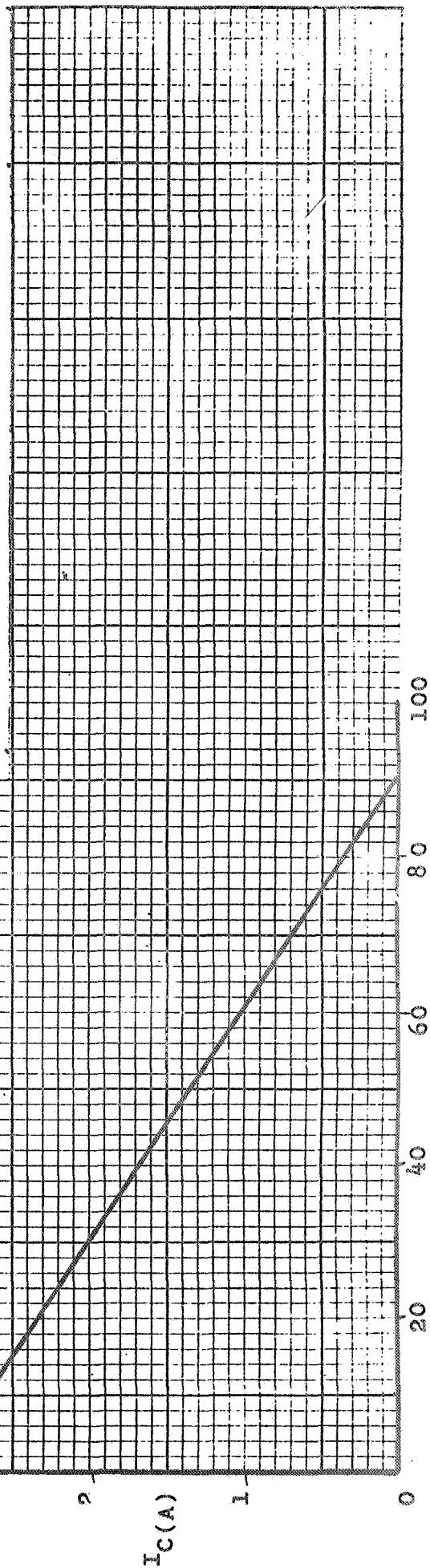
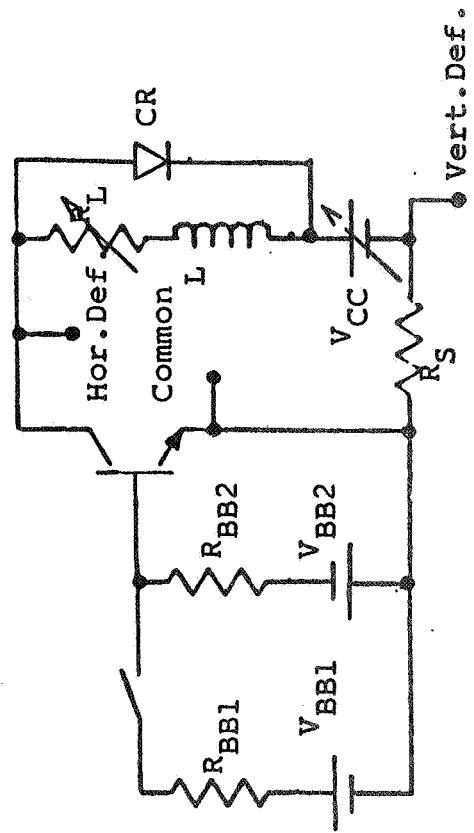


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

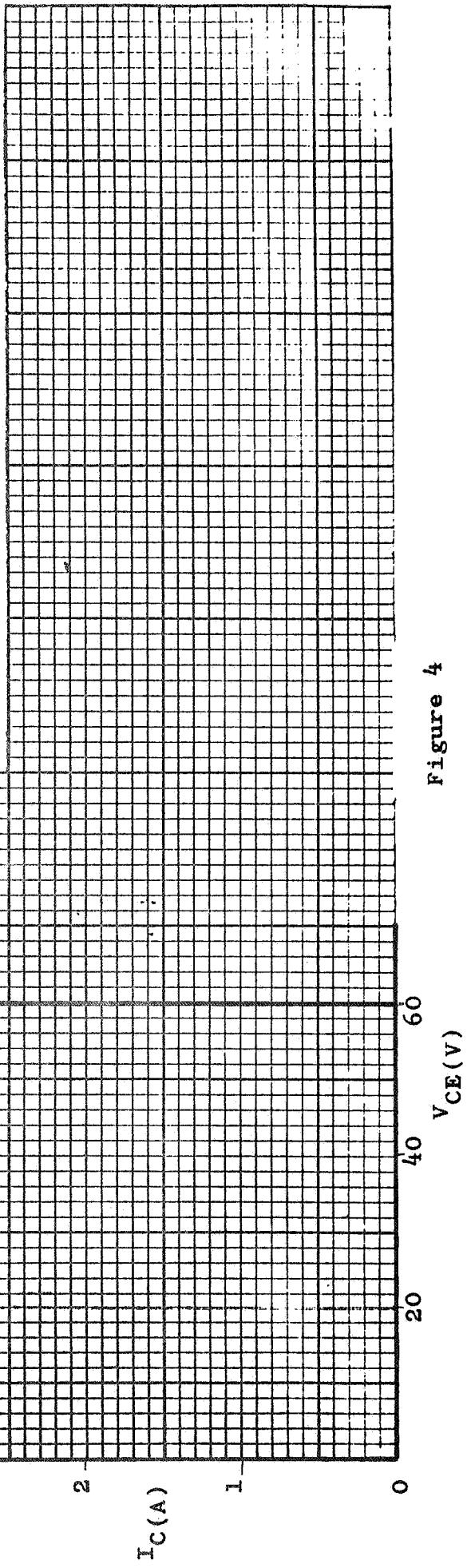
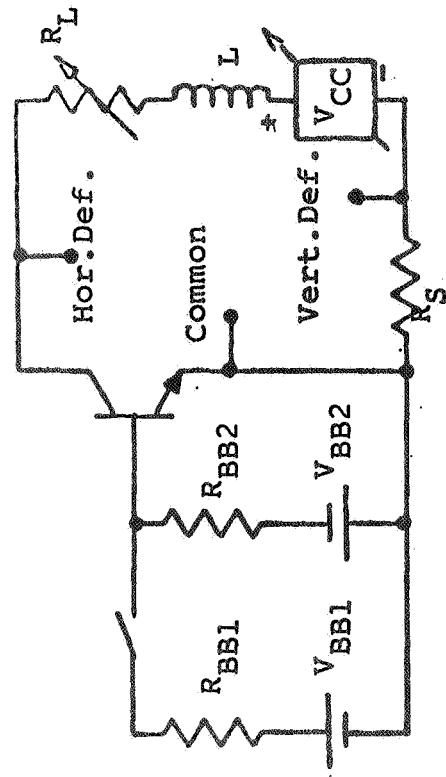
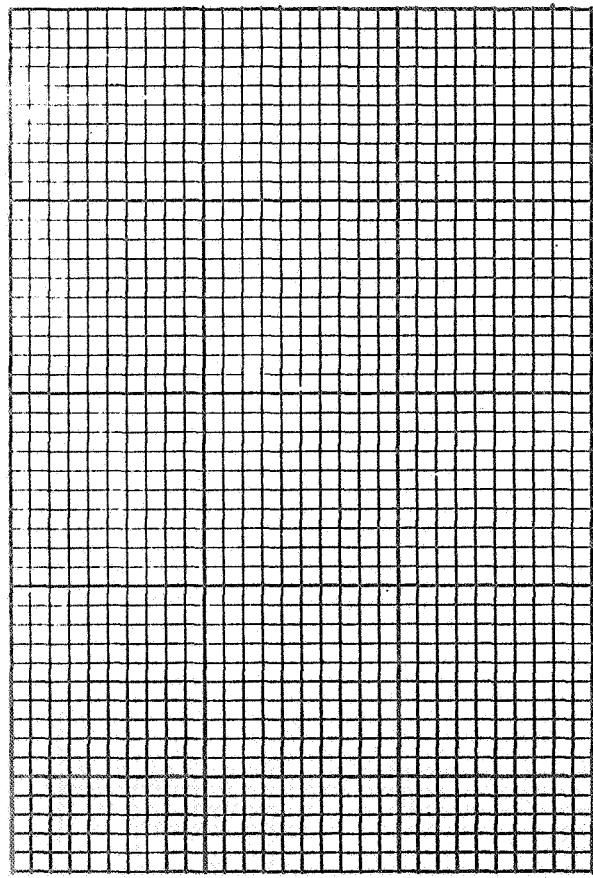


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-UNCLAMPED INDUCTIVE LOAD

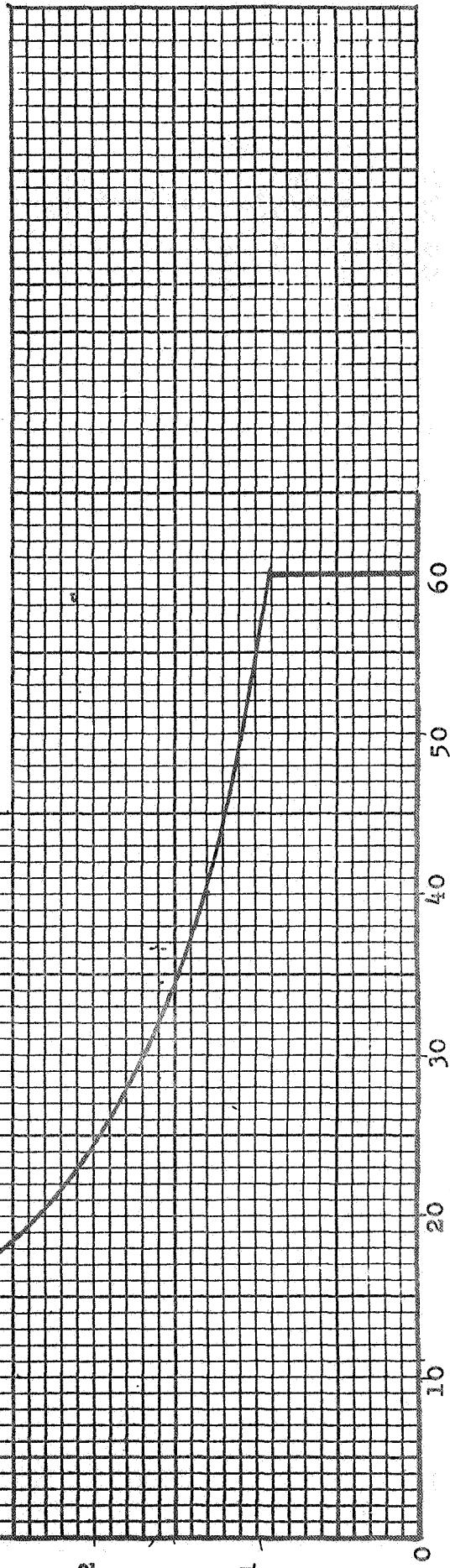


Test Circuit: JS-6-T5-2.1



$I_C$  [A]

78.



$L$  [mH]

Figure 5

SHORTED CLASS B SOAR

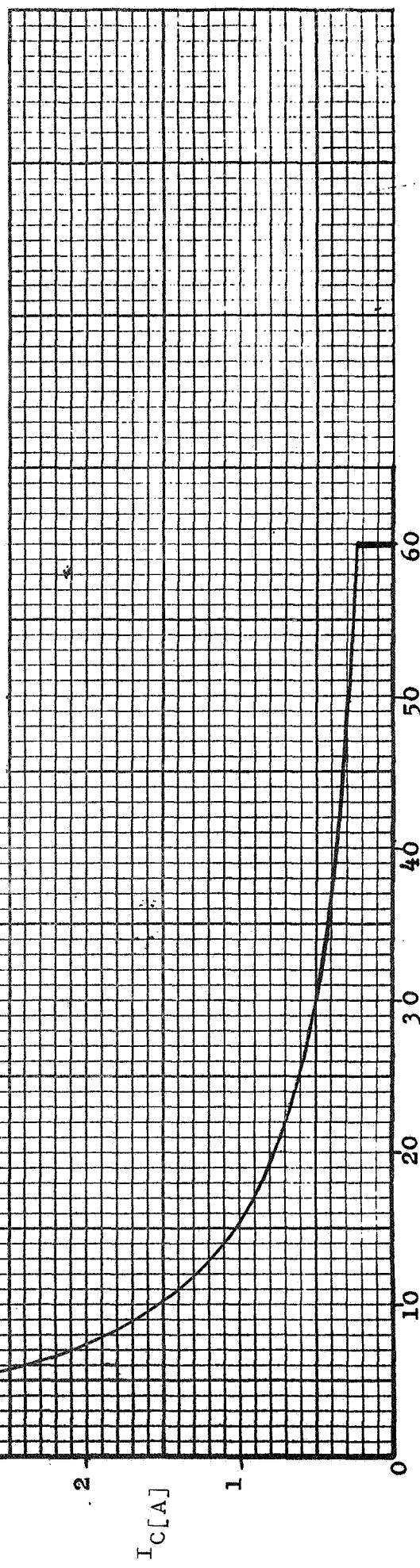
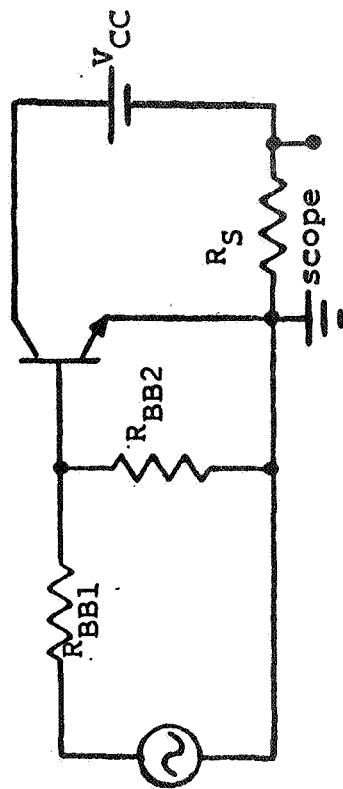


Figure 6

Silicon Power Transistor

< Type 2N2126 >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer C --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER

HUNTSVILLE, ALABAMA

Contract No. NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
1.0.0	<u>General Description</u>	
1.1.0	Type - NPN	
1.2.0	Material - Silicon	
2.0.0	Terminal Designation	
	1 - Base	
	2 - Emitter	
	3 - Collector	
	case - Collector	
2.2.1	Maximum Stud Torque - 100 in.lbs.	
3.0.0	<u>Maximum Ratings</u>	
3.1.0	Temperature	
3.1.1	$T_{stg}^{(max)} = +175^{\circ}\text{C}$	<u>JS-6-T1.1</u>
	$T_{stg}^{(min)} = -65^{\circ}\text{C}$	<u>JS-6-T1.2</u>
3.1.2	$T_j = 175^{\circ}\text{C}$	<u>JS-6-T2</u>
		$T_C = 100^{\circ}\text{C}$ , $V_{CB} = 100\text{V}$ , $I_C = 1.67\text{A}$
3.1.3	$T(\text{Lead}) = 230^{\circ}\text{C}$	Distance from case - 1/4 in., Time - 10s
3.2.0	Voltage	
3.2.1	$V_{CBO} = 200\text{V}$	<u>JS-5-T3</u> or MIL-STD-750A Method 3001.1 (See page 18)
3.2.2	$V_{EBO} = 15\text{V}$	<u>JS-6-T4</u> or MIL-STD-750A Method 3026.1 (See page 19)
3.2.3	$V_{CEX} = 180\text{V}$	<u>JS-6-T5-2.1</u> $I_C(V_{CE} = V_{CEX}) = 30\text{A}$ , $V_{CC} = 180\text{V}$ , $R_L = 6\Omega$ , $L = 1\text{mH}^*$ , CR - 1N1204, $V_{BB1} = 14\text{V}$ , $R_{BB1} = 1\Omega$ , $V_{BB2} = 8\text{V}$ , $R_{BB2} = 3\Omega$ , Duty Cycle = 1%, $t_p = 1\text{ms}$ , $R_s = 0.1\Omega$
	*Miller No. 7870	

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.3.0 Current	
3.3.1 $I_C = 30A$	<u>JS-6-T6</u> $I_b = 6A, T_C = 25^\circ C$
3.3.2 $I_B = 10A$	<u>JS-6-T8</u> $T_C = 25^\circ C$
3.3.3 $I_E = 36A$	<u>JS-6-T10</u> $I_b = 6A, T_C = 25^\circ C$
3.4.0 Power	
3.4.1 $P_T = 167W$	<u>JS-6-T12</u> $T_C = 100^\circ C, V_{CB} = 175V, I_C = .93A$ Derating Factor - $2.22W/\text{ }^\circ C$
3.4.2 $P_{TM} = I_C V_{CC} = 465W$	<u>JS-6-T13</u> $T_C = 100^\circ C, V_{CC} = 155V, V_{BB} = 8V,$ $R_{BB} = 3\Omega, I_C = 30A, \text{ Pulse Width} = 100\mu s,$ Duty Cycle = 1%, $t_r \leq 50\mu s,$ $t_f = 50\mu s$
3.5.0 Maximum Operating Conditions	
3.5.1 Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> <u>Test Point:</u> (See 3.4.1)
3.5.2 Pulsed Forward Biased SOAR	<u>JS-6-T14</u> <u>Test Points:</u> $T_C = 100^\circ C, V_{BB} = 8V, R_{BB} = 3\Omega$ $t_r \leq 50\mu s, t_f \leq 50\mu s, I_C = 30A,$ Duty Cycle $\leq 1\%, R_S = 0.1\Omega$ 1. For $t_p = 10ms: V_{CC} = 50V$ 2. For $t_p = 1ms: V_{CC} = 90$ 3. For $t_p = 500\mu s: V_{CC} = 120V$ 4. For $t_p = 100\mu s: V_{CC} = 155V$

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
3.6.0	SOAR Switching between Saturation and Cutoff	
3.6.1	Resistive Load	<u>JS-6-T5-2.1</u> with $L = 0$ and CR Disconnected
		<u>Test Points:</u>
		$R_{BB1} = 1\Omega$ , $R_{BB2} = 3\Omega$ , $V_{BB1} = 14V$ , $V_{BB2} = 8V$ , $T_C = 100^\circ C$ , $t_f \leq 50\mu s$ Coll. Current, $t_r \leq 50\mu s$ Coll. Current, $R_S = 0.1\Omega$ , $I_C = 30A$ , $V_{CC} = 200V$
3.6.2	Clamped Inductive Load	<u>JS-6-T5-2.1</u>
		<u>Test Points:</u> (See 3.2.3)
3.6.3	Unclamped Inductive Load	<u>JS-6-T5-2.1</u> and CR disconnected
		<u>Test Points:</u>
		1. $V_{BB1} = 14V$ $L = 0.2mH^*$ $R_{BB1} = 1\Omega$ $R_L = 0.4\Omega$ $V_{BB2} = 8V$ $V_{CC} = 16.5V$ $R_{BB2} = 3\Omega$ $f = 60Hz$ $R_S = 0.1\Omega$ $d = 10\%$
		2. $V_{BB1} = 7V$ $L = 1mH^{**}$ $R_{BB1} = 1\Omega$ $R_L = 2.1\Omega$ $V_{BB2} = 8V$ $V_{CC} = 10.5V$ $R_{BB2} = 3\Omega$ $f = 60Hz$ $R_S = 0.1\Omega$ $d = 10\%$

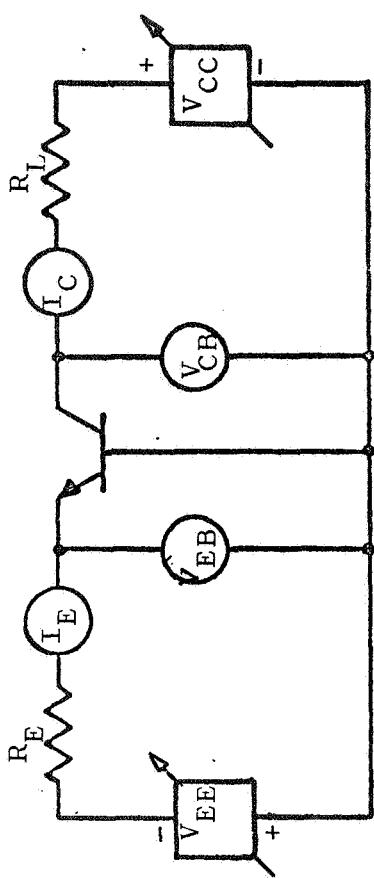
\*Miller No. 7828

\*\*Miller No. 7830 in series with 7871

<u>Item</u>		<u>Test Methods and Test Conditions</u>
3.7.0	Shorted Class B SOAR	[See Figure 6]  <u>Test Points:</u> $I_{Cpeak} = 5.4A$ , $V_{CC} = 92.5V$ , $R_S = 0.1\Omega$ $R_{BB1} = 1\Omega$ , $R_{BB2} = 3\Omega$ , $f = 20Hz$ , $T_C = 100^\circ C$
4.0.0	<u>Electrical Characterisitics</u>	$T_C = 25^\circ C$ [unless otherwise noted]
	Maximum limits unless otherwise noted	
	Technique:	
	DC - Continuous Operation	
	C.T. - Curve Tracer	
	P - 300 $\mu$ s Pulse, 2% Duty Cycle	
4.1.0	Static	
4.1.1	$I_{CEX} = 30mA$	$V_{CEX} = 200V$ , $V_{BE} = -1.5V$ , Technique - C.T., $T_C = 175^\circ C$
4.1.2	$I_{CEO} = 100mA$	$V_{CEO} = 175V$ , Technique - C.T.
4.1.3	$I_{EBO} = 25mA$	$V_{EBO} = 15V$ , $T_C = 175^\circ C$ Technique - C.T.
4.1.4	$V_{CEO} = 185V$ min	<u>JS-6-T5-2.1</u> and CR disconnected $I_C = 5A$ , $R_{BB1} = 3\Omega$ , $V_{BB1} = 3V$ , $R_{BB2} = \infty\Omega$ , $d = 50\%$ , $f = 60Hz$ , $L = 5mH$ , $R_L = 0.1\Omega$ , $R_S = 0.1\Omega$ Adjust $V_{CC}$ for specified $I_C$
4.1.5	$h_{FE} = 10$ min	$V_{CE} = 4V$ , $I_C = 20A$ Technique-C.T.
4.1.6	$V_{CE(sat)} = 1.5V$	$I_C = 20A$ , $I_B = 4A$ , Technique - C.T.
4.1.7	$V_{BE(sat)} = 2.5V$	$I_C = 20A$ , $I_B = 4A$ , Technique - C.T.

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
4.2.0	Dynamic	
4.2.1	$t_{on} = 20\mu s$	$V_{CC} = 12V, I_C = 20A, I_{B1} = 5A$
4.2.2	$t_{off} = 25\mu s$	$V_{CC} = 12V, I_C = 20A, I_{B2} = 5A$
4.2.3	$f_{hfe} = 8KHz \text{ min}$ $32KHz \text{ max}$	$I_C = 5A, V_{CE} = 12V$
5.0.0	<u>Thermal Characteristics</u>	
5.1.0	$T_{jmin} = 45ms$	$I_C = 2A, V_{CE} = 10V, T_C = 25^\circ C$ MIL-STD-750, Method 3146.1
5.2.0	$\theta_{JC} = 0.45^\circ C/W$	$I_C = 2A, V_{CB} = 10V$ MIL-STD-750A, Method 3136

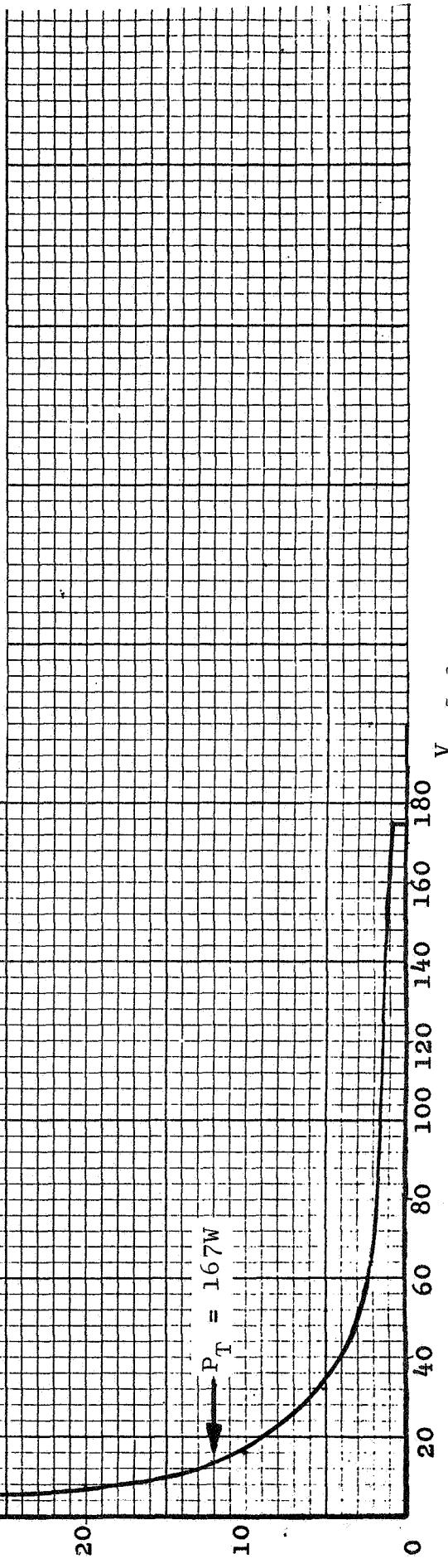
FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CEO}$

Test Circuit: JS-6-T12

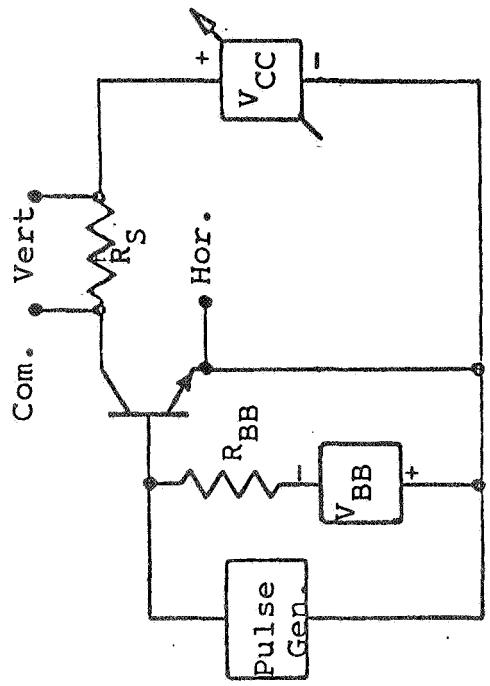
86.  
I<sub>C</sub>[A]



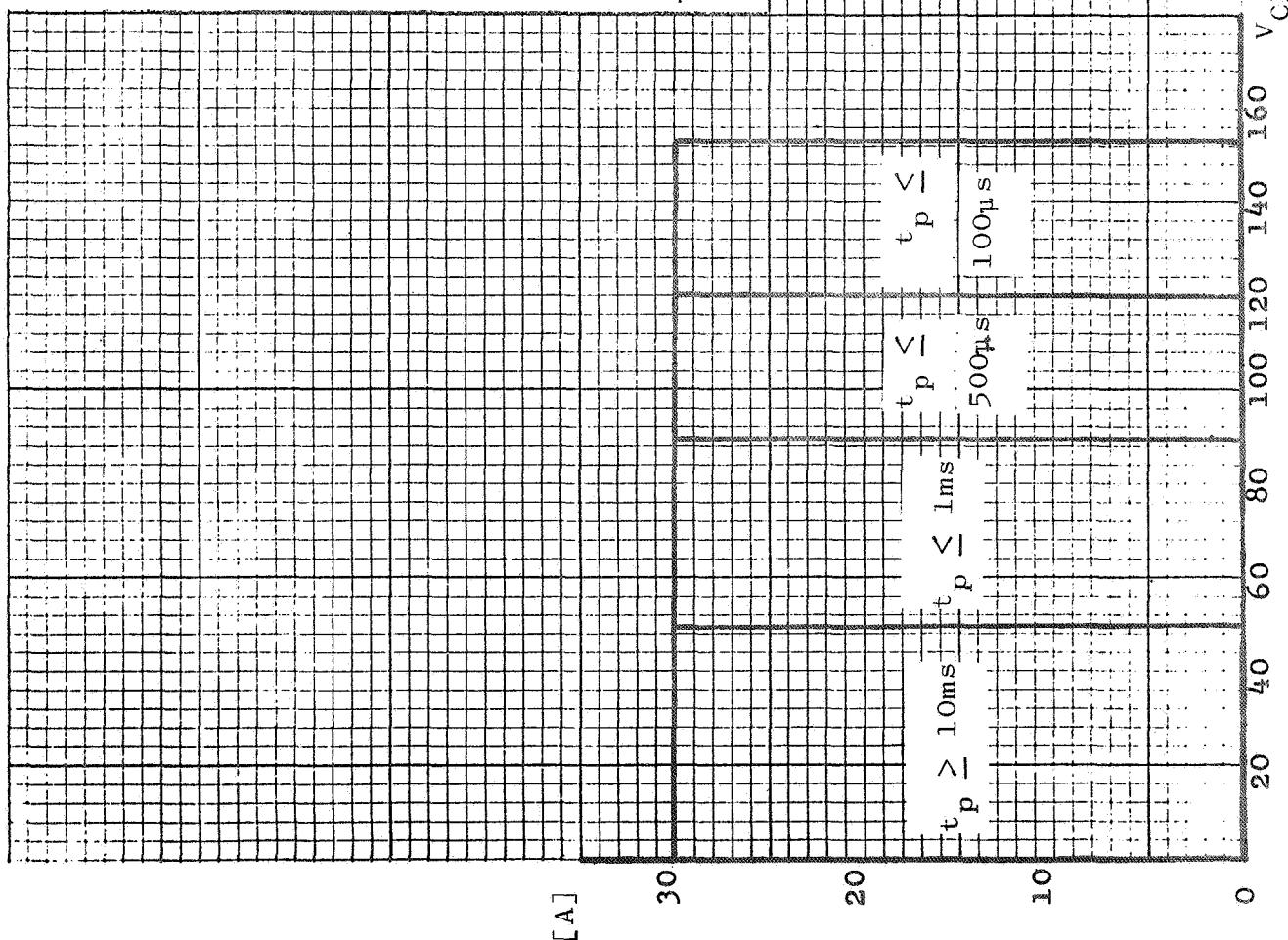
V<sub>CE</sub>[V]

Figure 1

PULSED FORWARD BIASED SOAR



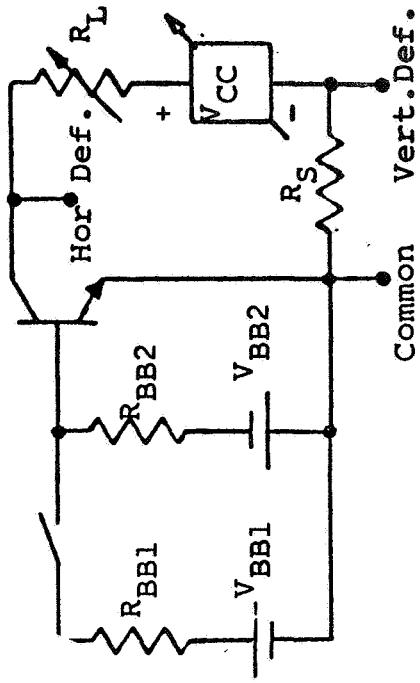
Test Circuit: JS-6-T14



87.

Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

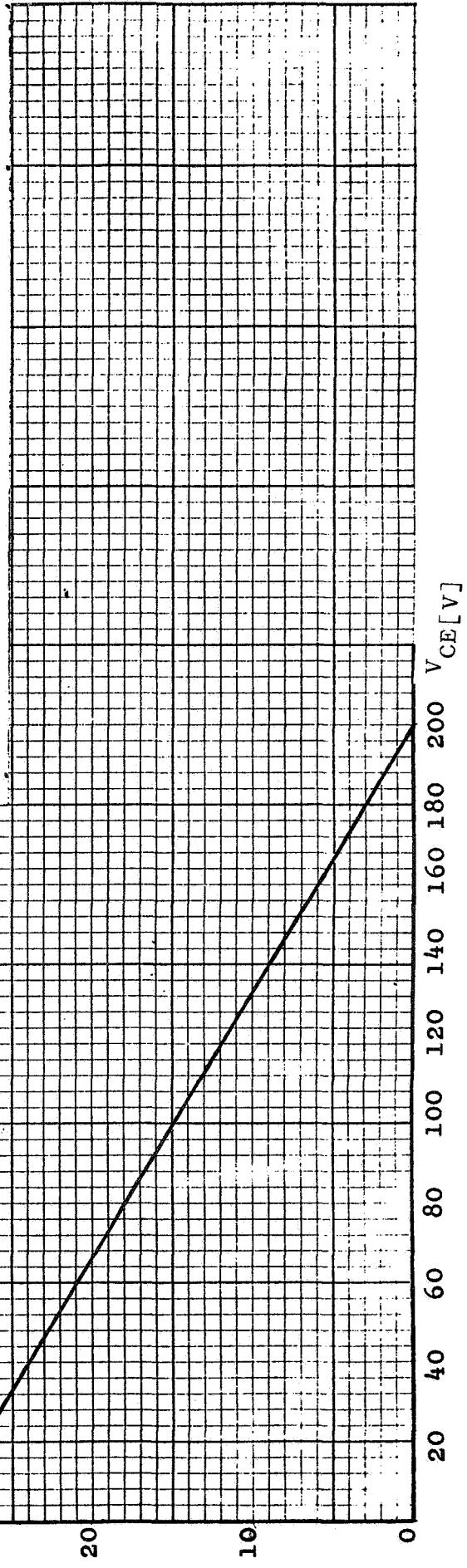
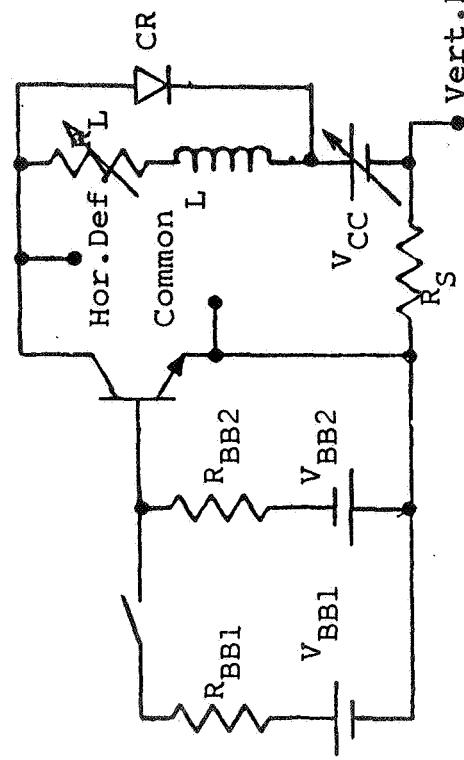
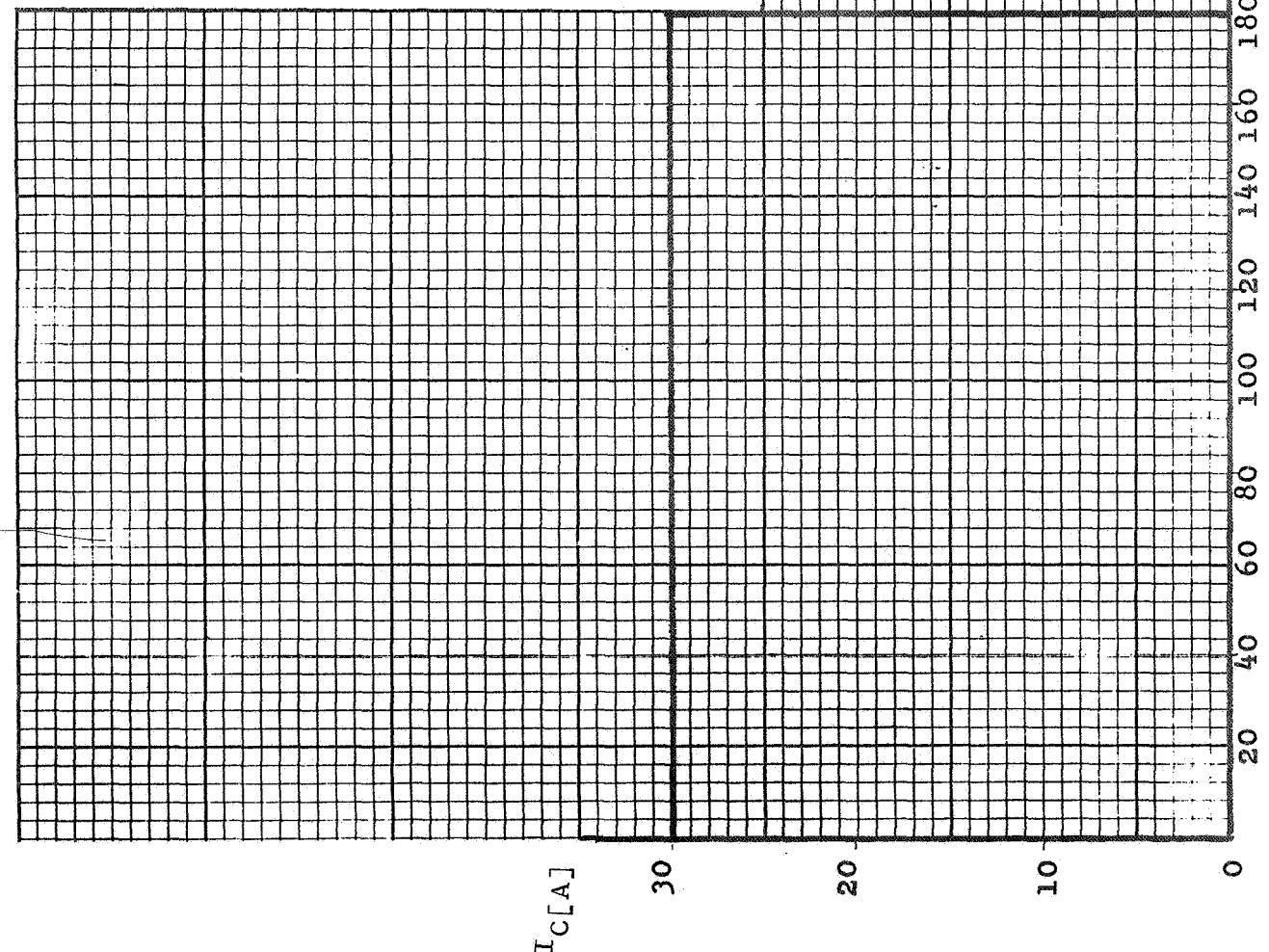


Figure 3

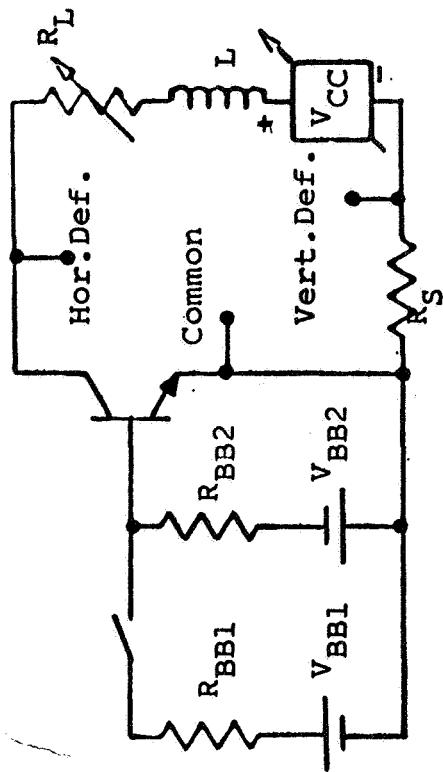
SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-CLAMPED INDUCTIVE LOAD



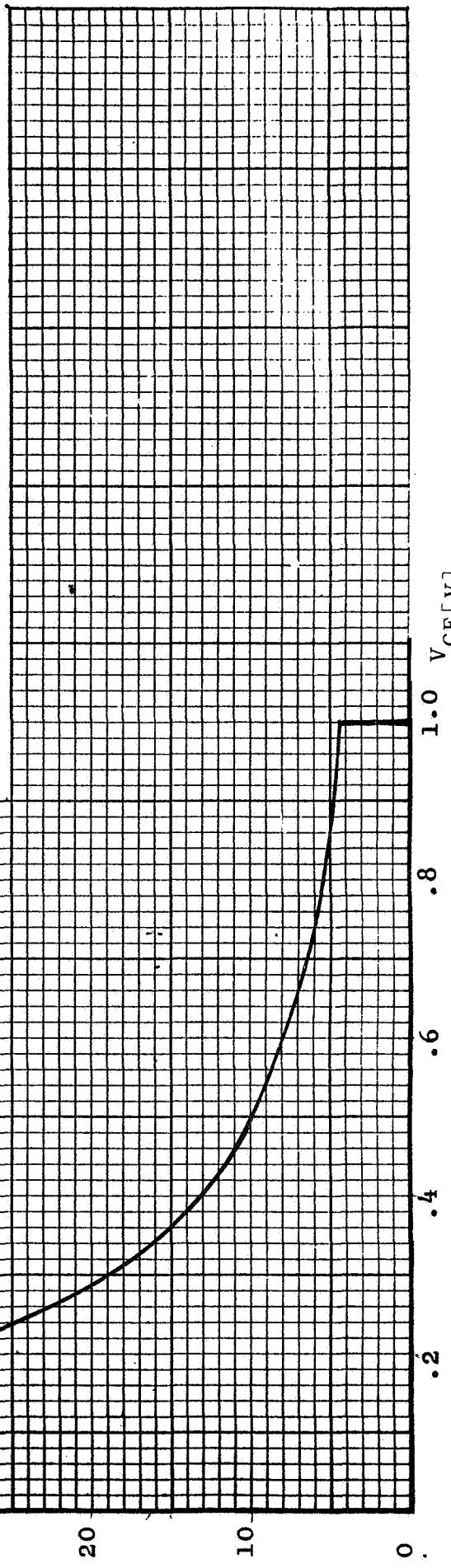
Test Circuit: JS-6-T5-2.1



SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF - UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1



I<sub>C</sub> [A]

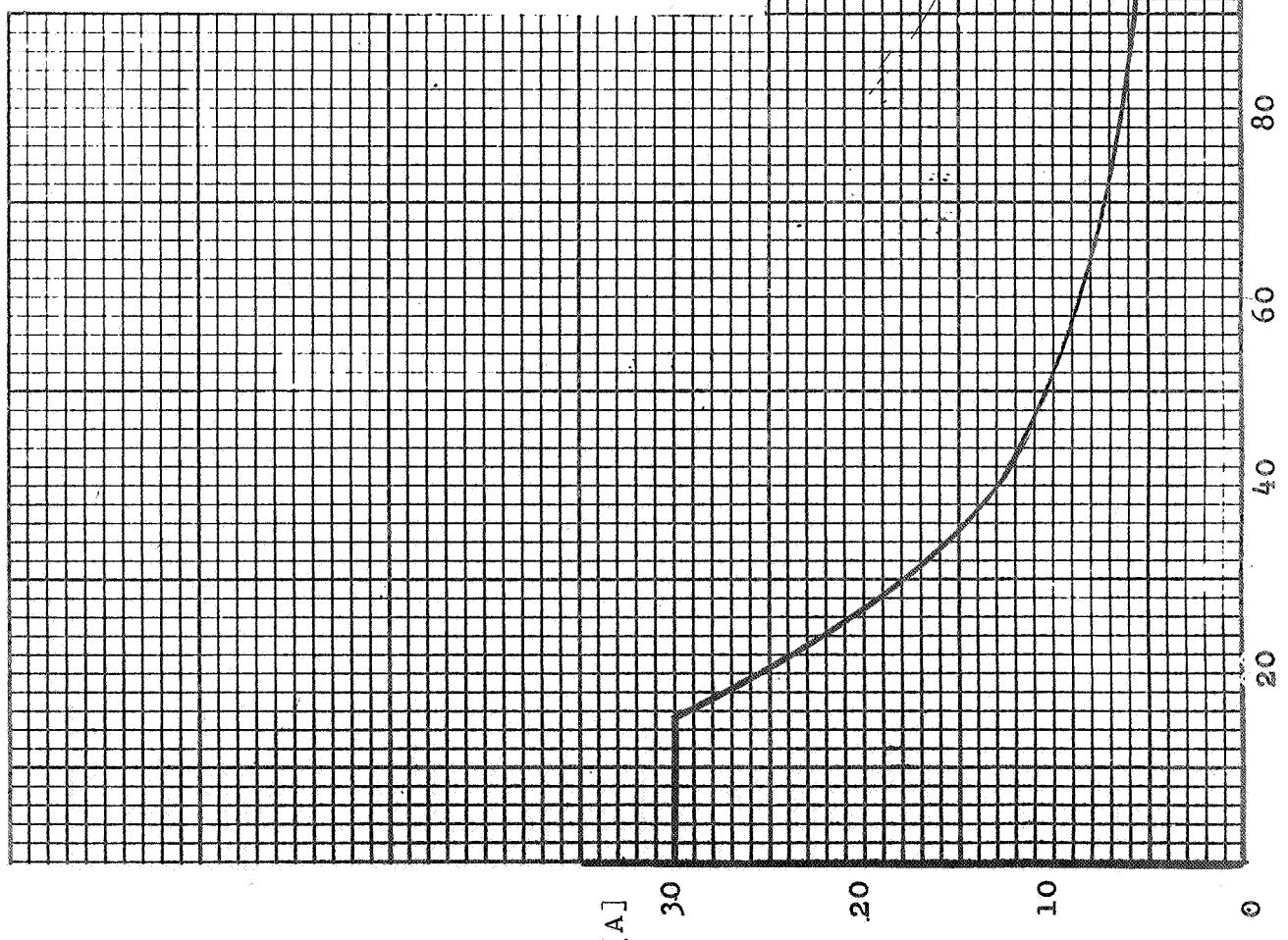
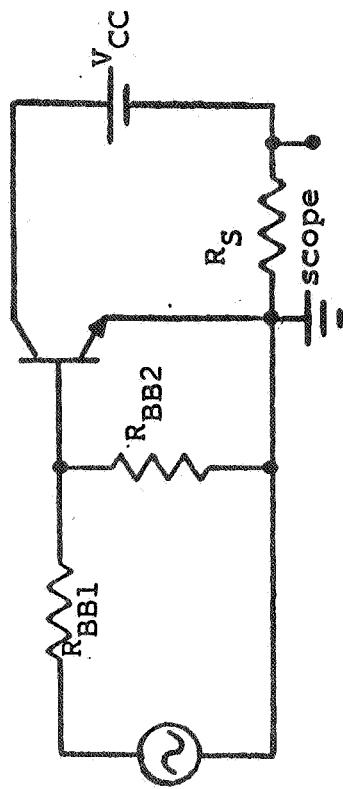
30

20

10

0

SHORTED CLASS B SOAR



$I_C$  [A]

91.

Figure 6

SILICON POWER TRANSISTOR

< Type 2N657A >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer E --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Method and Test Conditions</u>	
1.0.0	<u>General Description</u>	
1.1.0	Type - NPN	
1.2.0	Material - Silicon	
2.0.0	<u>Mechanical Data</u>	
2.1.0	Outline - TO-5	
2.2.0	Terminal Designation 1 - Emitter 2 - Base 3 - Collector case - Collector	
3.0.0	<u>Maximum Ratings</u>	
3.1.0	Temperature	
3.1.1	$T_{STG(max)} = 200^{\circ}\text{C}$	<u>JS-6-T1.2</u> [ JEDEC publication No. 65 "Test Procedures for Verification of Maximum Ratings of Power Transistors"]
	$T_{STG(min)} = 200^{\circ}\text{C}$	
3.1.2	$T_J(max) = 200^{\circ}\text{C}$	<u>JS-6-T2</u> $T_C = 100^{\circ}\text{C}$ , $V_{CB} = 100\text{V}$ , $I_C = 28.6\text{mA}$
3.1.3	$T(\text{Lead}) = 260^{\circ}\text{C}$	Distance from case = 1/16 in. Time = 10s
3.2.0	Voltage	$T_C = 25^{\circ}\text{C}$
3.2.1	$V_{CBO} = 100\text{V}$	<u>JS-6-T3</u> or MIL-STD-750A, method 3001.1
3.2.2	$V_{EBO} = 8\text{V}$	<u>JS-6-T4</u> of MIL-STD-750A, method 3026.1
3.2.3	$V_{CEX} = 100\text{V}$	<u>JS-6-T5</u> $I_C (V_{CE} = V_{CEX}) = 0.5\text{A}$ , $V_{CC} = 100\text{V}$ , $R_L = 190\Omega$

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.2.3 $V_{CEX}$ [cont'd]	$L = 10mH; 0.11\Omega$ (Stancor C-2688), $CR = 1N1204, V_{BB1} = 10.1V, R_{BB1} = 33\Omega$ $V_{BB2} = 6.5V, R_{BB2} = 100\Omega, t_p = 1ms,$ $R_S = 1\Omega, \text{ Duty Cycle} = \leq 1\%$
3.3.0      Current	
3.3.1 $I_C = 500mA$	<u>JS-6-T6</u> $I_B = 50mA, T_C = 25^\circ C$
3.2.2 $I_B = 250mA$	<u>JS-6-T8</u> $T_C = 25^\circ C$
3.3.3 $I_E = 550mA$	<u>JS-6-T10</u> $I_B = 50mA, T_C = 25^\circ C$
3.4.0      Power	
3.4.1 $P_T = 2.86W$	<u>JS-6-T13</u> $T_C = 100^\circ C, V_{CC} = 100V, I_C = 0.5A$ $V_{BB} = 6.5V, R_{BB} = 100\Omega, \text{ Pulse Width } 0.5ms$ Duty Cycle $\leq 1\%$ , $t_r \leq 50\mu s, t_f \leq 50\mu s$
3.5.0      Maximum Operating Conditions	
3.5.1      Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> [See Figure 1] $T_C = 100^\circ C$ <u>Test Points:</u> [See 3.1.2]

<u>Item</u>		<u>Test Methods and Test Conditions</u>
3.5.2	Pulsed Forward Biased SOAR	<p><u>JS-6-T1.4</u> [See Figure 2]</p> <p><math>T_C = 100^\circ C</math>, <math>I_C = 0.5A</math>, <math>R_S = 0.1\Omega</math></p> <p><math>V_{BB} = 6.5V</math>, <math>R_{BB} = 100\Omega</math>, <math>t_r \leq 50\mu s</math>,</p> <p><math>t_f \leq 50\mu s</math>, Duty Cycle <math>\leq 1\%</math></p> <p><u>Test Points:</u></p> <ol style="list-style-type: none"> <li>1. For <math>t_p \leq 5ms</math>, <math>V_{CC} = 35V</math></li> <li>2. For <math>t_p \leq 2ms</math>, <math>V_{CC} = 50V</math></li> <li>3. For <math>t_p \leq 1ms</math>, <math>V_{CC} = 65V</math></li> <li>4. For <math>t_p \leq 0.5ms</math>, <math>V_{CC} = 100V</math></li> </ol>
3.6.0	SOAR Switching between Saturation and Cutoff	
3.6.1	Resistive Load	<p><u>JS-6-T2.1</u> with L - 0 and CR disconnected [See Figure 3]</p> <p><math>T_C = 100^\circ C</math></p> <p><u>Test Points:</u></p> <p><math>t_r \leq 50\mu s</math>, <math>t_f \leq 50\mu s</math>, <math>I_C = 0.5A</math>,</p> <p><math>V_{CC} = 100V</math>, <math>R_S = 0.1\Omega</math>, <math>R_{BB1} = 33\Omega</math></p> <p><math>R_{BB2} = 100\Omega</math>, <math>V_{BB1} = 10.1V</math>, <math>V_{BB2} = 6.5V</math></p>
3.6.2	Clamped Inductive Load	<p><u>JS-6-T5-2.1</u> [See Figure 4]</p> <p><math>T_C = 25^\circ C</math></p> <p><u>Test Points:</u> [See 3.2.3]</p>
3.6.3	Unclamped Inductive Load	<p><u>JS-6-T5-2.1</u> and CR disconnected [See Figure 5]</p> <p><math>T_C = 25^\circ C</math></p>

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.6.3      Unclamped Inductive Load [cont'd]	$f = 1\text{Hz}$ , Duty Cycle $\leq 5\%$ , $R_S = 0.1\Omega$ $R_{BB1} = 33\Omega$ , $R_{BB2} = 100\Omega$ , $V_{BB1} = 10.1V$ , $V_{BB2} = 6.5V$ 1. $L = 50\text{mH}$ ; $0.424\Omega$ [series 2-Stancor C-2686], $I_C = 0.5A$ , $V_{CC} = 9V$ , $R_L = 9\Omega$ 2. $I_C = 0.15A$ , $V_{CC} = 8V$ , $R_L = 34\Omega$ $L = 600\text{mH}$ ; $6\Omega$ [series 2-TRIAD C-47U]
3.7.0      Shorted Class B SOAR	[See Figure 6]  <u>Test Points:</u> $I_{Cpeak} = 50\text{mA}$ , $V_{CC} = 80V$ , $R_S = 1\Omega$ $R_{BB1} = 10\Omega$ , $R_{BB2} = 5\Omega$ , $f \geq 20\text{Hz}$ , $T_C = 100^\circ\text{C}$
4.0.0 <u>Electrical Characteristics</u>	$T_C = 25^\circ\text{C}$ [unless otherwise noted]

Maximum Limits unless otherwise noted

Technique:

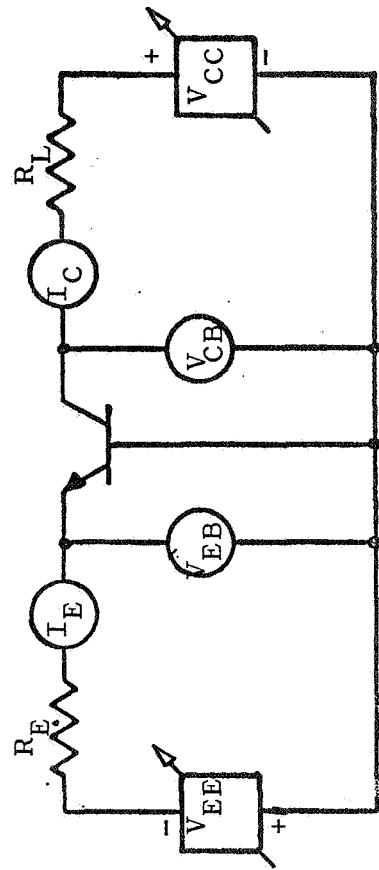
DC - Continuous Operation

C.T. - Curve Tracer

P -  $300\mu\text{s}$  Pulse,  
2% Duty Cycle

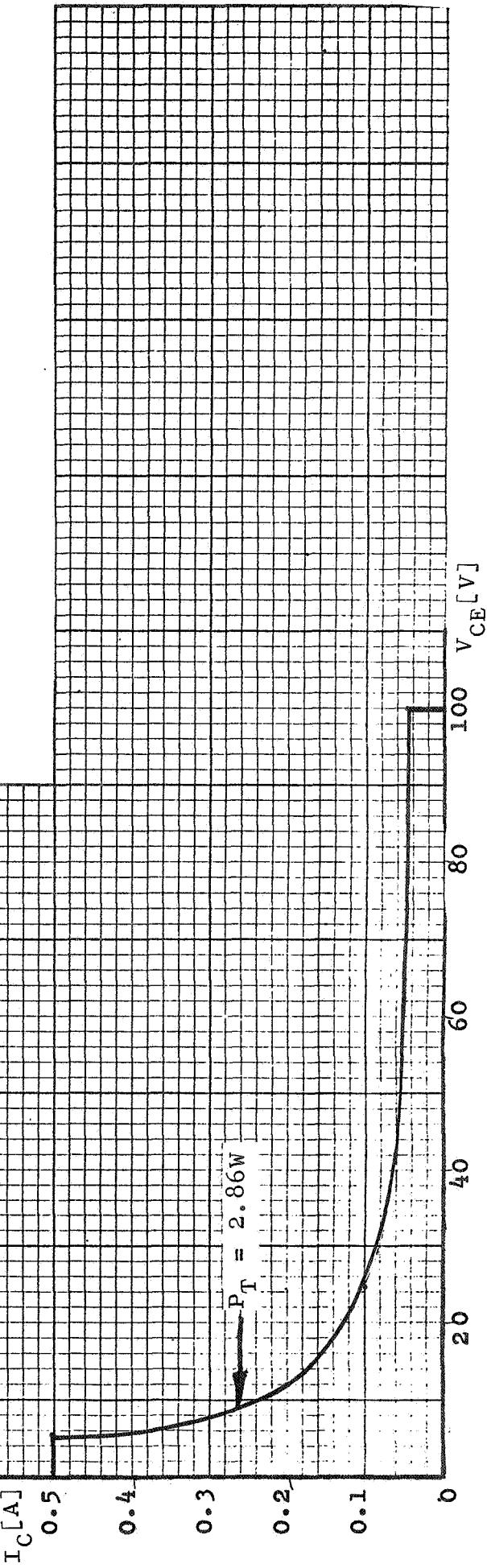
<u>Item</u>	<u>Test Methods and Test Conditions</u>	
4.1.0	Static	
4.1.1	$I_{CEO} = 100\mu A$	$V_{CEO} = 100V$ , Technique - C.T.
4.1.2	$I_{CBO} = 10\mu A$	$V_{CBO} = 30V$ , Technique - C.T.
4.1.3	$I_{CBO} = 250\mu A$	$V_{CBO} = 30V$ , $T_C = 150^\circ C$ Technique - C.T.
4.1.4	$V_{(BR)CEO} = 100V$	$I_C = 10mA$ , Technique - C.T.
4.1.5	$V_{CBO} = 100V$	$I_C = 100\mu A$ , Technique - C.T.
4.1.6	$V_{EBO} = 8V$	$I_E = 250\mu A$ , Technique - C.T.
4.1.7	$h_{FE} = 30 \text{ min}$  $90 \text{ max}$	$V_{CE} = 10V$ , $I_C = 200mA$ Technique = C.T.
4.1.8	$h_{FE} = 20 \text{ min}$	$V_{CE} = 10V$ , $I_C = 0.5A$ , Technique - P
4.1.9	$V_{CE(sat)} = 2V$	$I_C = 200mA$ , $I_B = 40mA$ , Technique = C.T.
4.1.10	$V_{CE(sat)} = 4V$	$I_C = 0.5A$ , $I_B = 0.1A$ , Technique - C.T.
4.1.11	$V_{BE(sat)} = 3.5V$	$I_C = 0.5A$ , $I_B = 0.1A$ , Technique - C.T.
4.1.12	$h_{IE} = 200\text{ohms}$	$V_{CE} = 10V$ , $I_B = 8mA$ , Technique - P
4.2.0	Dynamic	
4.2.1	$f_{hfe} = 50\text{KHz(min)}$  $200\text{KHz(max)}$	$I_C = 50mA$ , $V_{CE} = 10V$
5.0.0	Thermal Characteristics	
5.1.0	$\tau_J(\text{min}) = 250\text{ms}$	$I_C = 0.2A$ , $V_{CE} = 5V$ , $T_C = 25^\circ C$ , MIL-STD-750 Method 3146.1
5.2.0	$\theta_{J-C(\text{max})} = 35^\circ C/W$	$I_C = 0.2A$ , $V_{CE} = 5V$ , $T_C = 25^\circ C$ , MIL-STD-750 Method 3136

FORWARD BIASED CONTINUOUS SOAR

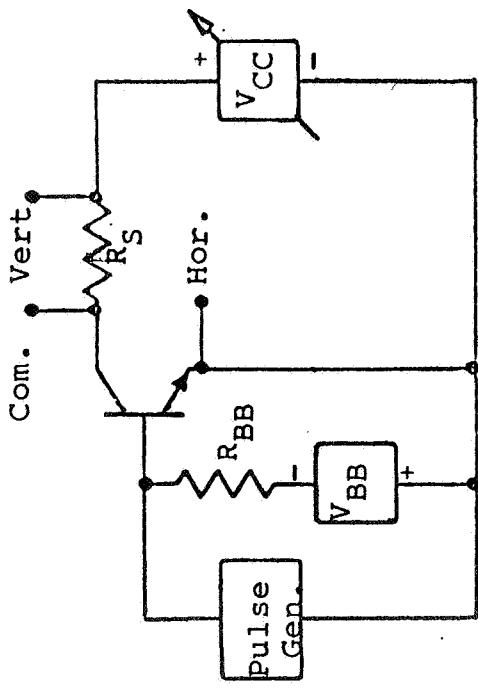


Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CEO}$

Test Circuit: JS-6-T12



PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

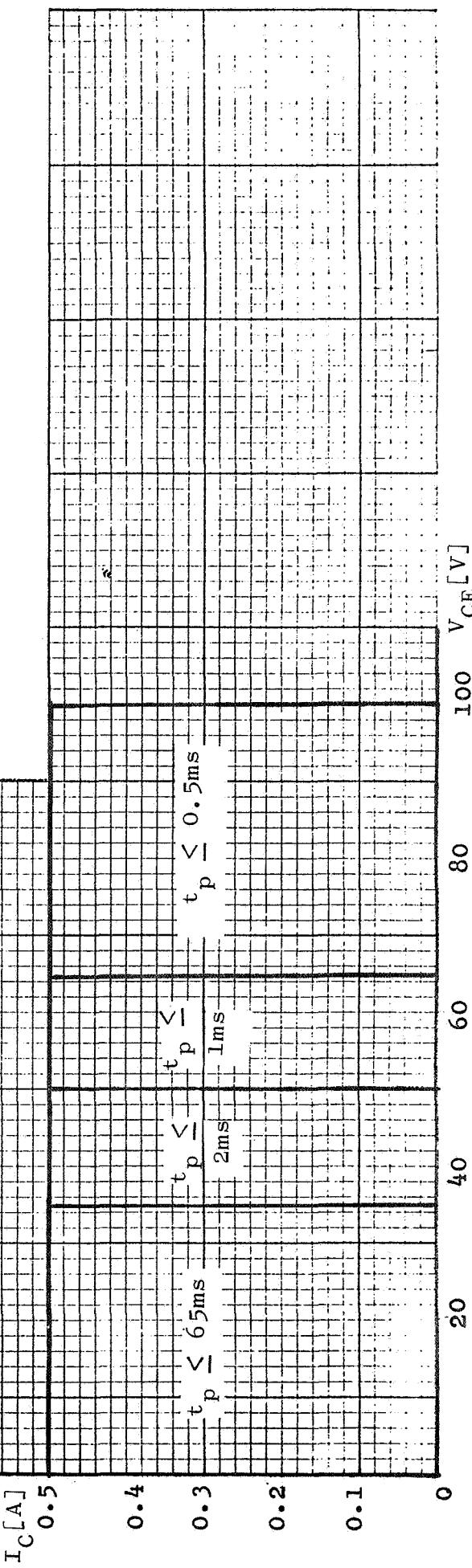
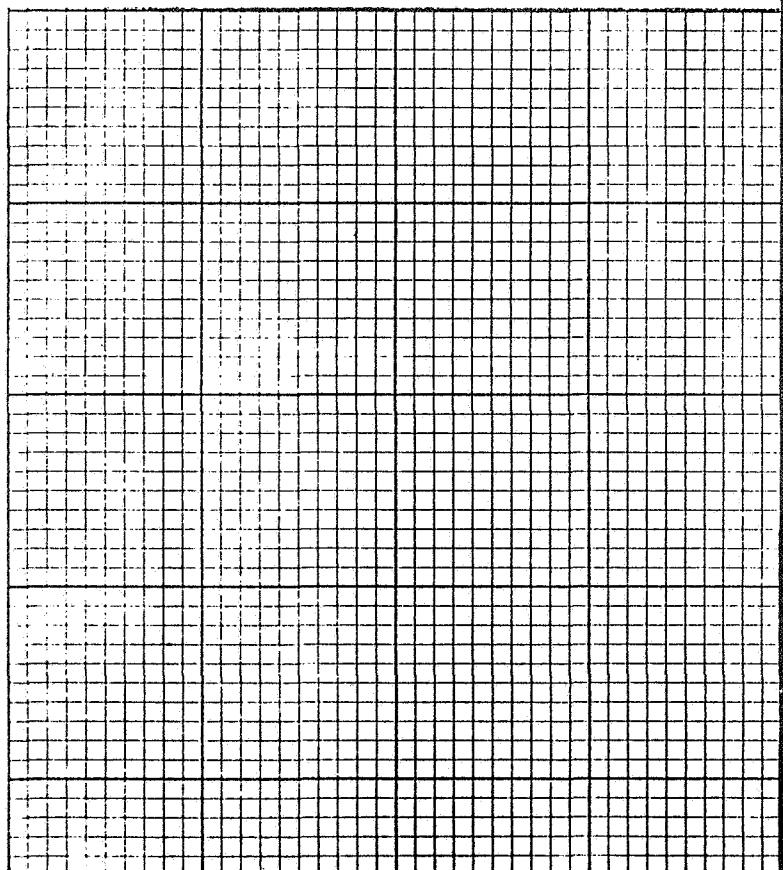
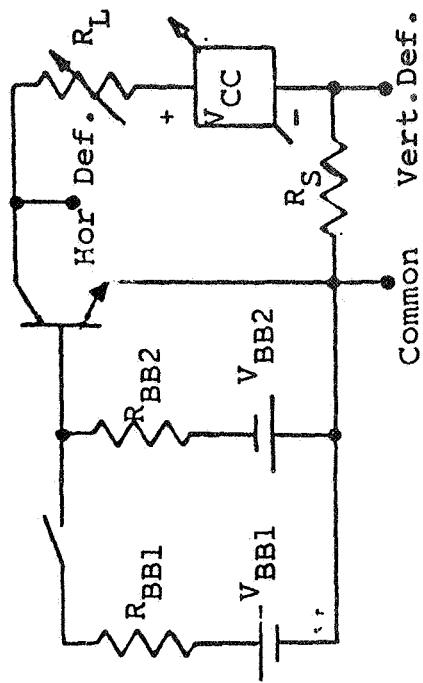


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

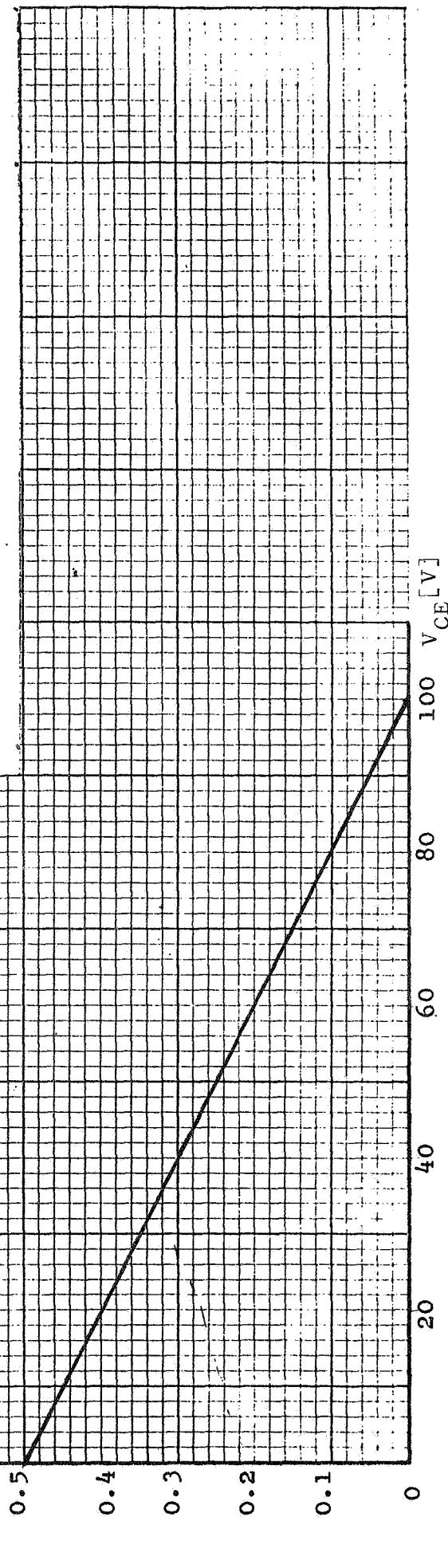


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-CLAMPED INDUCTIVE LOAD

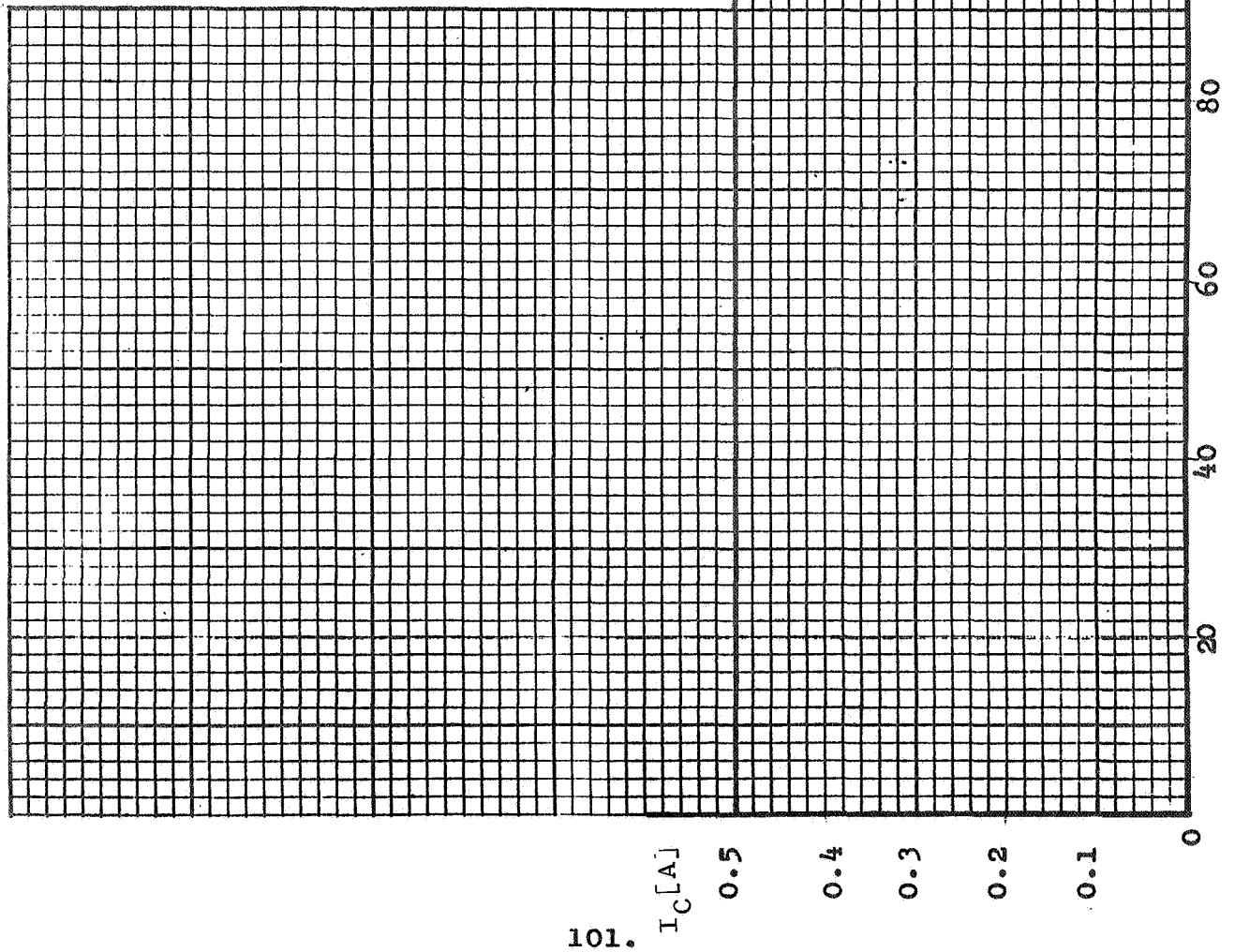
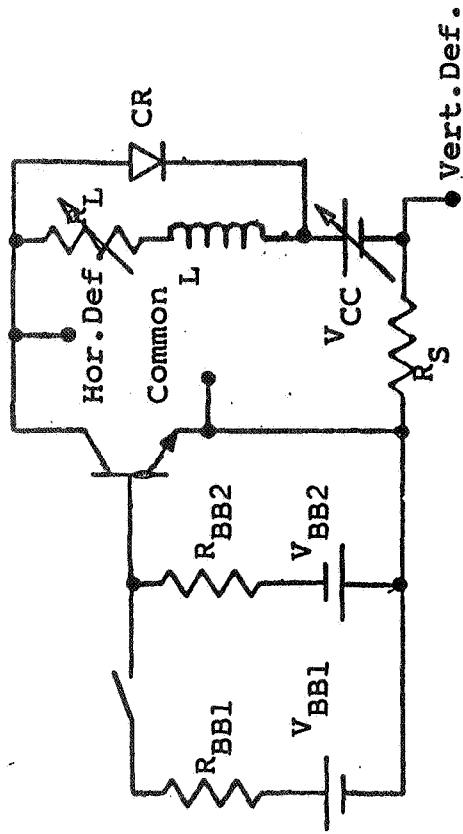
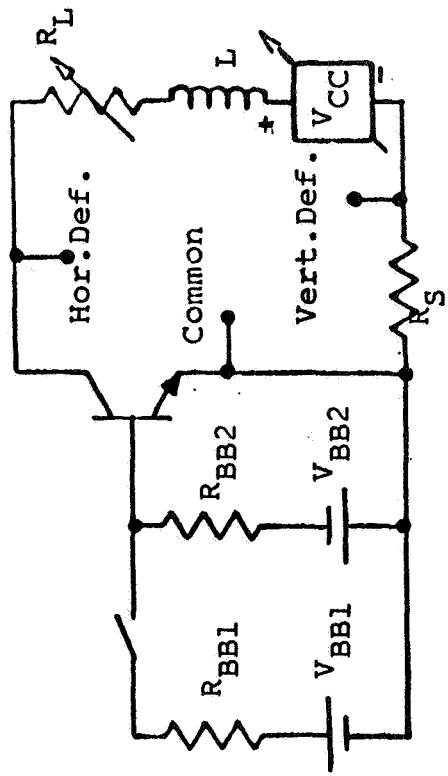
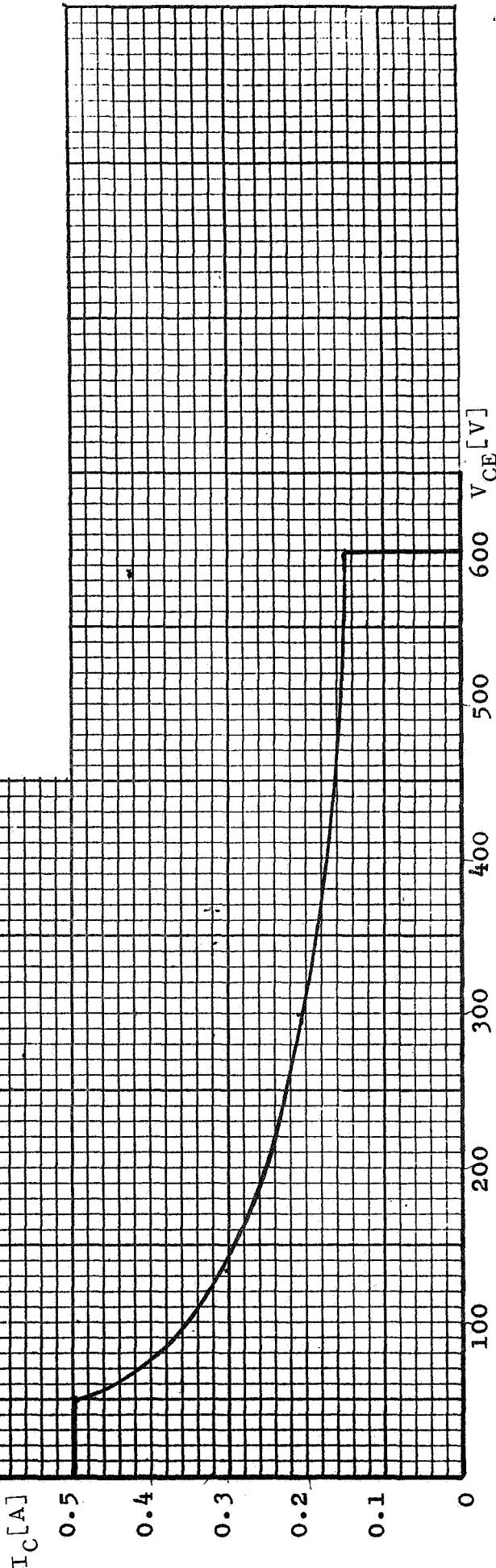


Figure 4

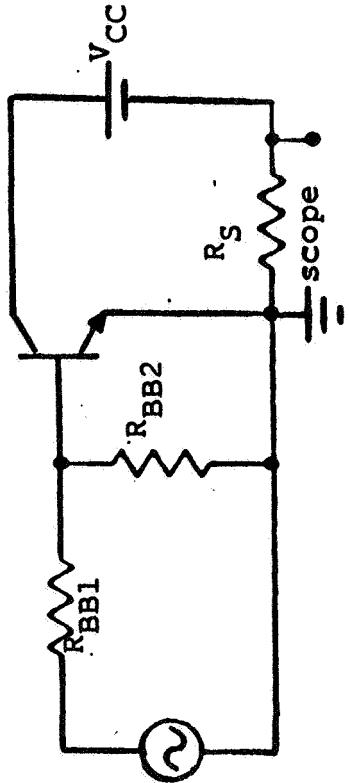
SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF- UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1



SHORTED CLASS B SOAR



103.

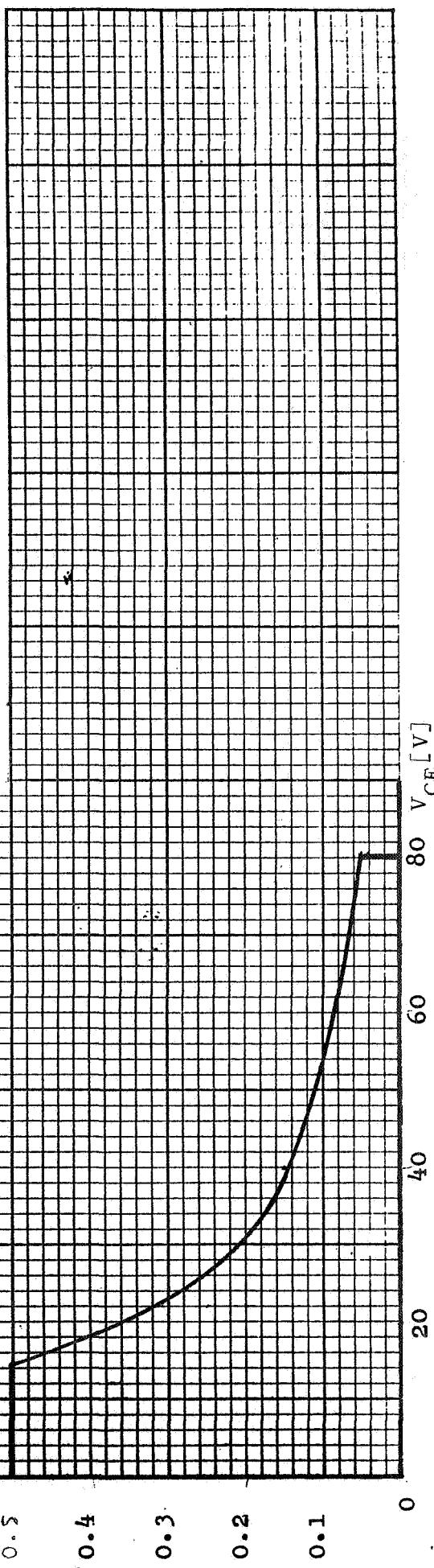


Figure 6

SILICON POWER TRANSISTOR

< Type 2N697 >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturers E & G --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Methods and Test Conditions</u>
1.0.0 <u>General Description</u>	
1.1.0      Type - NPN	
1.2.0      Material - Silicon	
2.0.0 <u>Mechanical Data</u>	
2.1.0      Outline - TO-5	
2.2.0      Terminal Designation	
1 --- Emitter	
2 --- Base	
3 --- Collector	
case --- Collector	
3.0.0 <u>Maximum Ratings</u>	
3.1.0      Temperature	
3.1.1 $T_{STG(min)} = -65^{\circ}\text{C}$	<u>JS-6-T1.1</u> [ JEDEC Publication No. 65 "Test Procedures for
$T_{STG(max)} = 300^{\circ}\text{C}$	<u>JS-6-T1.2</u> Verification of Maximum Ratings of Power Transistors"]
3.1.2 $T_J = 175^{\circ}\text{C}$	<u>JS-6-T2</u>
	$T_C = 100^{\circ}\text{C}$ , $V_{CB} = 40\text{V}$ , $I_C = 0.025\text{A}$
3.1.3 $T(\text{Lead}) = 260^{\circ}\text{C}$	Distance from case = 1/16 in Time 10s
3.2.0      Voltage	$T_C = 25^{\circ}\text{C}$
3.2.1 $V_{CBO} = 60\text{V}$	<u>JS-6-T3</u> or MIL-STD-750A, Method 3001.1
3.2.2 $V_{EBO} = 5\text{V}$	<u>JS-6-T4</u> or MIL-STD-750A, Method 3026.1
3.2.3 $V_{CEX} = 40\text{V}$	<u>JS-6-T5</u> $I_C(V_{CC} = V_{CEX}) = 0.5\text{A}$ , $V_{CC} = 40\text{V}$ , $R_L = 72\Omega$

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
3.2.3 $V_{CEX}$ [cont'd]		$L = 10\text{mH} / 0.11\Omega$ , [Stancor C-2699] $CR = 1N120^4$ , $V_{BB1} = 8.5V$ , $R_{BB1} = 30\Omega$ $V_{BB2} = 4V$ , $R_{BB2} = 65\Omega$ , Duty Cycle = $\leq 1\%$
3.3.0      Current		
3.3.1 $I_C = 0.5A$	<u>JS-6-T6</u>	$I_B = 0.05A$ , $T_C = 25^\circ\text{C}$
3.3.2 $I_B = 0.1A$	<u>JS-6-T8</u>	$T_C = 25^\circ\text{C}$
3.3.3 $I_E = 0.55A$	<u>JS-6-T10</u>	$I_B = 0.05A$ , $T_C = 25^\circ\text{C}$
3.4.0      Power		
3.4.1 $P_T = 1W$	<u>JS-6-T12</u>	$T_C = 100^\circ\text{C}$ , $V_{CB} = 40V$ , $I_C = 0.025A$ Derating Factor = $13.3\text{mW}/^\circ\text{C}$
3.4.2 $P_{TM} = 20W$	<u>JS-6-T13</u>	$T_C = 100^\circ\text{C}$ , $V_{CC} = 40V$ , $I_C = 0.5A$ , $V_{BB} = 4V$ , $R_{BB} = 65\Omega$ , Pulse Width = $0.1\text{m}$ Duty Cycle $\leq 1\%$ , $t_r \leq 50\mu\text{s}$ , $t_f \leq 50\mu\text{s}$
3.5.0      Maximum Operating Conditions		
3.5.1      Forward Biased Continuous DC SQAR	<u>JS-6-T12</u>	[See Figure 1]

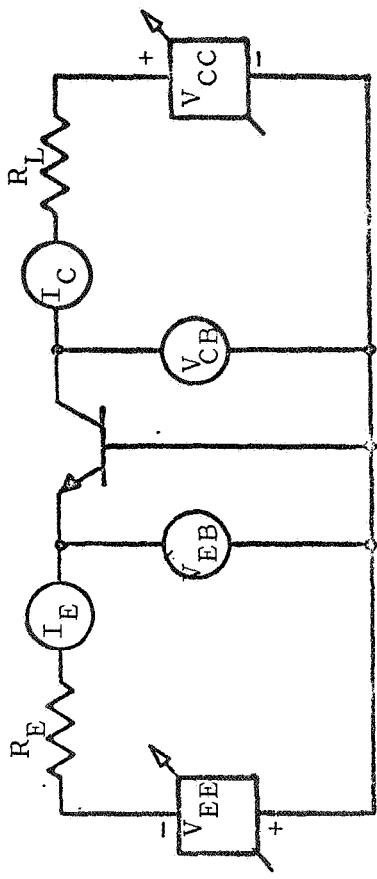
<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.5.1      Forward Biased Continuous DC SOAR [cont'd]	$T_C = 100^\circ C$ <u>Test Point:</u> [See 3.4.1]
3.5.2      Pulsed Forward Biased SOAR	<u>JS-6-T14</u> [See Figure 2] <u>Test Point:</u> $T_C = 100^\circ C, I_C = 0.5A, R_S = 1\Omega$ $V_{BB} = 4V, R_{BB} = 65\Omega, t_r \leq 50\mu s,$ $t_f \leq 50\mu s, \text{ Duty Cycle} \leq 1\%$ 1. For $t_p = 10ms; V_{CC} = 10V$ 2. For $t_p = 1ms; V_{CC} = 18V$ 3. For $t_p = 0.5ms; V_{CC} = 30V$ 4. For $t_p = 0.1ms; V_{CC} = 40V$
3.6.0      SOAR Switching between Saturation and Cutoff	
3.6.1      Resistive Load	<u>JS-6-T5-2.1</u> with L - 0 and CR disconnected [See Figure 3] $T_C = 100^\circ C$ <u>Test Point:</u> $V_{CC} = 60V, I_C = 0.5A, t_r \leq 50\mu s,$ $t_f \leq 50\mu s, R_{BB1} = 30\Omega, R_{BB2} = 65\Omega,$ $V_{BB1} = 8.5V, V_{BB2} = 4V$
3.6.2      Clamped Inductive Load	<u>JS-6-T5-2.1</u> [See Figure 4] $T_C = 25^\circ C$ <u>Test Point:</u> [See 3.2.3]

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.6.3      Unclamped Inductive Load	<p><u>JS-6-T5-2.1</u> and CR disconnected [See Figure 5]</p> <p><math>T_C = 25^\circ C</math></p> <p><u>Test Point:</u></p> <p><math>f = 60Hz</math>, Duty Cycle <math>\leq 1\%</math>  <math>R_S = 1\Omega</math>, <math>t_r \leq 50\mu s</math>, <math>t_f \leq 50\mu s</math></p> <p>1. <math>R_{BB1} = 30\Omega</math>, <math>R_{BB2} = 65\Omega</math>,  <math>V_{BB1} = 8.5V</math>, <math>V_{BB2} = 4V</math>,  <math>L = 10mH / 0.11\Omega</math>, (Stancor C-2688)</p> <p>2. <math>R_{BB1} = 120\Omega</math>, <math>R_{BB2} = 150\Omega</math>,  <math>V_{BB1} = 5V</math>, <math>V_{BB2} = 2V</math>, <math>I_C = 0.1A</math>,  <math>V_{CC} = 14V</math>, <math>R_L = 125\Omega</math>, <math>L = 100mH / 1.175\Omega</math>, (Series Stancor C-2688 and TRIAD C-47u)</p>
3.7.0      Shorted Class B SOAR	[See Figure 6]
4.0.0 <u>Electrical Characteristics</u>	<p><u>Test Points:</u></p> <p><math>I_C</math> peak = <math>0.05A</math>, <math>V_{CC} = 40V</math>,  <math>R_S = 10\Omega</math>, <math>R_{BB1} = 10\Omega</math>; <math>R_{BB2} = 27\Omega</math>;  <math>f = 20Hz</math>, <math>T_C = 100^\circ C</math></p> <p><math>T_C = 25^\circ C</math> [unless otherwise noted]</p> <p>Maximum Limits unless otherwise noted</p>

<u>Item</u>	<u>Test Methods and Test Conditions</u>	
4.0.0	<u>Electrical Characteristics</u> [Cont'd]	
	Technique:	
	DC - Continuous Operation	
	C.T. - Curve Tracer	
	P - 300 $\mu$ s Pulse, 2% Duty Cycle	
4.1.0	Static	
4.1.1	$I_{CEO} = 10\mu A$	$V_{CEO} = 40V$ Technique - C.T.
4.1.2	$I_{CBO} = 1\mu A$	$V_{CBO} = 30V$ Technique - C.T.
4.1.3	$I_{CBO} = 100\mu A$	$V_{CBO} = 30V, T_C = 150^{\circ}C$ , Technique-C.T.
4.1.4	$V_{CBO} = 60V$	$I_C = 100\mu A$ Technique - C.T.
4.1.5	$V_{CER} = 40 V$	$I_C = 100\mu A, R_B \leq 10\Omega$ Technique-C.T.
4.1.6	$V_{EBO} = 5V$	$I_E = 100\mu A$ Technique - C.T.
4.1.7	$V_{(BR)CEO} = 30V$ min	$I_C = 0.05A$ Technique - C.T.
4.1.8	$h_{FE} = 40$ min 120 max	$V_{CE} = 10V, I_C = 0.15A$ Technique - P
4.1.9	$h_{FE} = 25$ min	$V_{CE} = 10V, I_C = 0.5A$ Technique - P
4.1.10	$V_{CE(sat)} = 1.5V$	$I_C = 0.15A, I_B = 0.015A$ , Technique - C.T.
4.1.11	$V_{CE(sat)} = 4V$	$I_C = 0.5A, I_B = 0.1A$ Technique - P
4.1.12	$V_{BE(sat)} = 1.3V$	$I_C = 0.15A, I_B = 0.015A$ Technique - C.T.
4.1.13	$V_{BE(sat)} = 2.5V$	$I_C = 0.5A, I_B = 0.1A$ Technique - P
4.2.0	Dynamic	

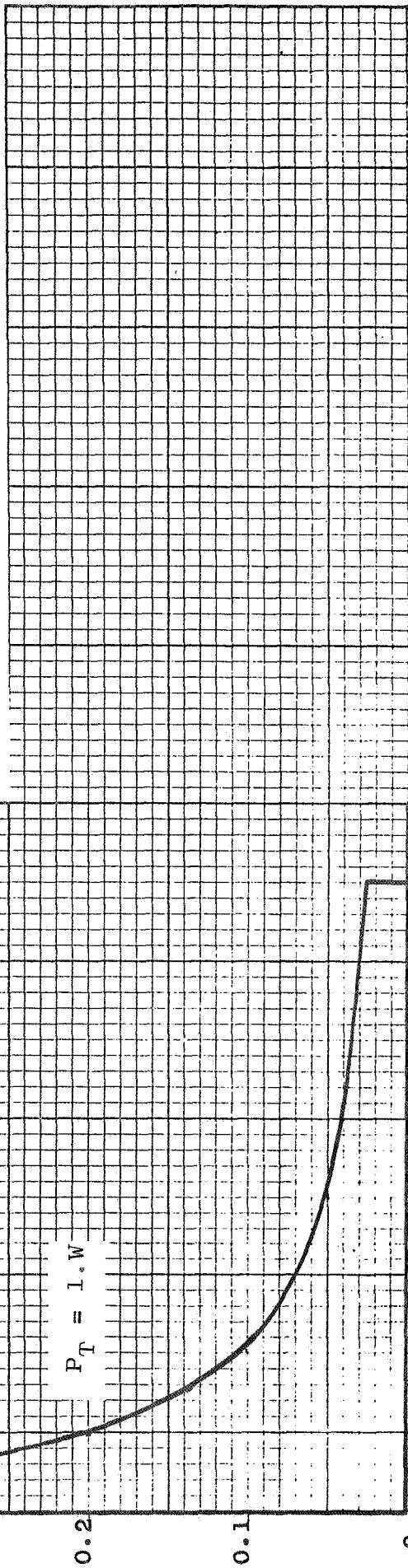
<u>Item</u>		<u>Test Methods and Test Conditions</u>
4.2.1	$f_T = 50\text{MHz min}$ $160\text{MHz max}$	$I_C = 0.05A, V_{CE} = 10V$ $f = 20\text{MHz}$
4.2.2	$C_{obo} = 35\text{pF}$	$V_{CB} = 10V, f = 1\text{MHz}$
5.0.0	Thermal Characteristics	
5.1.0	$J(\text{min}) = 70\text{ms}$	$I_C = 0.4A, V_{CE} = 5V, \text{ MIL-STD-750}$ Method 3146.1
5.2.0	$\theta_{J-C(\text{max})} = 75^\circ\text{C/W}$	$I_C = 0.4A, V_{CE} = 5V, T_C = 20^\circ\text{C}$ MIL-STD-750 Method 3136
5.3.0	$\theta_{J-A(\text{max})} = 250^\circ\text{C/W}$	

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CEO}$

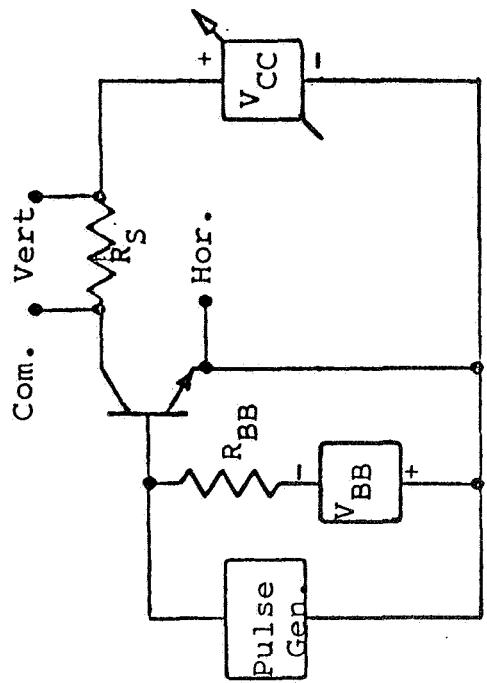
Test Circuit: JS-6-T12



$P_T = 1. \text{W}$

Figure 1

PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14

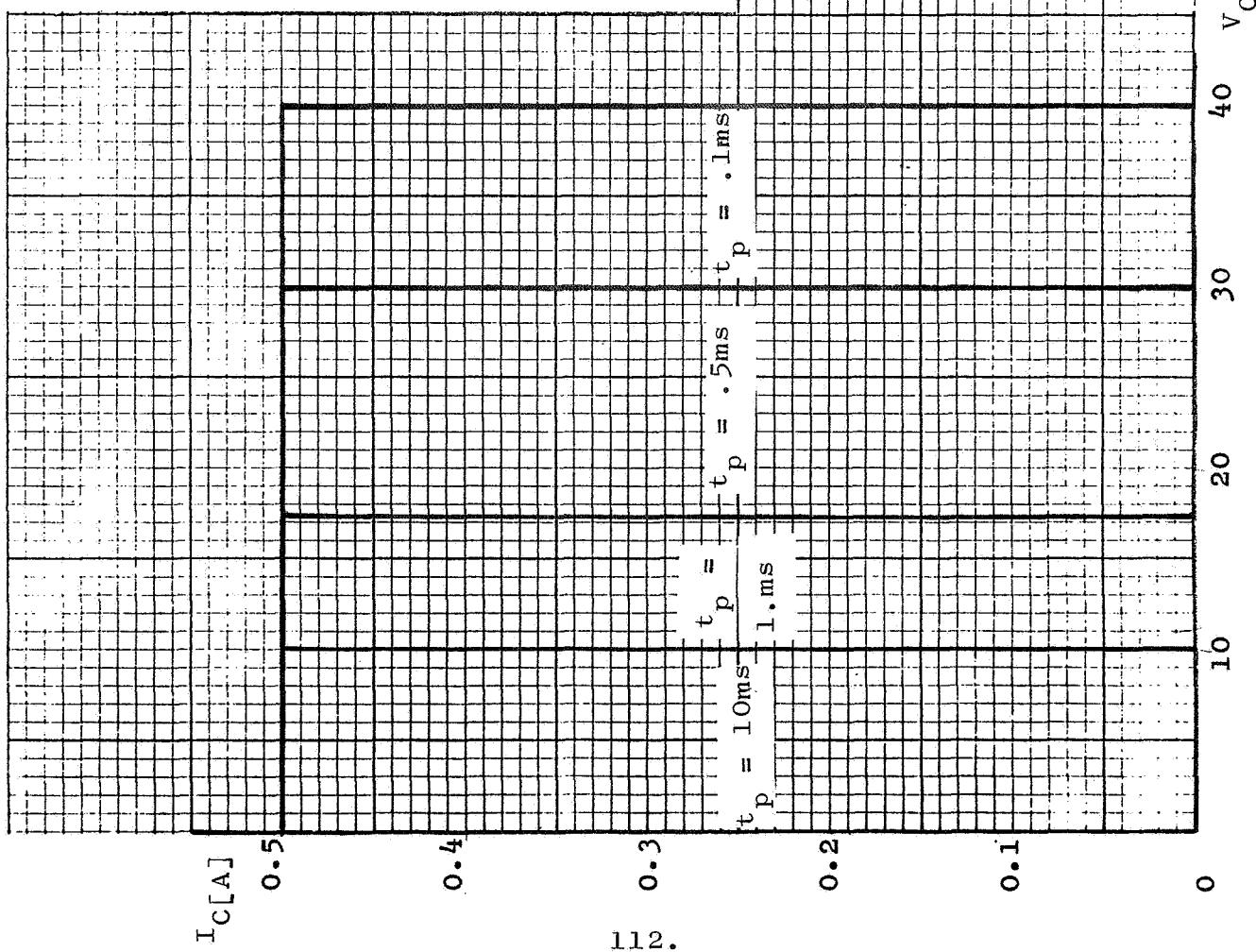
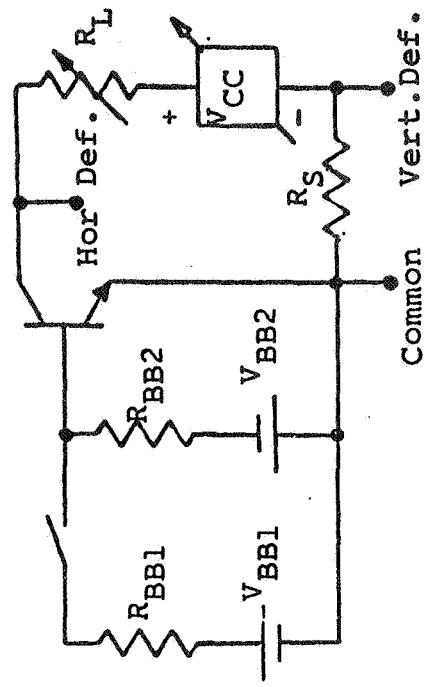


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

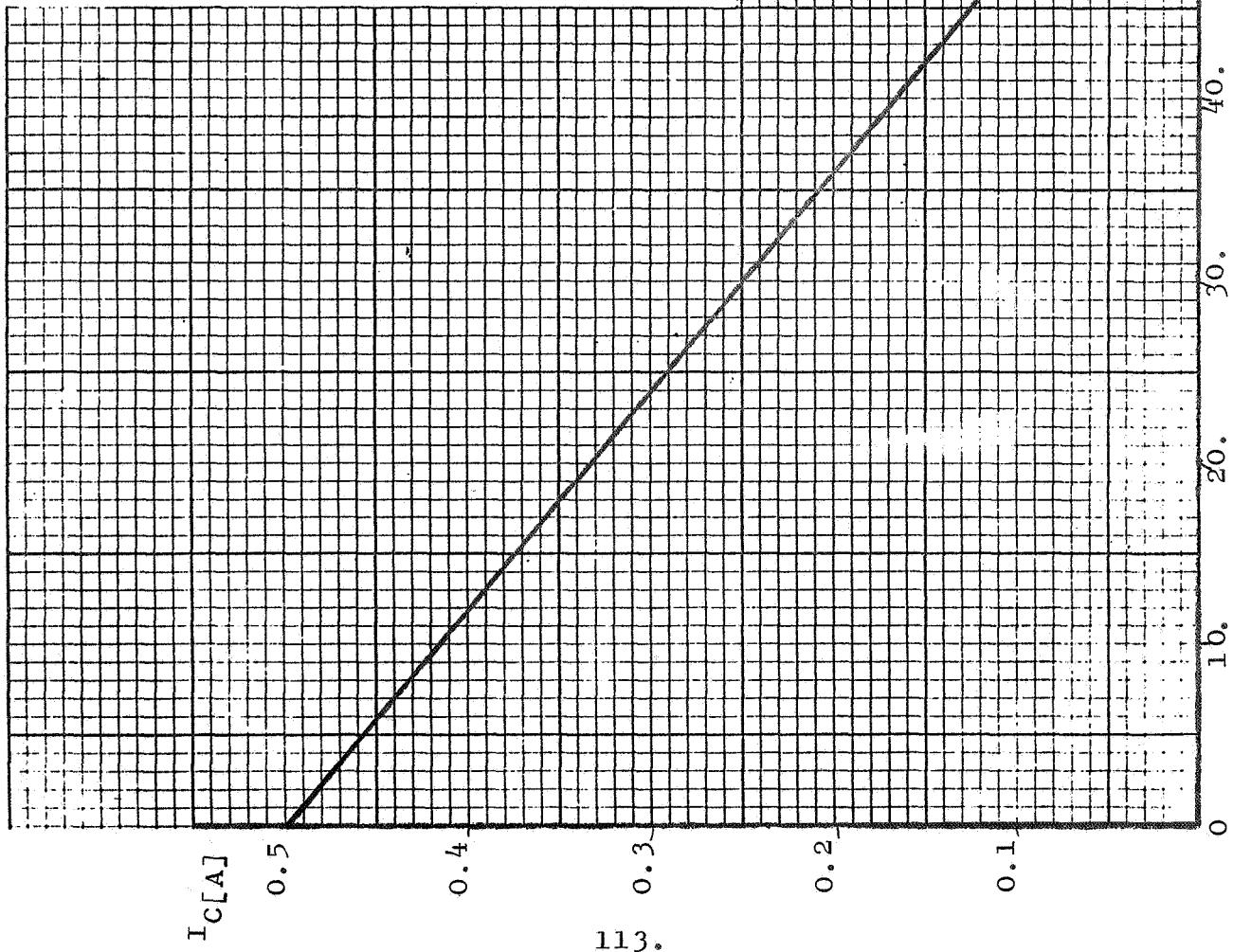
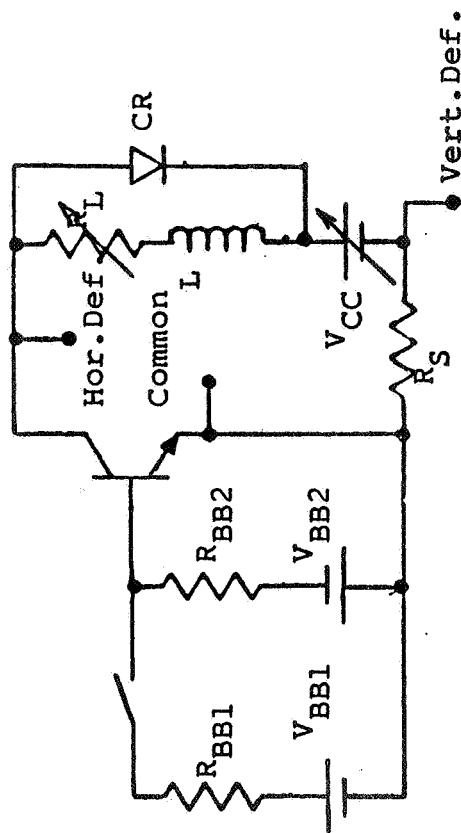


Figure 3

$V_{CE}$  [V]

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

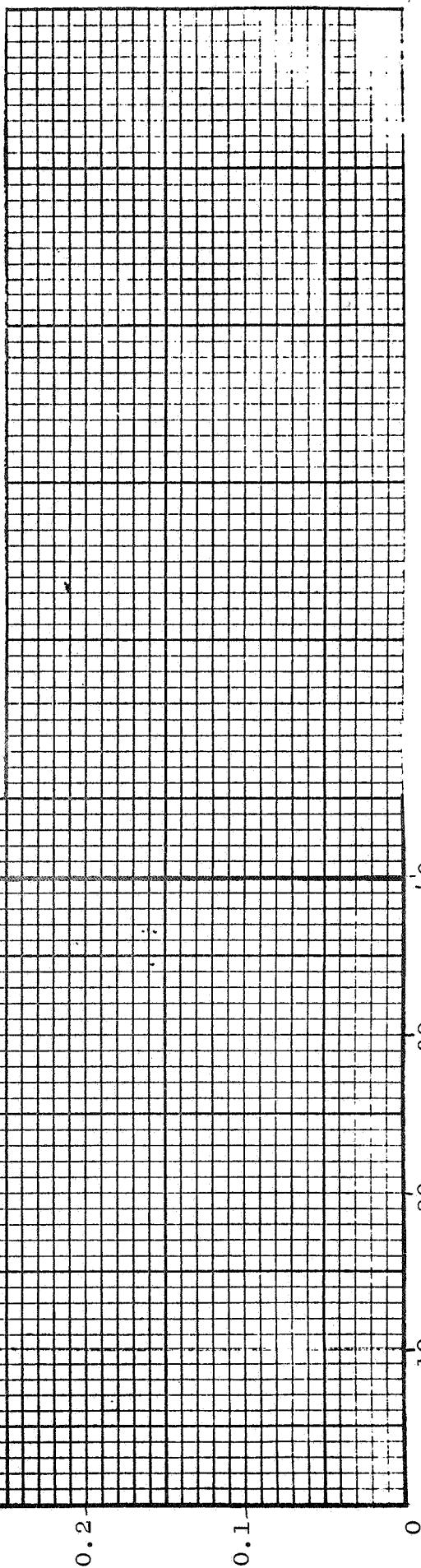
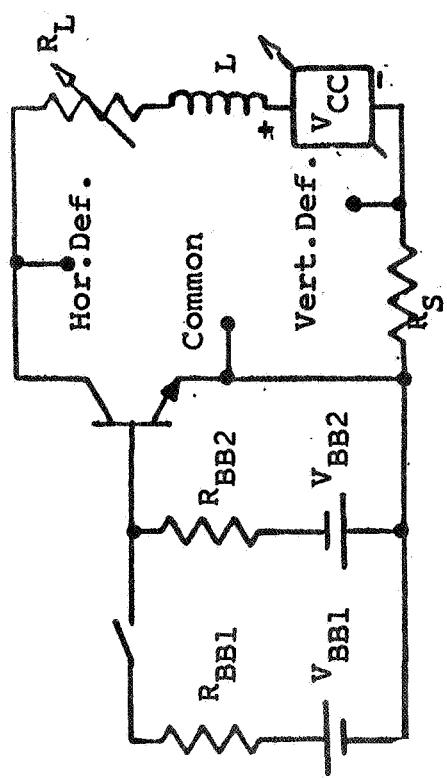
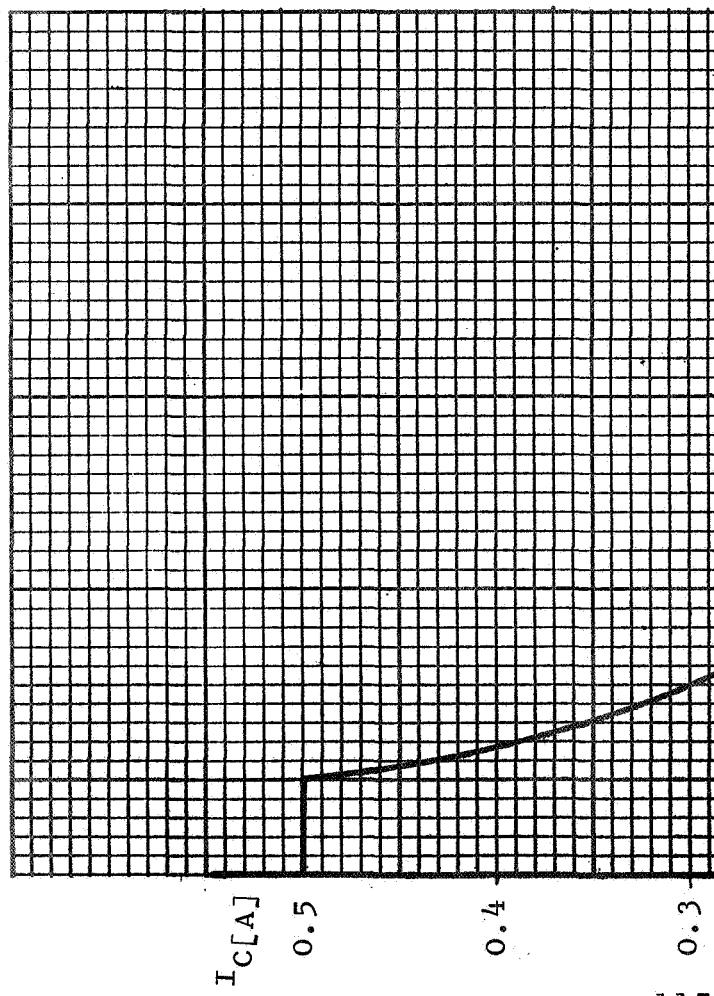


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1



115.

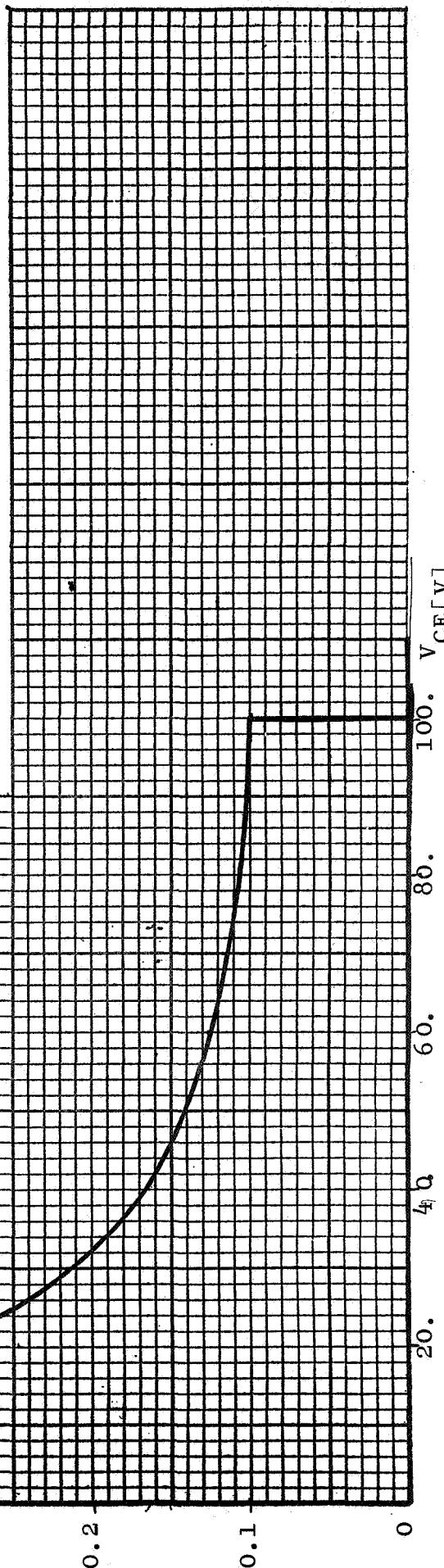


Figure 5

SHORTED CLASS B SOAR

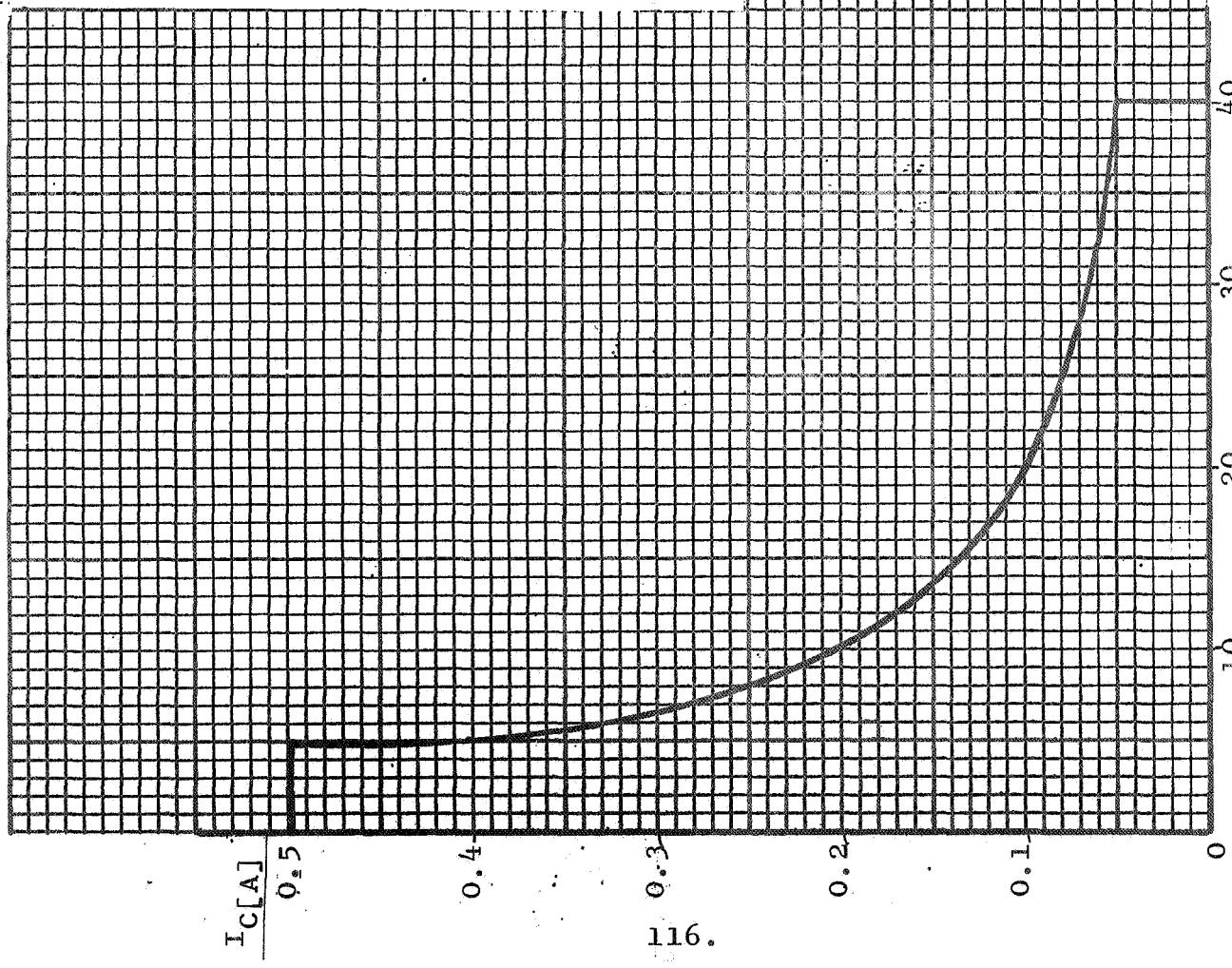
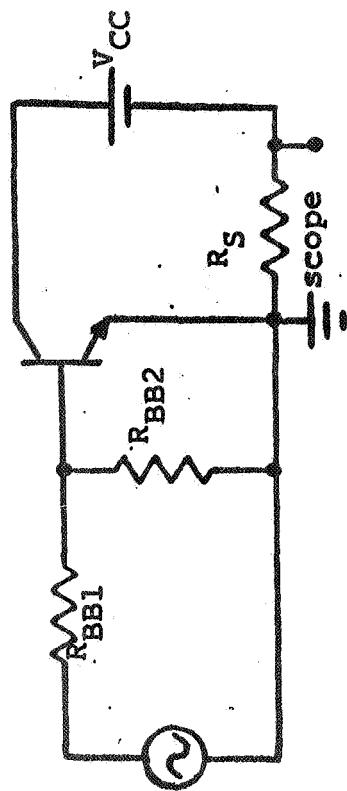


Figure 6

--- TEST REPORT ---  
SILICON POWER TRANSISTOR  
< 2N2880 >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

--- Manufacturer H ---

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Methods and Test Conditions</u>
1.0.0 <u>General Description</u>	
1.1.0 Type = NPN	
1.2.0 Material = Silicon	
2.0.0 <u>Mechanical Data</u>	
2.1.0 Outline = TO-111	
2.2.0 Terminal Designation	
1. --- Emitter	
2. --- Base	
3. --- Collector	
Case - Collector	
3.0.0 <u>Maximum Ratings</u>	
3.1.0 Temperature	
3.1.1 $T_{STG(min)} = -65^{\circ}\text{C}$	<u>JS-6-T1.1</u>
$T_{STG(max)} = +200^{\circ}\text{C}$	<u>JS-6-T1.2</u>
3.1.2 $T_J(max) = 200^{\circ}\text{C}$	<u>JS-6-T2</u>
	$T_C = 100^{\circ}\text{C}$
	$P_T = 30\text{W}, I_C = 5\text{A}$
3.1.3 $T$ (Lead) = $+230^{\circ}\text{C}$	Distance from case = $1/16"$
	Time = 10 sec.
3.2.0 Voltage	$T_C = 25^{\circ}\text{C}$
3.2.1 $V_{CBO} = 100\text{V}$	<u>JS-6-T3 or MIL-STD-750A</u>
	Method 3001.1

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.2.2 $V_{EBO} = 8V$	<u>JS-6-T3 or MIL-STD-750A</u> Method 3026.1
3.2.3 $V_{CEX} = 100V$	<u>JS-6-T4 or MIL-STD-750A</u> Method 3053  $I_C (V_{CE} = V_{CEX}) = 5A$ $V_{CC} = 100V, R_L = 19.5\Omega$ $L^* = 1.0mH, CR = 1N1204$ $V_{BB1} = 9V, R_{BB1} = 5\Omega$ $V_{BB2} = 2.5V, R_{BB2} = 5\Omega$ Pulse width = 1.0ms, Duty Cycle = 2% $R_S = 0.1\Omega, t_r \leq 50\mu s$ $t_f \leq 50\mu s$ * Miller No. 7871 in series with Miller No. 7825-3
3.3.0 Current	
3.3.1 $I_C = 5A$	<u>JS-6-T6</u>  $I_B = 0.5A, T_C \leq 25^\circ C$
3.3.2 $I_B = 0.5A$	<u>JS-6-T8</u>  $T_C \leq 25^\circ C$
3.4.0 Power	
3.4.1 $P_T = 30W$	<u>TS-6-T12 or MIL-STD-750A</u> Method 3051  $T_C \leq 100^\circ C$  Derating Factor= $0.3 W/\text{ }^\circ C$ $V_{CB} \approx 30V, I_C = 1A$

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.4.2 $P_{TM} = I_C V_{CC} = 350W$	<u>JS-6-T13 or MIL-STD-750A</u>
	<u>Method 3052</u>
	$T_C = 100^\circ C, V_{CC} = 70V$
	$V_{BB} = 2.5V, R_{BB} = 5\Omega$
	$Pulse width = 0.5ms$
	$Duty Cycle \leq 1\%$
	$t_r \leq 50\mu s, t_f \leq 50\mu s$
3.5.0 Maximum Operating Conditions	
3.5.1 Forward Biased Continuous DC SOAR	<u>JS-6-T12 or MIL-STD-750A</u>
	<u>Method 3051 [see figure 1]</u>
	<u>Test Points:</u> 1. [see 3.4.1]
	2. $V_{CB} \approx 70V, I_C = 0.2A,$
	$T_C = 100^\circ C, P_T = 14W$
3.5.2 Pulsed Forward Biased SOAR	<u>JS-6-T1.4 or MIL-STD-750A</u>
	<u>Method 3052</u>
	<u>Test Points:</u> [see figure 2]
	$T_C \leq 100^\circ C, V_{BB} = 2.5V$
	$R_{BB} = 5\Omega, I_C = 5A$
	$t_r \leq 50\mu s, t_f \leq 50\mu s$
	$Duty Cycle \leq 1\%, R_S = 0.1\Omega$
	1. For $t_p = 5ms; V_{CC} = 20V$
	2. For $t_p = 2.5ms; V_{CC} = 35V$
	3. For $t_p = 1ms; V_{CC} = 50V$
	4. For $t_p = 0.5ms; V_{CC} = 70V$

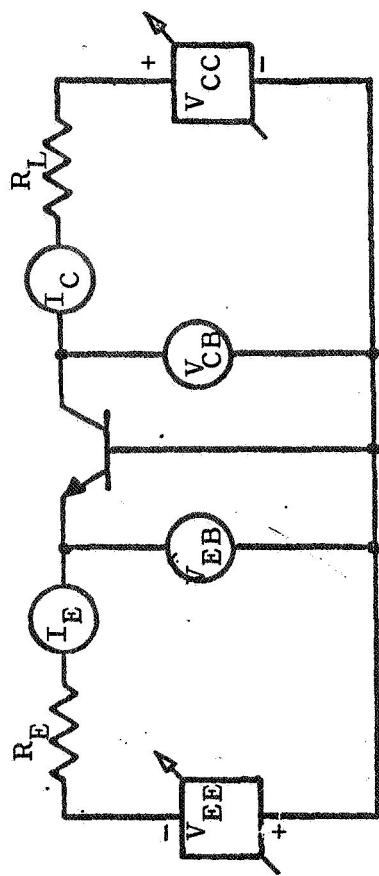
<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.6.0 SOAR Switching between Saturation and Cutoff	
3.6.1 Resistive Load	<p><u>JS-6-T5.1 or MIL-STD-750A</u></p> <p>Method 3053 with L = 0 and CR disconnected [see figure 3]</p> <p><u>Test Points:</u></p> <p><math>I_C = 5A</math>, <math>V_{CC} = 100V</math>, <math>R_{BB1} = 5\Omega</math>  <math>R_{BB2} = 5\Omega</math>, <math>V_{BB1} = 9V</math>, <math>V_{BB2} = 2.5V</math>  <math>T_C = 100^\circ C</math>; <math>R_S = 0.1\Omega</math>  <math>t_r \leq 50\mu s</math>, <math>t_f \leq 50\mu s</math> Collector Current</p>
3.6.2 Clamped Inductive Load	<p><u>JS-6-T5.1 or MIL-STD-750A</u></p> <p>Method 3053 [see figure 4]</p> <p><u>Test Points:</u></p> <p><math>I_C = 5A</math>, <math>V_{CC} = 100V</math>, <math>R_L = 19.5\Omega</math>  <math>L = 1mH</math>, <math>R_{BB1} = 5\Omega</math>, <math>R_{BB2} = 5\Omega</math>  <math>V_{BB1} = 9V</math>, <math>V_{BB2} = 2.5V</math>, <math>t_p = 1ms</math>,  <math>CR = 1N1204</math>, <math>T_C = 25^\circ C</math>, <math>t_r \leq 50\mu s</math>  <math>t_f \leq 50\mu s</math>, Duty Cycle = 2%  <math>R_S = 0.1\Omega</math></p>
3.6.3 Unclamped Inductive Load	<p><u>JS-6-T5.1 or MIL-STD-750A</u></p> <p>Method 3053 with CR disconnected</p> <p><u>Test Points:</u> [see figure 5]</p> <p><math>R_{BB1} = 5\Omega</math>, <math>R_{BB2} = 5\Omega</math>, <math>R_S = 0.1\Omega</math>  <math>V_{BB1} = 9V</math>, <math>V_{BB2} = 2.5V</math>, <math>f = 20Hz</math></p>

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.6.3 [Cont'd]	$T_C = 25^\circ C$ 1. $I_C = 4A, V_{CC} = 30V, R_L = 7\Omega$ $L = 125\mu H$ - Two Miller 7825-3 in parallel 2. $I_C = 0.5A, V_{CC} = 10V, R_L = 19\Omega$ $L = 10mH$ - Stancor C-2688
3.7.0 Shorted Class B SOAR	[see figure 6]
	<u>Test Points:</u>
	$I_C$ (peak) = 0.3A, $V_{CC} = 70V$ , $R_S = 0.1\Omega, R_{BB1} = 1\Omega, R_{BB2} = 3\Omega$ , $f = 20Hz, T_C = 100^\circ C$
4.0.0 <u>Electrical Characteristics</u>	
Maximum limits unless otherwise noted.	$T_C = 25^\circ C$ [unless otherwise noted]
	<u>Techniques:</u>
	DC = Continuous Operation
	C.T. = Curve Tracer
	P = 300 $\mu s$ Pulse
	2% Duty Cycle
4.1.0 Static	
4.1.1 $I_{CEX} = 50\mu A$	$V_{CE} = 60V, V_{BE} = -0.5V$ , $T_C = 150^\circ C$ , Techniques - C.T.

<u>Item</u>	<u>Test Methods and Test Conditions</u>
4.1.2 $I_{CEX} = 10\mu A$	$V_{CE} = 100V, V_{BE} = -0.5V$ Technique - C.T.
4.1.3 $I_{CBO} = 50\mu A$	$V_{CB} = 60V, T_C = 150^{\circ}C$ Technique - C.T.
4.1.4 $I_{CBO} = 0.1\mu A$	$V_{CB} = 60V$ Technique - C.T.
4.1.5 $I_{EBO} = 10\mu A$	$V_{EB} = 8V$ Technique - C.T.
4.1.6 $I_{EBO} = 0.1\mu A$	$V_{EB} = 5V$ Technique - C.T.
4.1.7 $V_{(BR)CEO} = 80V \text{ min}$	$I_C = 10mA$ Technique - C.T.
4.1.8 $V_{(BR)CEO} = 70V \text{ min}$	$I_C = 0.1A$ Technique - C.T.
4.1.9 $I_{CEO} = 100\mu A$	$V_{CEO} = 50V$ Technique - C.T.
4.1.10 $h_{FE} = 30 \text{ min}$ $120 \text{ max}$	$V_{CE} = 2V, I_C = 10mA$ Technique - P
4.1.11 $h_{FE} = 40 \text{ min}$ $120 \text{ max}$	$V_{CE} = 2V, I_C = 1A$ Technique - P
4.1.12 $h_{FE} = 15 \text{ min}$ $60 \text{ max}$	$V_{CE} = 2V, I_C = 1A, T_C = -55^{\circ}C$ Technique - P
4.1.13 $h_{FE} = 60 \text{ min}$ $200 \text{ max}$	$V_{CE} = 2V, I_C = 1A, T_C = 150^{\circ}C$ Technique - P
4.1.14 $h_{FE} = 15 \text{ min}$ $45 \text{ max}$	$V_{CE} = 5V, I_C = 5A$ Technique - P

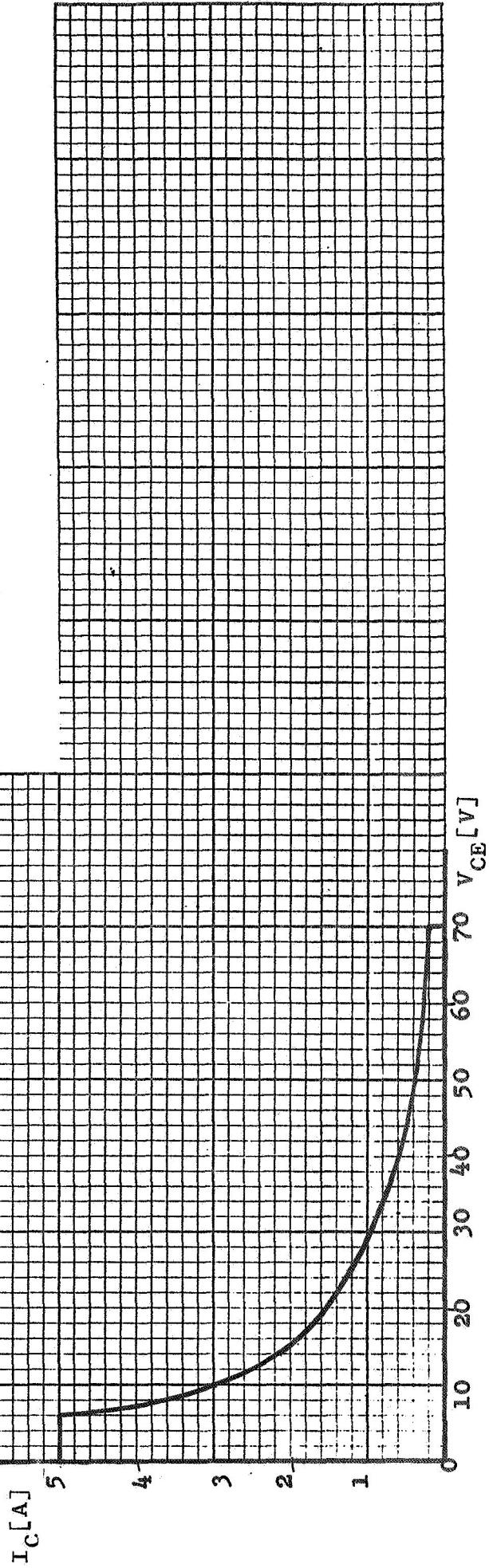
<u>Item</u>	<u>Test Methods and Test Conditions</u>
4.1.15 $V_{CE(sat)} = 0.25V$ max	$I_C = 1A, I_B = 0.1A$ Technique - C.T.
4.1.16 $V_{CE(sat)} = 2.0V$ max	$I_C = 5A, I_B = 0.5A$ Technique - C.T.
4.1.17 $V_{BE(sat)} = 1.2V$ max	$I_C = 1A, I_B = 0.1A$ Technique - C.T.
4.1.18 $V_{BE(sat)} = 2V$ max	$I_C = 5A, I_B = 0.5A$ Technique - C.T.
4.1.19 $V_{BE} = 1.2V$ max	$V_{CE} = 2V, I_C = 1A$ Technique - C.T.
4.2.0 Dynamic	
4.2.1 $t_{ON} = 300ns$	$V_{CC} = 20V, I_C = 1A$
4.2.2 $t_{OFF} = 2.0\mu s$	$I_{B1} = - I_{B2} = 100mA$
4.2.3 $ h_{FE}  = 2 \text{ min}$ $= 9 \text{ max}$	$V_{CE} = 10V, I_C = 1A, f = 10MHz$
4.2.4 $C_{obo} = 150 \text{ pF max}$	$V_{CB} = 10V, f = 1MHz$
5.0.0 <u>Thermal</u> <u>Characteristics</u>	
5.1.0 $\tau_J = 5ms \text{ min}$	MIL-STD-750, method 3146.1
5.2.0 $\theta_{J-C} = 3.33^{\circ}\text{C/W}$	$V_{CE} = 10V, I_C = 2A, T_C = 25^{\circ}\text{C}$ MIL-STD-750A, method 3136 $V_{CE} = 5V, I_C = 2A$

FORWARD BIASED CONTINUOUS SOAR

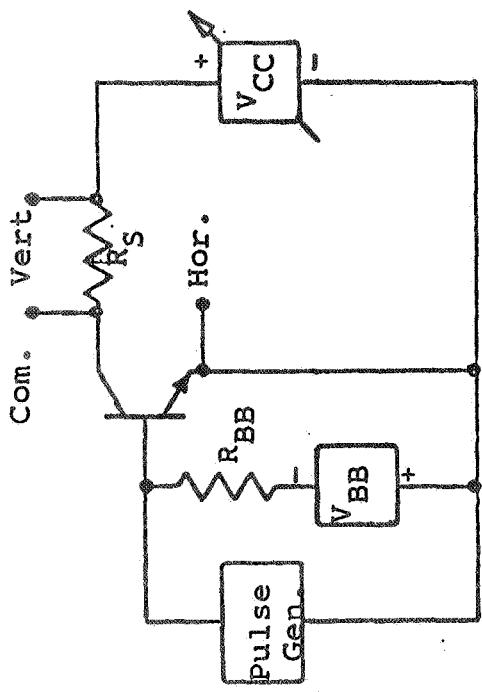


Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CEO}$

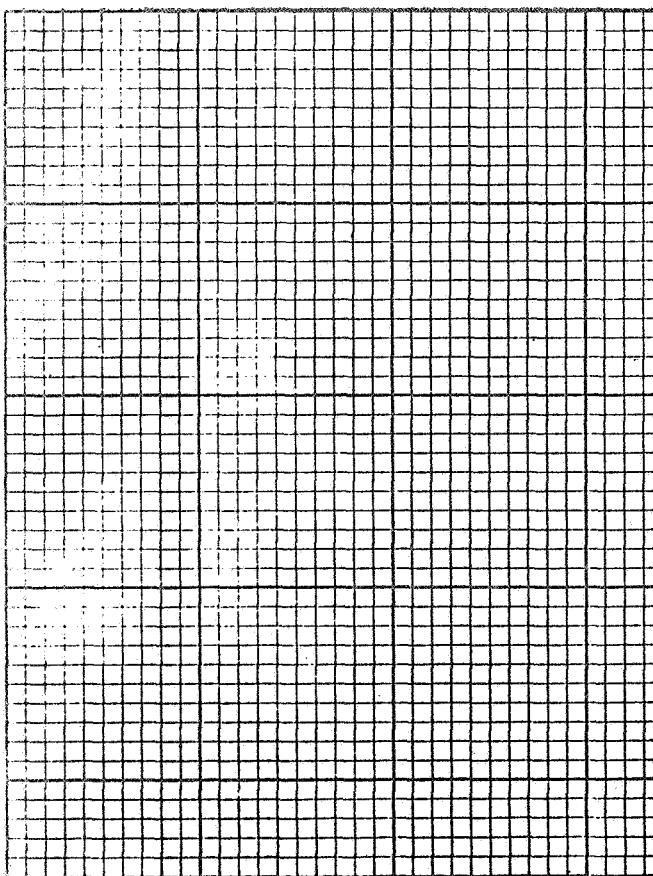
Test Circuit: JS-6-T12



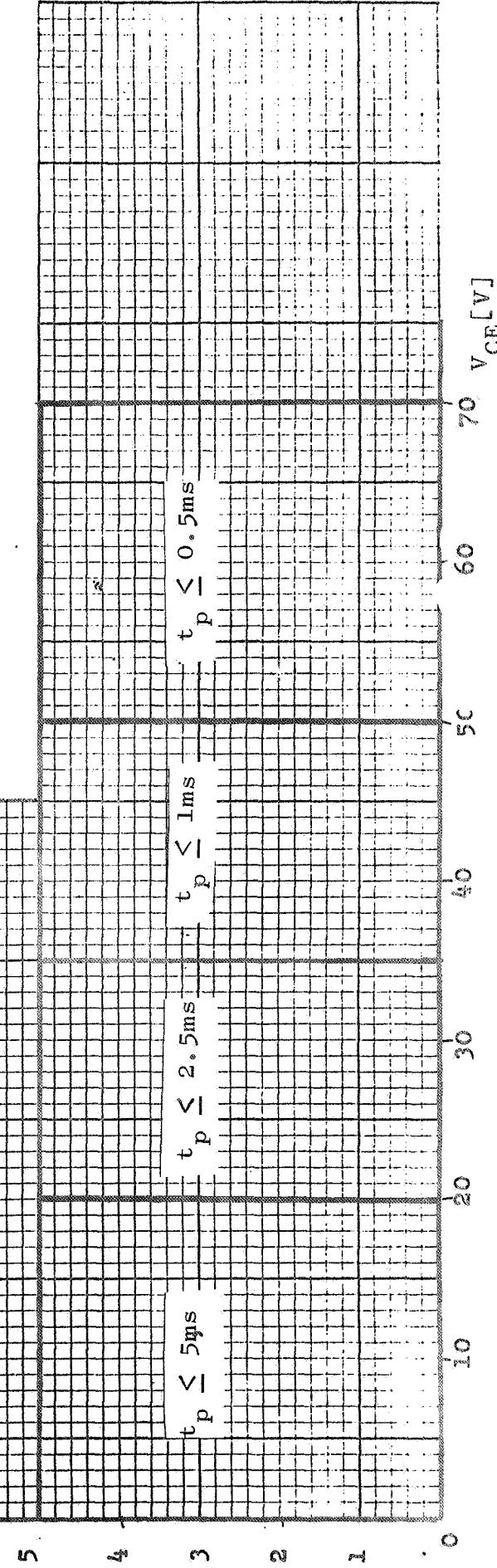
PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14



$I_C$  [A]



SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-RESISTIVE LOAD

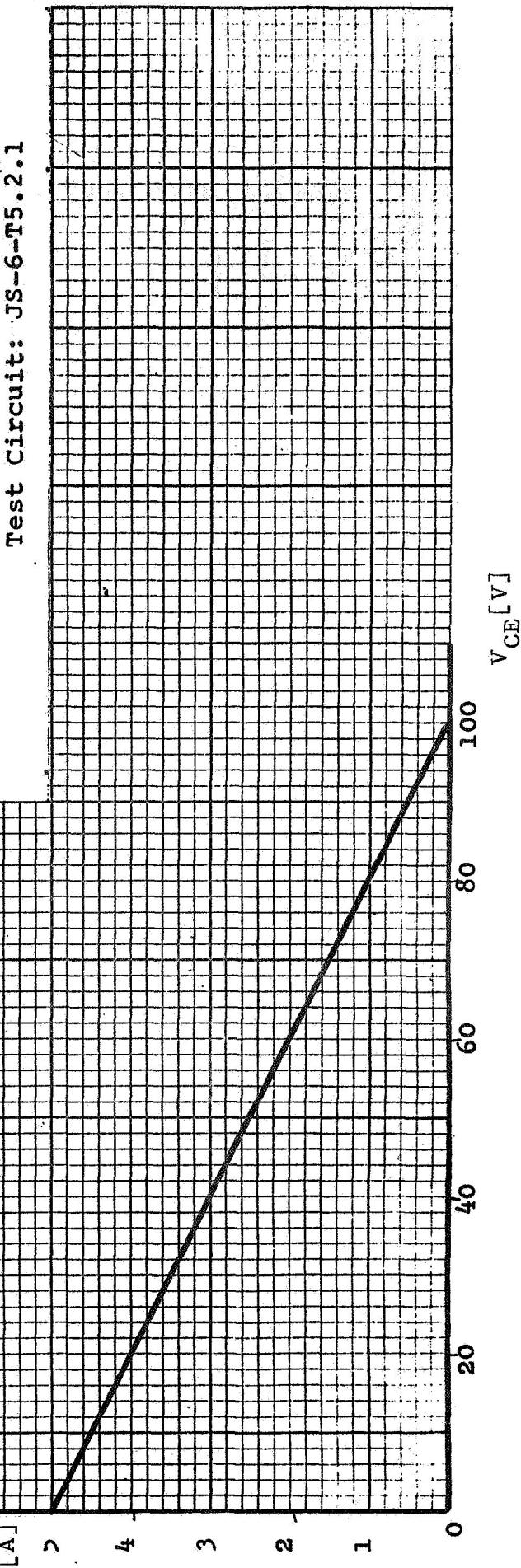
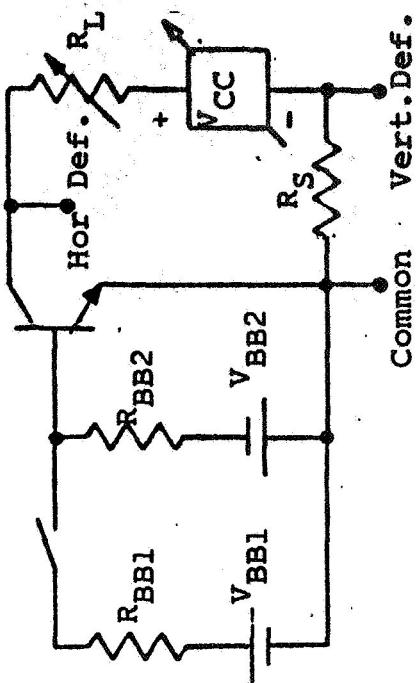
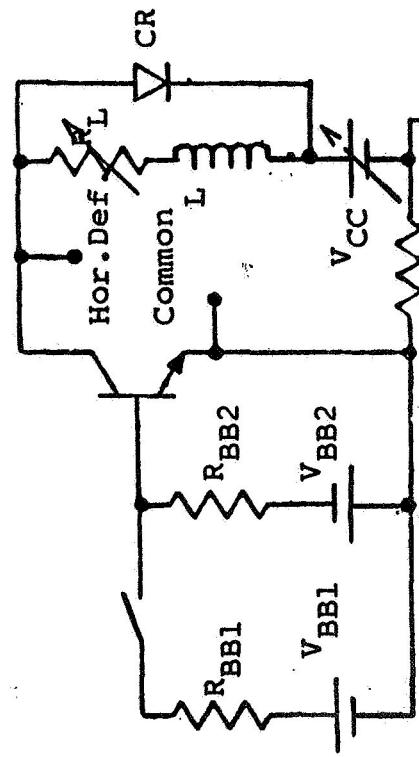
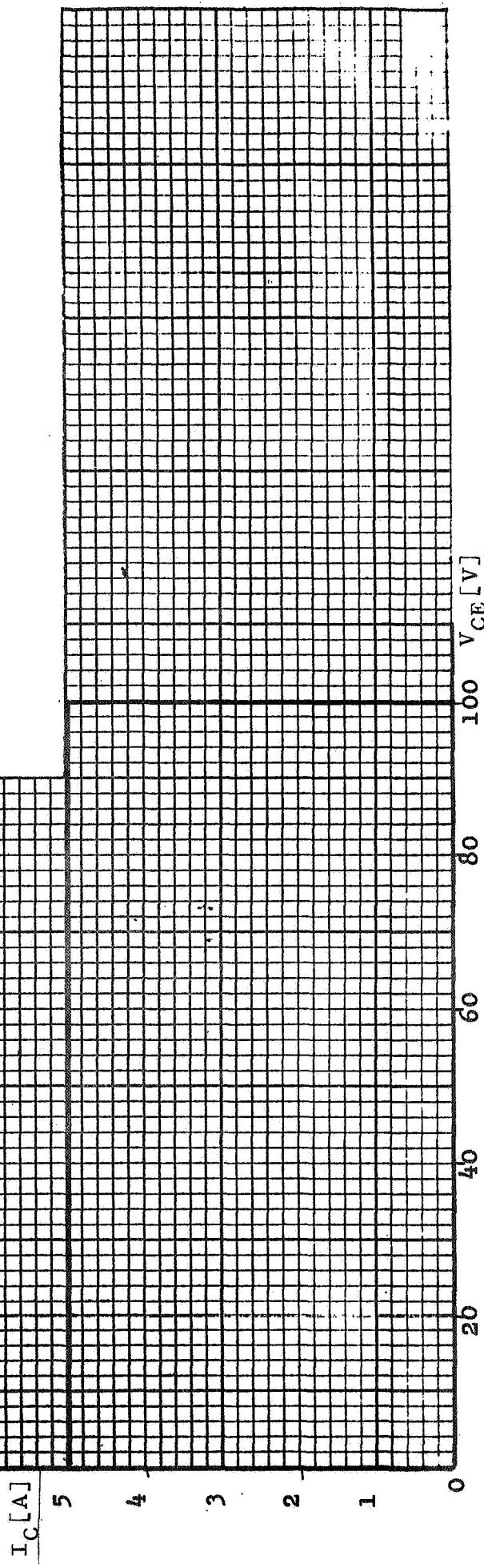


Figure 3

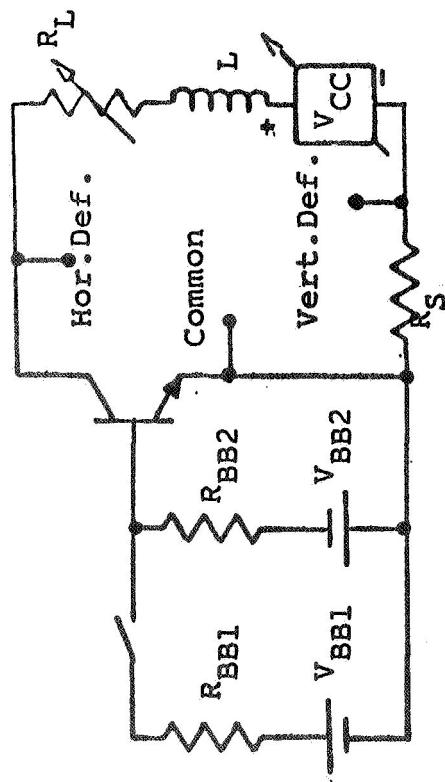
SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1  
vert.Def.



SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF - UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

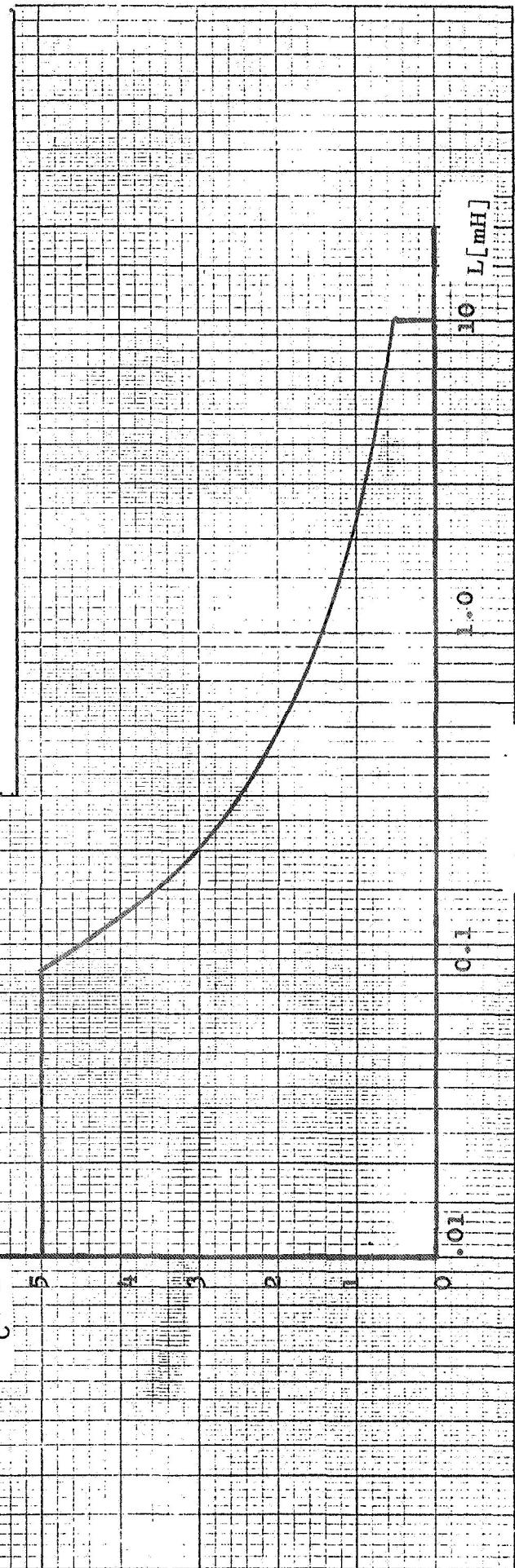


Figure 5

SHORTED CLASS B SOAR

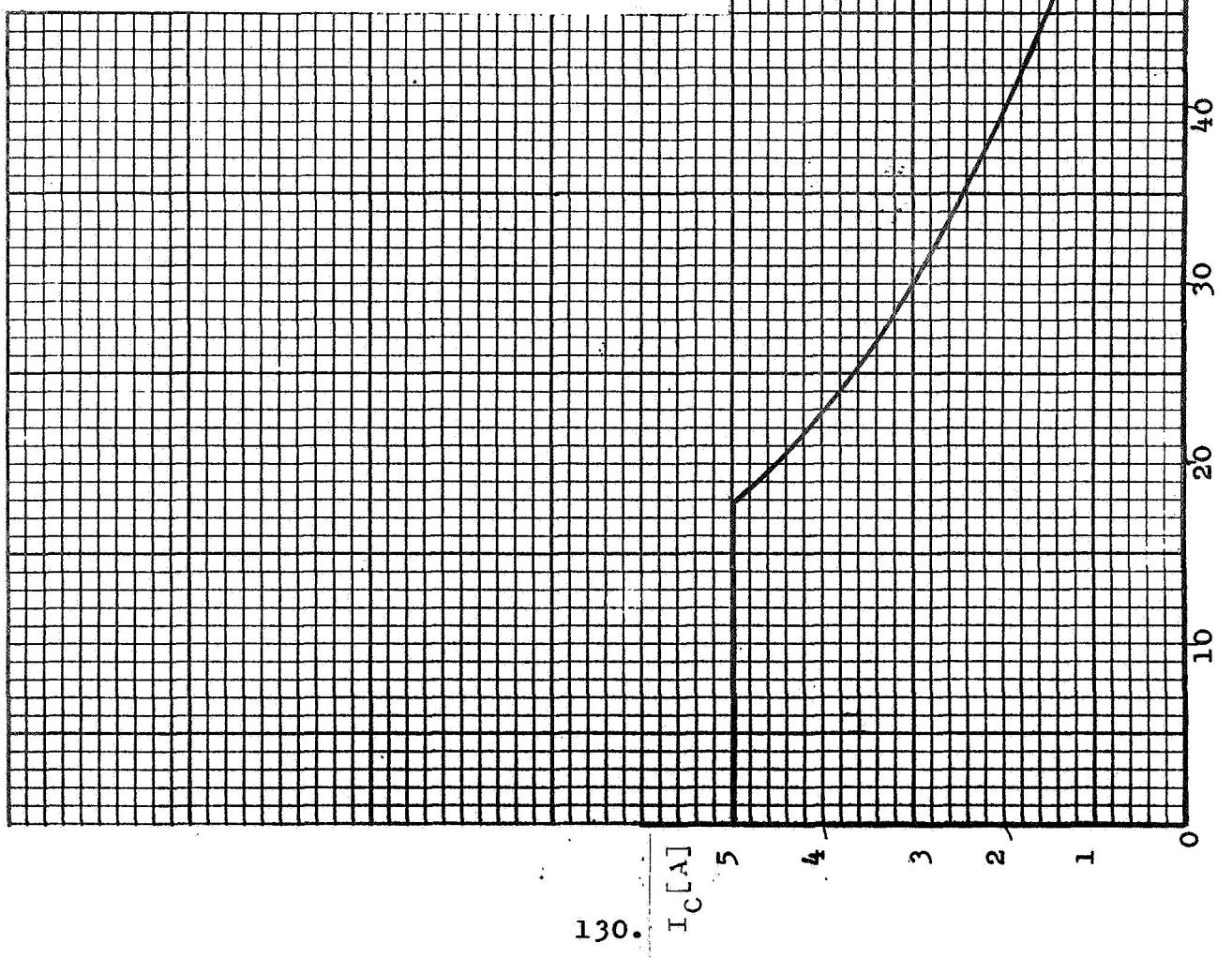
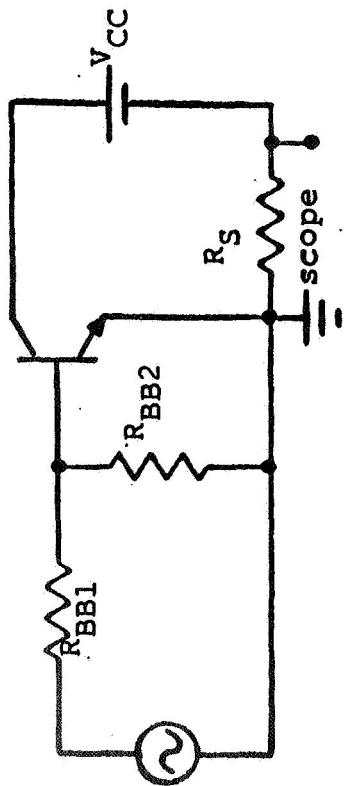


Figure 6

-- TEST REPORT --

SILICON POWER TRANSISTOR

< S2N4150 >

SAFE OPERATING AREA  
DETERMINATION FOR PREVENTION  
OF SECOND BREAKDOWN

-- Manufacturer H --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

<u>Item</u>	<u>Test Methods and Test Condition</u>
1.0.0 <u>General Description</u>	
1.1.0 Type -- NPN	
1.2.0 Material -- Silicon	
2.0.0 <u>Mechanical Data</u>	
2.1.0 Outline T0-5	
2.2.0 Terminal Designation	
1 --- Base	
2 --- Emitter	
3 --- Collector	
Case---Collector	
3.0.0 <u>Maximum Ratings</u>	
3.1.0 Temperature	
3.1.1 $T_{STG(min)} = -55^{\circ}\text{C}$	<u>JS-6-T1.1</u> [ JEDEC Suggested standard:
$T_{STG(max)} = +200^{\circ}\text{C}$	<u>JS-6-T1.2</u> "Test Procedure for Verification of Maximum Ratings." JEDEC Publication No. 65.]
3.1.2 $T_J(\text{max}) = +200^{\circ}\text{C}$	<u>JS-6-T2</u> or MIL-STD-750A Method 3051
	$T_C = 100^{\circ}\text{C}$ , $P_T = 5\text{W}$ , $I_C = 0.1\text{A}$ ,
	$V_{CE} = 50\text{V}$
3.1.3 $T$ (Lead) = $230^{\circ}\text{C}$	Distance from Case 1/16"
	Time = 3 sec.
3.2.0 Voltage	

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.2.1 $V_{(BR)CBO} = 120V$	<u>JS-6-T3</u> or MIL-STD-750A Method 3001.1
3.2.2 $V_{(BR)EBO} = 7V$	<u>JS-6-T4</u> or MIL-STD-750A Method 3026.1
3.2.3 $V_{(BR)CEX} = 70V$	<u>JS-6-T5.1</u> or MIL-STD-750A Method 3053 $I_C \leq 10A$ , $V_{CE} = 70V$ , $R_{BB1} = 10\Omega$ , $R_{BB2} = 20\Omega$ . $V_{BB1} = 16V$ , $V_{BB2} = 5.0V$ $R_L = 7\Omega$ , $L^* = 1.0mH$ $R_S = 0.1\Omega$ $t_r \leq 10\mu s$ , $t_f \leq 10\mu s$ , $t_p = 300\mu s$ Duty cycle $\leq 0.2\%$ *J.W. Miller: 7871 in series with 7825-3
3.3.0 Current	
3.3.1 $I_C = 3.0A$	<u>JS-6-T-6</u> $I_B = 0.3A$ , $T_C = 25^\circ C$
3.3.2 $I_{CM} = 10A$	<u>JS-6-T7</u> $T_C = 25^\circ C$ $R_S = 0.1\Omega$ $V_{BB} = 5V$ $R_{BB} = 20\Omega$ $I_B = 1A$ , $t_p = 300\mu s$ $d \leq 0.2\%$ $t_r \leq 10\mu s$ , $t_f \leq 10\mu s$
3.3.3 $I_B = 0.5A$	<u>JS-6-T8</u> $T_C = 25^\circ C$

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.3.4 $I_{BM} = 1.0A$	<u>JS-6-T4</u> $T_C = 25^\circ C$ , $R_S = 1.0\Omega$ , $t_p = 300\mu s$ , $t_r \leq 10\mu s$ $t_f \leq 10\mu s$ , $d \leq 0.2\%$
3.3.5 $I_E = 3.3A$	<u>JS-6-T10</u> $I_B = 0.3A$ , $T_C = 25^\circ C$
3.3.6 $I_{EM} = 11A$	[see 3.3.2]
3.4.0 Power	
3.4.1 $P_T = 5.0W$	<u>JS-6-T12</u> Test Point:[See 3.1.2]
3.4.2 $P_{TM} = I_C V_{CC} = 700W$	<u>JS-6-T13</u> or MIL-STD-750A Method 3052 $T_C = 100^\circ C$ , $V_{CC} = 70V$ , $V_{BB1} = 16V$ , $R_{BB} = 10\Omega$ , $I_C = 10A$ , Pulse Width = $100\mu s$ Duty Cycle $\leq 0.2\%$ $t_r \leq 10\mu s$ $t_f \leq 10\mu s$
3.5.0 Maximum Operating Conditions	
3.5.1 Forward Biased Continuous DC-SOAR	<u>JS-6-T12</u> or MIL-STD-750A Method 3051 Test Points: [See 3.1.2]

<u>Item</u>	<u>Test Methods and Test Conditions</u>
3.5.2 Pulsed Forward Biased SOAR	<u>JS-6-T14 or MIL-STD-750A</u> <u>Method 3052</u>
	<u>Test Points:</u> $T_C = 100^\circ C$ , $V_{BB} = 5V$ , $R_{BB} = 20\Omega$ , $t_r \leq 10\mu s$ , $t_f \leq 10\mu s$ , $I_C = 10A$ , Duty Cycle $\leq 0.2\%$ , $R_S = 0.1\Omega$ , 1. $t_p = 100\mu s$ : $V_{CC} = 70V$ 2. $t_p = 200\mu s$ : $V_{CC} = 50V$ 3. $t_p = 300\mu s$ : $V_{CC} = 30V$
3.6.0 SOAR Switching between Saturation and Cutoff	
3.6.1 Resistive Load	<u>JS-6-T5-5.1 or MIL-STD-750A</u> Method 3053 with $L = 0$ and CR disconnected <u>Test Points:</u> $R_{BB1} = 10\Omega$ , $R_{BB2} = 20\Omega$ , $V_{BB1} = 16V$ , $V_{BB2} = 5.0V$ , $T_C = 100^\circ C$ , $t_f \leq 10\mu s$ , $t_r \leq 10\mu s$ , $R_S = 0.1\Omega$ , $R_L = 12\Omega$ , $V_{CC} = 120$ , $d \leq 0.2\%$ , $t_p \leq 300\mu s$
3.6.2 Clamped Inductive Load	<u>JS-6-T5.1 or MIL-STD-750A</u> Method 3053 Test Point: [see 3.2.3]

<u>Item</u>	<u>Test Methods and Test Conditions</u>			
3.6.3 Unclamped Inductive Load	<u>JS-6-T5.1 or MIL-STD-750A</u>			
Method 3053 and CR disconnected				
<u>Test Points:</u>				
1. $V_{BB1} = 16V$ $L^* = 1.0mH$				
$R_{BB1} = 10\Omega$ $R_L = .35\Omega$				
$V_{BB2} = 5.0V$ $V_{CC} = \text{adjust to}$				
$I_C = 10A$				
$R_{BB2} = 20\Omega$ $t_p = 300\mu s$				
$R_S = 0.1\Omega$ $d \leq 0.2\%$				
*J.W.Miller: 7871 in series with 7825-3				
2. $V_{BB1} = 6.0V$ $L^* = 10mH$				
$R_{BB1} = 10\Omega$ $R_L = .11\Omega$				
$V_{BB2} = 5.0V$ $V_{CC} = \text{adjust to}$				
$I_C = 0.5A$				
$R_{BB2} = 20\Omega$ $t_p = 300\mu s$				
*Chicago Standard Transformer Corp.				
C-2688				
3.7.0 Shorted Class B SOAR	[See Figure 6]			
<u>Test Points:</u>				
$I_C(\text{peak}) = 0.43A$ , $V_{CC} = 35V$				
$R_S = 0.1\Omega$ , $R_{BB1} = 10\Omega$ , $R_{BB2} = 20\Omega$				
$f = 20Hz$ , $T_C = 100^\circ C$				

<u>Item</u>	<u>Test Methods and Test Conditions</u>
<b>4.0.0 <u>Electrical Characteristics</u></b>	
Maximum limits unless otherwise noted.	$T_C = 25^\circ C$ [unless otherwise noted]
Technique:	
MIL-STD-750A * JS-6	
C.T. = Curve Tracer	
P = 300 $\mu$ s Pulse 2% Duty Cycle	
<b>4.1.0 Static</b>	
4.1.1 $I_{CBO} = 100\text{nA}$ max	$V_{CB} = 80V$ , Technique *Method 3036.1D
4.1.2 $I_{CBO} = 10\mu A$ max	$V_{CB} = 80V$ , $T_C = 150^\circ C$ Technique *Method 3036.1 D
4.1.3 $I_{CBO} = 10\mu A$ max	$V_{CB} = 100V$ , Technique *Method 3036.1 D
4.1.4 $I_{CEV} = 100\mu A$ max	$V_{CE} = 60V$ , $V_{EB} = 0.5V$ , $T_C = 150^\circ C$ Technique *Method 3041.1A
4.1.5 $I_{CEO} = 10\mu A$ max	$V_{CE} = 60V$ , Technique *Method 3041.1 A
4.1.6 $I_{EBO} = 10\mu A$ max	$V_{EB} = 5V$ , Technique *Method 3061.1 D
4.1.7 $V_{CEO} = 70V$ min	$I_C = 100\text{mA}$ , Technique C.T. [half wave]
4.1.8 $h_{FE} = 40$ min 145 max	$I_C = 10\text{mA}$ , $V_{CE} = 5V$ Technique C.T.
4.1.9 $h_{FE} = 45$ min 170 max	$I_C = 100\text{mA}$ , $V_{CE} = 5V$ Technique P
4.1.10 $h_{FE} = 50$ min 175 max	$I_C = 1.0A$ , $V_{CE} = 5V$ Technique P

<u>Item</u>	<u>Test Methods and Test Conditions</u>
4.1.11 $h_{FE} = 40$ min 120 max	$I_C = 5.0A, V_{CE} = 5V$ Technique P
4.1.12 $h_{FE} = 10$ min	$I_C = 10A, V_{CE} = 5V$ Technique P
4.1.13 $h_{FE} = 75$ min 350 max	$I_C = 100mA, V_{CE} = 5V, T_C = 150^\circ C$ Technique P
4.1.14 $h_{FE} = 70$ min 320 max	$I_C = 1.0A, V_{CE} = 5V, T_C = 150^\circ C$ Technique P
4.1.15 $h_{FE} = 30$ min 150 max	$I_C = 5.0A, V_{CE} = 5V, T_C = 150^\circ C$ Technique P
4.1.16 $h_{FE} = 30$ min 90 max	$I_C = 100mA, V_{CE} = 5V, T_C = -55^\circ C$ Technique P
4.1.17 $h_{FE} = 30$ min 100 max	$I_C = 1.0A, V_{CE} = 5V, T_C = -55^\circ C$ Technique P
4.1.18 $h_{FE} = 20$ min 75 max	$I_C = 5.0A, V_{CE} = 5V, T_C = -55^\circ C$ Technique P
4.1.19 $V_{CE(S)} = 0.55V$ max	$I_C = 5.0A, I_B 0.5A$ Technique * P
4.1.20 $V_{CE(S)} = 2.0V$ max	$I_C = 10A, I_B = 1.0A$ Technique * P
4.1.21 $V_{BE(S)} = 1.4V$ max	$I_C = 5.0A, I_B = 0.5A$ Technique * P
4.1.22 $V_{BE(S)} = 2.0V$ max	$I_C = 10A, I_B = 1.0A$ Technique * P

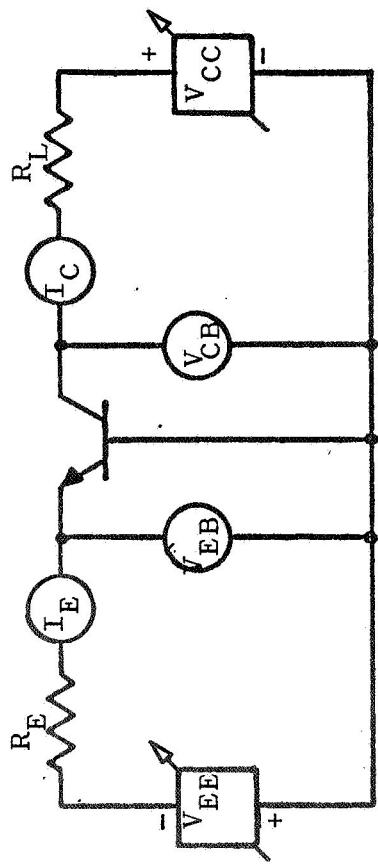
<u>Item</u>	<u>Test Methods and Test Conditions</u>
4.2.0 Dynamic	
4.2.1 $h_{FE}$ = 1.5 min 8.0 max	$I_C$ = 200mA, $V_{CE}$ = 10V, $f$ = 10MHz
4.2.2 $C_{obo}$ = 350 pF max	$V_{CB}$ = 10V, $I_E$ = 0 $f$ = 1MHz
4.2.3 $t_{ON}$ = 0.5μs max	circuit specified with registered spec. S2N4150
4.2.4 $t_{OFF}$ = 2.5μs max	Circuit specified with registered spec. S2N4150

#### 5.0.0 Thermal Characteristics

- 5.1.1  $\gamma_J$  = 20 ms min
- 5.1.2  $\theta_{JC}$  = 20 °C/W max
- 5.1.3  $\theta_{JA}$  = 175 °C/W max

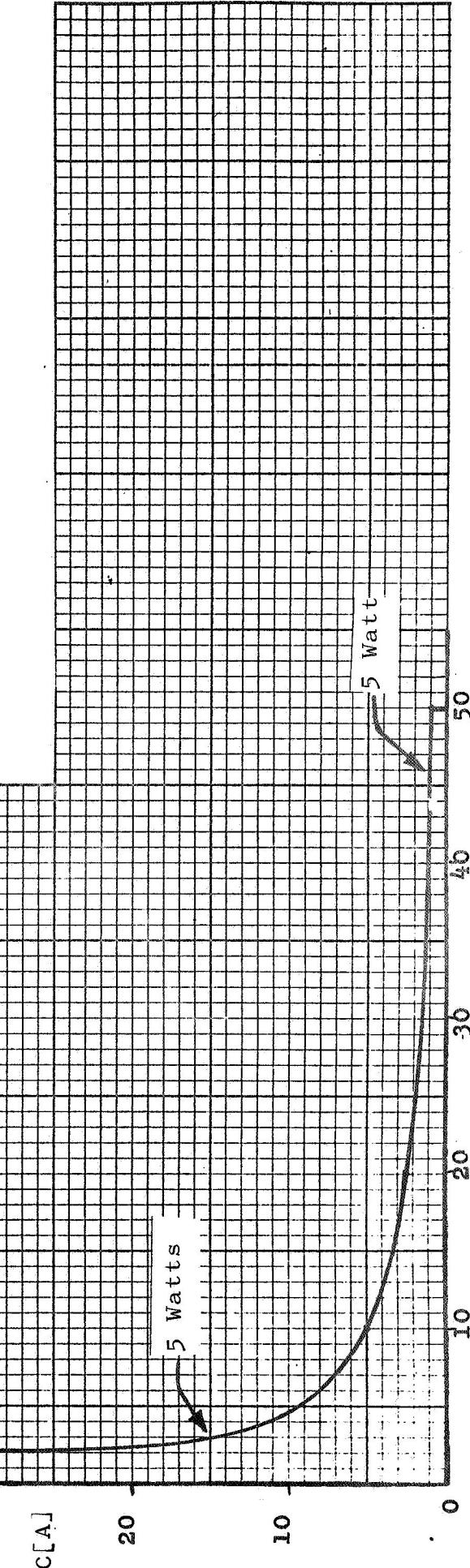
\*Test clips 1/4" from case

FORWARD BIASED CONTINUOUS SOAR

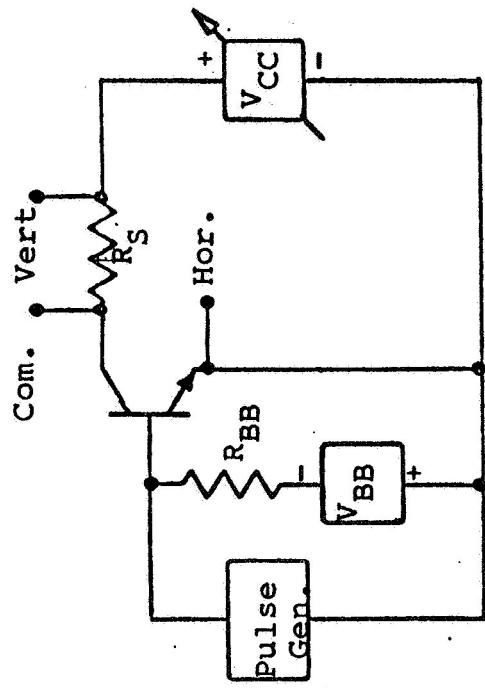


Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CEO}$

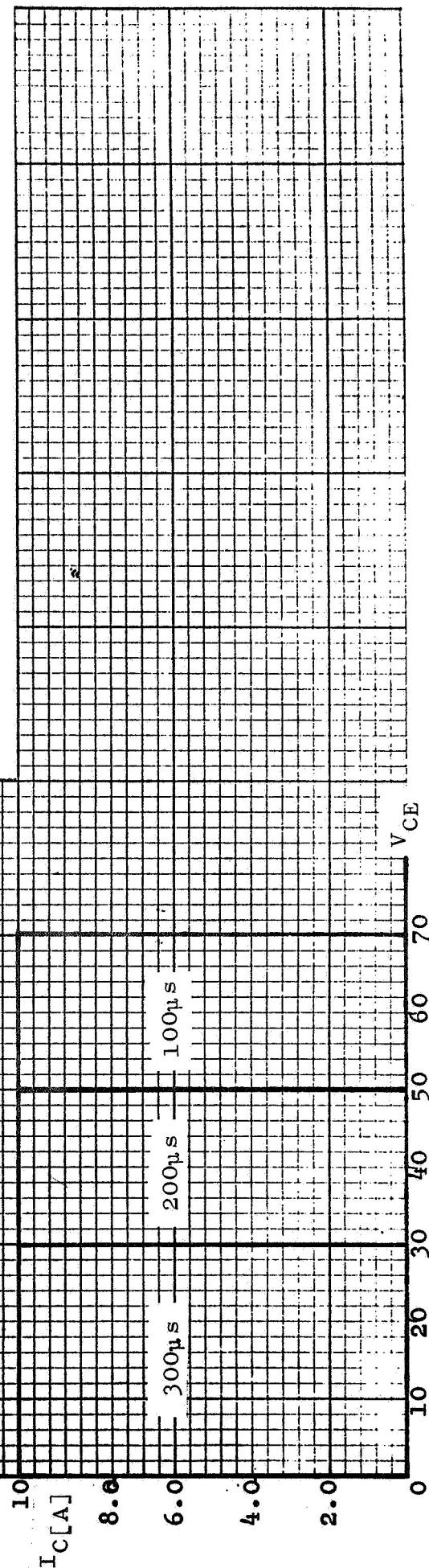
Test Circuit: JS-6-T12.



PULSED FORWARD BIASED SOAR



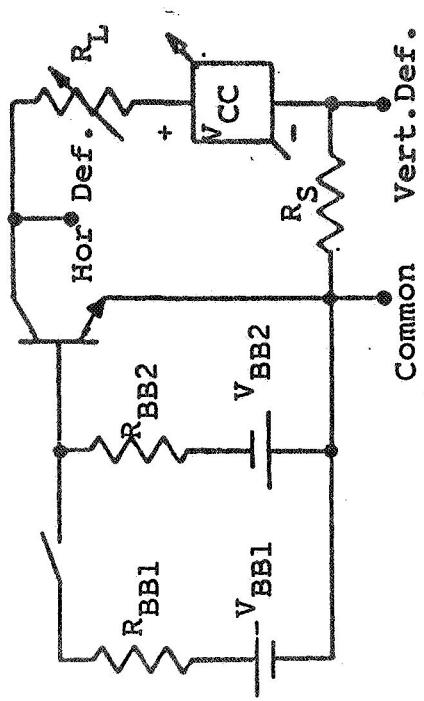
Test Circuit: JS-6-T14



141.

Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF—RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

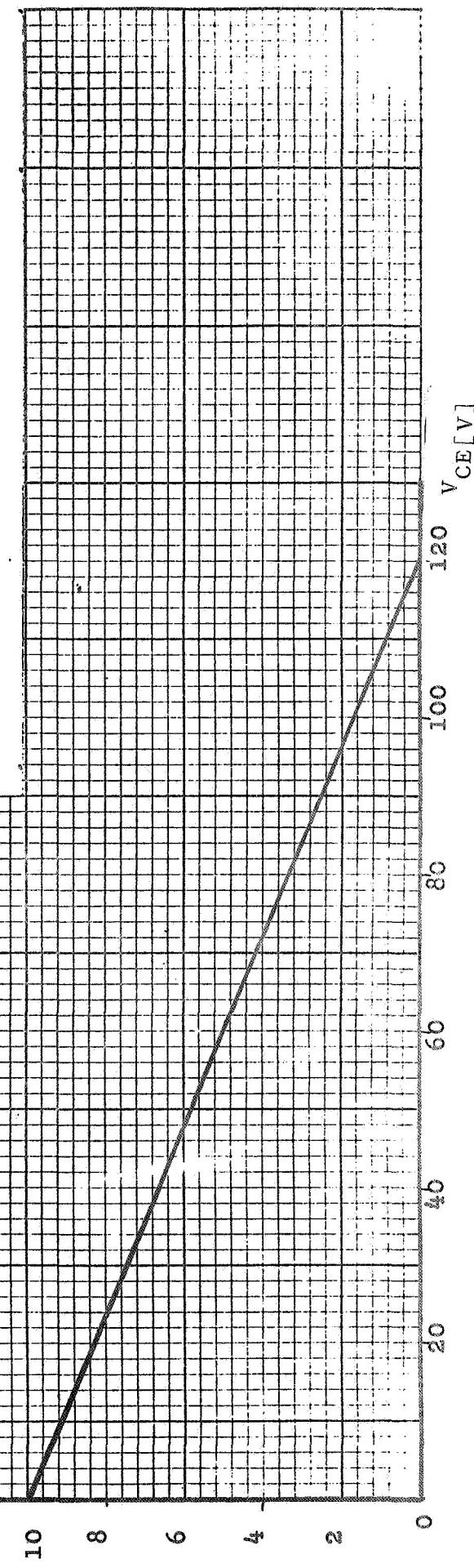
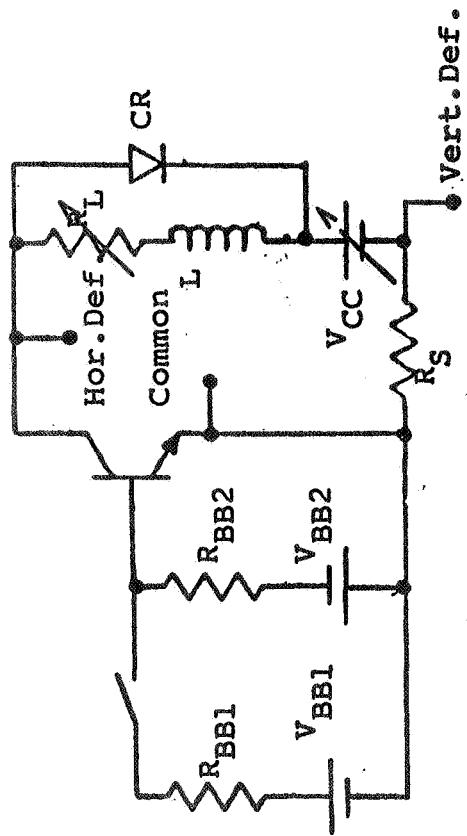
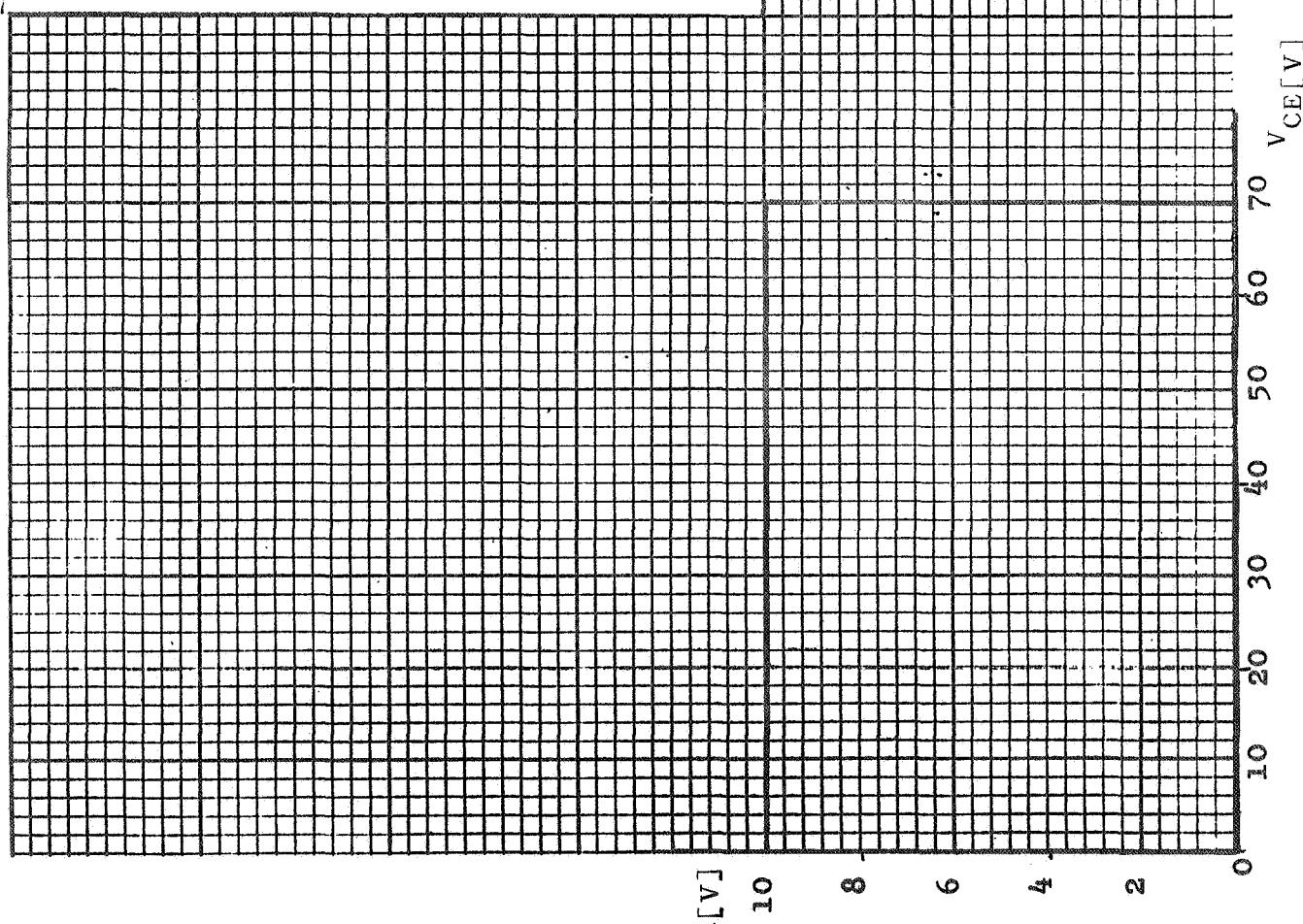


Figure 3

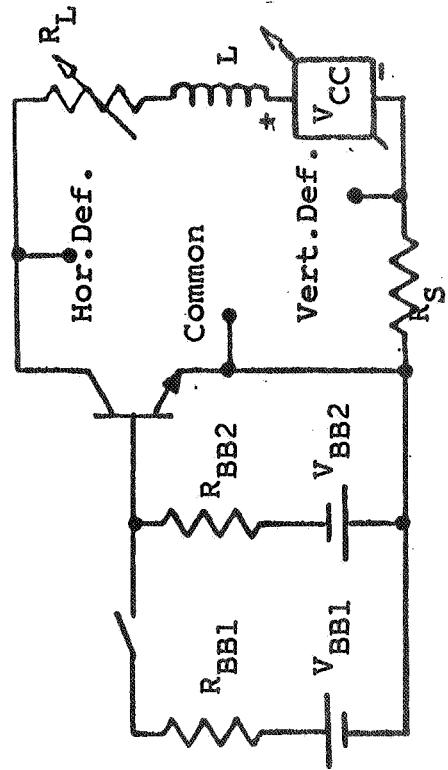
SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1



SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

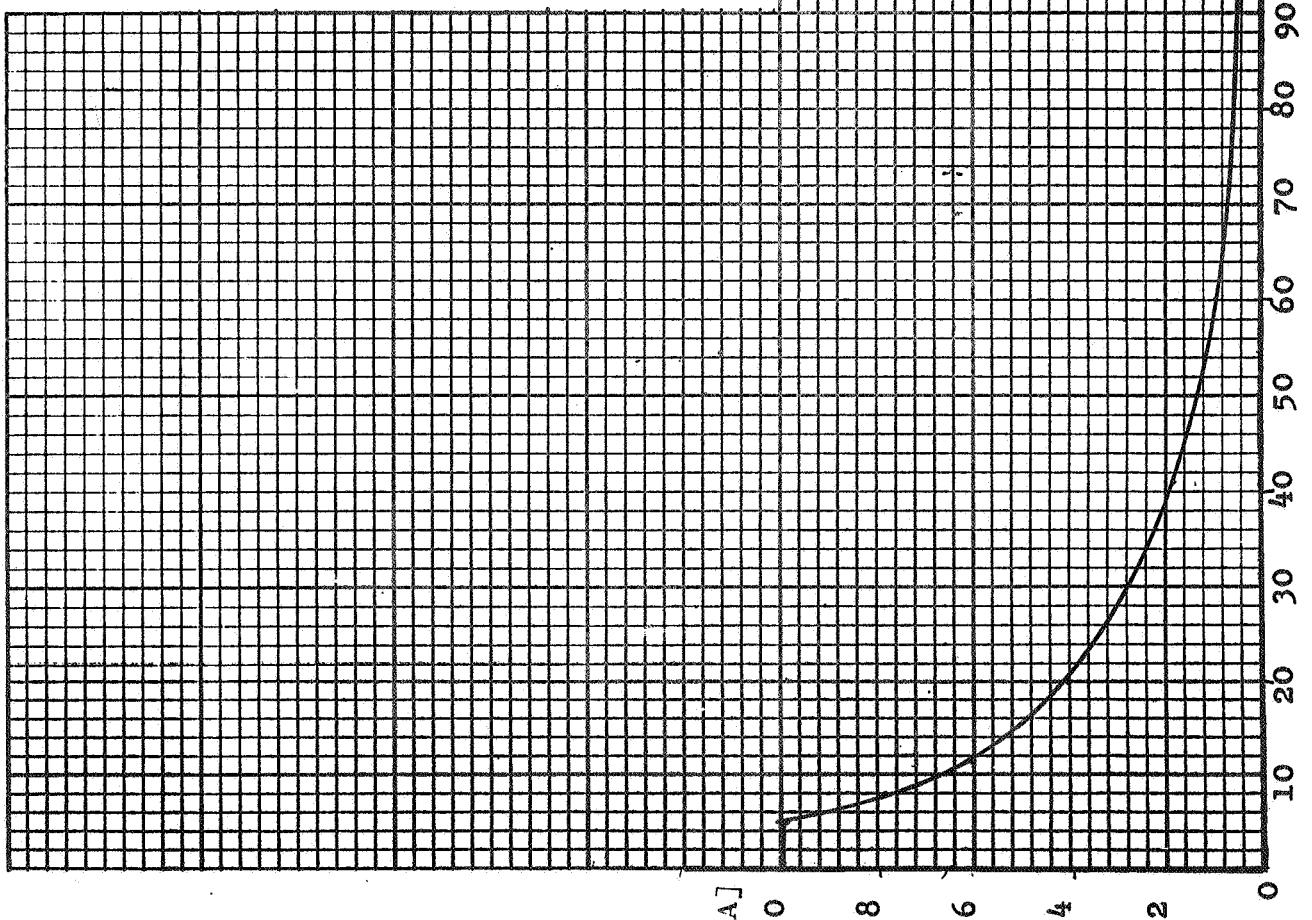
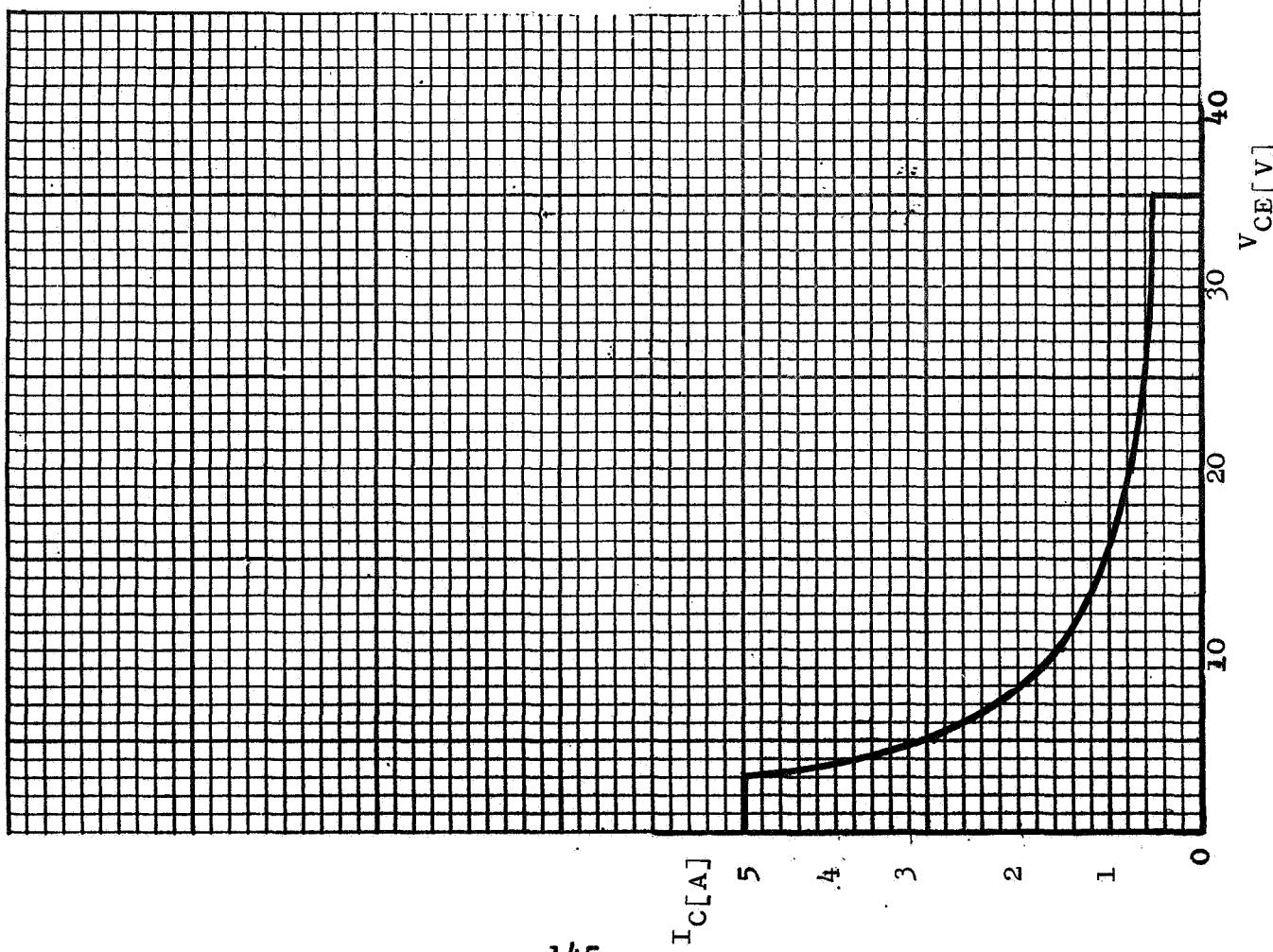
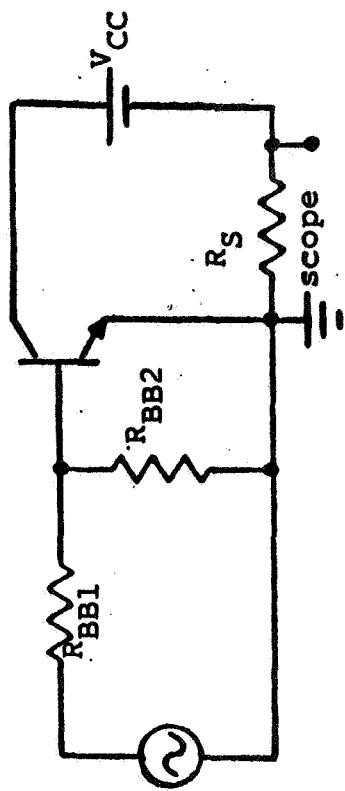


Figure 5

SHORTED CLASS B SOAR



-- TEST REPORT --

SILICON POWER TRANSISTOR  
< 2N5559 >

EXAMPLE DEVICE SPECIFICATIONS

-- Manufacturer Bendix --

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

The format used in the presentation of this data  
was recently developed for the registration of  
transistor specifications.

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

## JOINT ELECTRON DEVICE ENGINEERING COUNCIL REGISTRATION DATA - JS-6 'RDF1

Item	Registered Data	Test Methods & Test Conditions	Remarks
1.0.0	GENERAL DESCRIPTION		Triode Transistor, Power Switching
1.1.0	Type NPN		NPN, PNP, etc.
1.2.0	Material Silicon		Ge., Si., etc.
2.0.0	MECHANICAL DATA		Note 1
2.1.0	Outline TO-3		Note 2
2.2.0	Terminal Designation 1 Base 2 Emitter 3 [empty] case Collector		Indicate all un-connected terminals as "NC".
3.0.0	MAXIMUM RATINGS		Note 3
3.1.0	Temperature		
3.1.1	T <sub>stg</sub> (max) 200 °C	JS-6-T1.2	Test Methods JS-6-T see "Test Procedures for Verification of Maximum Ratings of Power Transistors". JEDEC Publication No. 65
	T <sub>stg</sub> (min) -65 °C	JS-6-T1.1	
3.1.2	T <sub>J(max)</sub> 200 °C	JS-6-T2	
	T <sub>C</sub> 150 °C		T <sub>C</sub> = 75% to 90% T <sub>J</sub> Max
	V <sub>CB</sub> ≈ 20 V	I <sub>C</sub> 2.5 A	
3.1.3	T (Lead) 235 °C	Distance from case 1/32 in. Time 10 s	Item 3.1.3 is not required on transistors whose storage temperature is sufficiently high so that the lead temperature test becomes redundant.

Item	Registered Data	Test Methods & Test Conditions	Remarks	
3.2.0	Voltage	$T_C = 25^\circ C$		
3.2.1	$V_{CBO}$	150 V	JS-6-T3	
3.2.2	$V_{EBO}$	7 V	JS-6-T4	
3.2.3	$V_{CEX}$	120 V	<p>JS-6-T5.1</p> <p><math>I_C (V_{CE} = V_{CEX})</math> 10 A</p> <p><math>V_{CC}</math> 120 V <math>R_L</math> 10 <math>\Omega</math></p> <p>L 1 mH CR 1N1204</p> <p><math>V_{BB1}</math> 6.2 V <math>R_{BB1}</math> 3 <math>\Omega</math></p> <p><math>V_{BB2}</math> 0 V <math>R_{BB2}</math> 5 <math>\Omega</math></p> <p>Pulse Width 1 ms Duty Cycle 2 %</p> <p>or</p>	<p>Inductive Method</p> <p><math>R_{BB2}</math> may be infinite</p> <p><math>V_{BB2}</math> may be zero</p> <p>Equivalent registered type number of CR, if used, must be given.</p>
		JS-6-T5.2	Pulsed Method	
		$I_C$ A $R_{BB}$ $\Omega$	$R_{BB}$ may be zero	
		$V_{BB(off)}$ V		
		Pulse Width ms Duty Cycle %		

Item	Registered Data	Test Methods & Test Conditions	Remarks
3.3.0	Current		
3.3.1	$I_C$ <span style="border: 1px solid black; padding: 2px;">10 A</span>	JS-6-T6  $I_B$ <span style="border: 1px solid black; padding: 2px;">2 A</span> $T_C \leq 25^\circ C$	Continuous collector current
3.3.2	$I_{CM}$ <span style="border: 1px solid black; padding: 2px;">15 A</span>	JS-6-T7  $T_C = 25^\circ C$ $R_S$ <span style="border: 1px solid black; padding: 2px;">0.1 Ω</span>  $V_{BB}$ <span style="border: 1px solid black; padding: 2px;">0 V</span> $R_{BB}$ <span style="border: 1px solid black; padding: 2px;">∞ Ω</span>	Peak collector current
		<u>Input Pulse Characteristics</u>  Pulse Amplitude <span style="border: 1px solid black; padding: 2px;">5A</span>  Pulse Width <span style="border: 1px solid black; padding: 2px;">1000 ms</span>  Duty Cycle <span style="border: 1px solid black; padding: 2px;">1 %</span>  $t_r \leq 5 \mu s$ $t_f \leq 5 \mu s$	
3.3.3	$I_B$ <span style="border: 1px solid black; padding: 2px;">5 A</span>	JS-6-T8  $T_C \leq 25^\circ C$	Continuous base current
3.3.4	$I_{BM}$ <span style="border: 1px solid black; padding: 2px;">7 A</span>	JS-6-T9  $T_C = 25^\circ C$  <u>Input Pulse Characteristics</u>  Pulse Width <span style="border: 1px solid black; padding: 2px;">1000 ms</span>  Duty Cycle <span style="border: 1px solid black; padding: 2px;">10 %</span>  $t_r \leq 5 \mu s$ $t_f \leq 5 \mu s$	Peak base current
3.3.5	$I_E$ <span style="border: 1px solid black; padding: 2px;">12 A</span>	JS-6-T10  $I_B$ <span style="border: 1px solid black; padding: 2px;">2 A</span> $T_C$ <span style="border: 1px solid black; padding: 2px;">25^\circ C</span>	Continuous Emitter current

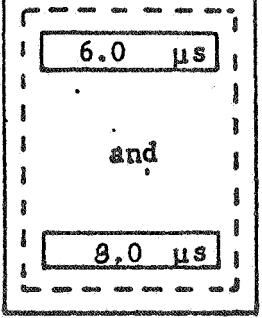
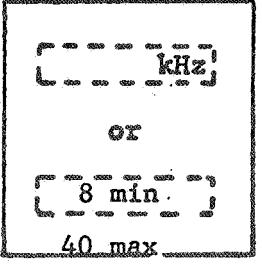
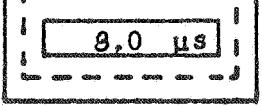
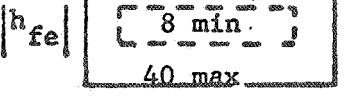
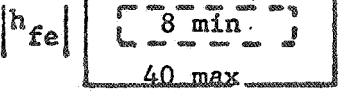
Item	Registered Data	Test Methods & Test Conditions	Remarks
3.3.6	$I_{EM}$ [---- A]	<p>JS-6-T11</p> <p><math>T_C = 25^\circ C</math>      <math>R_S</math> [ ] <math>\Omega</math></p> <p><math>V_{BB}</math> [ ] V      <math>R_{BB}</math> [ ] <math>\Omega</math></p> <p><u>Input Pulse Characteristics</u></p> <p>Pulse Width [ ] ms</p> <p>Duty Cycle [ ] %</p> <p><math>t_r \leq</math> [ ] <math>\mu s</math>      <math>t_f \leq</math> [ ] <math>\mu s</math></p>	Peak Emitter Current
3.4.0	Power		
3.4.1	$P_T$ [ ] 100 W	<p>JS-6-T12</p> <p><math>T_C</math> [ ] 100 <math>^\circ C</math></p> <p><math>V_{CB}</math> [ ] 50 V      <math>I_C</math> [ ] 2 A</p>	$T_C = 55^\circ C$ (for device with $T_J$ (max) $\leq 125^\circ C$ )
3.4.2	$P_{TM}$ [ ] 900 W	<p>JS-6-T13</p> <p><math>T_C = 25^\circ C</math></p> <p><math>V_{CC}</math> [ ] 90 V</p> <p><math>V_{BB}</math> [ ] 0 V      <math>R_{BB}</math> [ ] 5 <math>\Omega</math></p> <p><u>Input Pulse Characteristics</u></p> <p>Pulse Width [ ] 0.25 ms</p> <p>Duty Cycle [ ] 1 %</p> <p><math>t_r \leq</math> [ ] 5 <math>\mu s</math>      <math>t_f \leq</math> [ ] 5 <math>\mu s</math></p>	$T_C = 100^\circ C$ (for devices with $T_J$ (max) $> 125^\circ C$ ) $P_{TM} = I_C V_{CC}$

Item	Registered Data	Test Methods & Test Conditions	Remarks
3.5.0	Maximum Operating Conditions		Refer to Appendix A
3.5.1	DC - Attach drawing of operating area $V_{CE}$ vs $I_C$	$T_C = 100^\circ C$ Fig. 1 1. $I_C = 0.5A$ ; $V_{CE} = 80V$ 2. $I_C = 2A$ ; $V_{CE} = 50V$	$T_C = T_C$ (3.4.1) The circuit of JS-6-T12 is recommended.
3.5.2	Pulsed (Forward Bias Drive) Attach drawing of operating area. $V_{CE}$ vs $I_C$ for one or more pulse widths	JS-6-T14, $T_C = 25^\circ C$ ; Fig. 2  $V_{BB} = 0 V$ $R_{BB} = 5 \Omega$  <u>Input Pulse Characteristics</u> Pulse Width _____ ms Duty Cycle _____ % $t_r = \leq 5 \mu s$ $t_f = \leq 5 \mu s$	Pulse width shall be 1, 2, 3, or $5 \times 10^x$ sec.
3.6.0	Maximum Operating Conditions for Switching between Saturation and Cutoff		For example refer to Appendix B Specify 3.6.1 or 3.6.2 or 3.6.3
3.6.1	Resistive Load	JS-6-T5.1 with $L = 0$ and CR disconnected $T_C = 25^\circ C$ ; Fig. 3  <u>Input Pulse Characteristics</u> Pulse Width 1 ms Duty Cycle 2 % $t_r = \leq 5 \mu s$ $t_f = \leq 5 \mu s$ $R_{BB1} = 3 \Omega$ $R_{BB2} = 5 \Omega$ $V_{BB1} = 6.2 V$ $V_{BB2} = 0 V$	Supply graph of Safe Operating Area on the $I_C$ - $V_{CE}$ plane. Safe Operating Area graph must include: $V_{CE}$ (3.2.3) $I_C$ (3.3.1)  If one test condition cannot satisfy $V_{CE}$ (3.2.3) and $I_C$ (3.3.1) specify conditions for each test.

Item	Registered Data	Test Methods & Test Conditions	Remarks
3.6.2	<p>Clamped Inductive Load</p> <p>OR</p>	<p>JS-6-T5.1</p> <p><math>T_C = 25^{\circ}\text{C}</math> Fig. 4</p> <p><u>Input Pulse Characteristics</u></p> <p>Pulse Width <math>1 \text{ ms}</math></p> <p>Duty Cycle <math>2 \%</math></p> <p><math>t_r \leq 5 \mu\text{s}</math> <math>t_f \leq 5 \mu\text{s}</math></p> <p><math>R_{BB1} 3 \Omega</math></p> <p><math>R_{BB2} 5 \Omega</math></p> <p><math>V_{BB1} 6.2 \text{ V}</math></p> <p><math>V_{BB2} 0 \text{ V}</math></p> <p><math>L 1 \text{ mH}</math></p> <p><small>JEDEC CR 1N1204 The/Type Number of the characteristics must be specified.</small></p>	<p>Supply graph of Safe Operating Area on the <math>I_C</math>-<math>V_{CE}</math> plane. Safe Operating Area graph must include:</p> <p><math>V_{CE}</math> (3.2.3)</p> <p><math>I_C</math> (3.3.1).</p> <p>If one test condition cannot satisfy <math>V_{CE}</math> (3.2.3) and <math>I_C</math> (3.3.1) specify conditions for each test.</p>
3.6.3	<p>Unclamped Inductive Load</p>	<p>JS-6-T5.1 and CR Disconnected</p> <p><math>T_C = 25^{\circ}\text{C}</math> Fig. 5</p> <p><u>Input Pulse Characteristics</u></p> <p>Pulse Width <math>20 \text{ ms}</math></p> <p>Duty Cycle <math>30 \%</math></p> <p><math>t_r \leq 5 \mu\text{s}</math> <math>t_f \leq 5 \mu\text{s}</math></p> <p><math>R_{BB1} 3 \Omega</math></p> <p><math>R_{BB2} 5 \Omega</math></p> <p><math>V_{BB1} 9.2 \text{ V}</math></p> <p><math>V_{BB2} 5 \text{ V}</math></p> <p><math>L 40 \text{ mH}</math></p> <p><math>Q \text{ of } L \geq 1500 @ f = 1 \text{ MHz}</math></p> <p><math>f_{\text{RESON}} \text{ of } L \geq 8 \text{ M Hz}</math></p> <p><math>I_C 4.0 \text{ A}</math></p> <p><math>V_{CC} 22 \text{ V}</math></p>	<p>For <math>L = 6.4 \text{ mH}; I_C = 10 \text{ A}</math></p> <p><math>I_C \geq I_C</math> (4.1.7)</p>

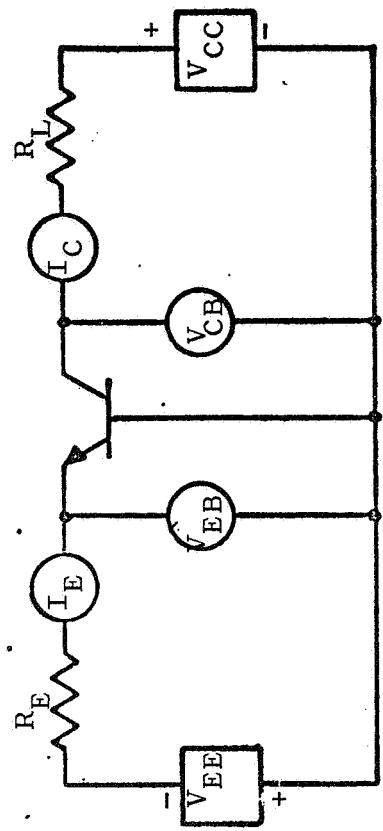
Item	Registered Data	Test Methods & Test Conditions	Remarks
4.0.0	Electrical Characteristics	$T_C = 25^\circ C$ (unless otherwise noted)	Maximum limits unless otherwise noted.
4.1.0	Static		Note 4
4.1.1	$I_{CEV}$ <span style="border: 1px solid black; padding: 2px;">2 mA</span>	$T_C$ <span style="border: 1px solid black; padding: 2px;">150 °C</span> $V_{CE}$ <span style="border: 1px solid black; padding: 2px;">150 V</span> $V_{BE}$ (fwd., rev.) <span style="border: 1px solid black; padding: 2px;">0 V</span> Technique <span style="border: 1px solid black; padding: 2px;">C.T.</span>	$T_C \geq 1/2 T_J$ (3.1.2)
4.1.2	$I_{CEV}$ <span style="border: 1px solid black; padding: 2px;">0.5 mA</span>  or  $I_{CBO}$ <span style="border: 1px solid black; padding: 2px;">---- mA</span>	$V_{CE}$ <span style="border: 1px solid black; padding: 2px;">150 V</span> $V_{BE}$ (fwd., rev.) <span style="border: 1px solid black; padding: 2px;">0 V</span> Technique <span style="border: 1px solid black; padding: 2px;">C.T.</span> or	$V_{CE} \geq 0.9 V_{CBO}$ (3.2.1) Specify 4.1.2 or 4.1.3 and 4.1.4
4.1.3	and	$V_{CB}$ <span style="border: 1px solid black; padding: 2px;">---- V</span> and	$V_{CB} = V_{CBO}$ (3.2.1)
4.1.4	$V_{EBF}$ <span style="border: 1px solid black; padding: 2px;">---- V</span>	$V_{CB}$ <span style="border: 1px solid black; padding: 2px;">---- V</span> Technique <span style="border: 1px solid black; padding: 2px;"></span>	$V_{CB} = V_{CBO}$ (3.2.1)

Item	Registered Data	Test Methods & Test Conditions	Remarks
4.1.5	$I_{EBO}$ <span style="border: 1px solid black; padding: 2px;">0.01 mA</span>	$V_{EB}$ <span style="border: 1px solid black; padding: 2px;">7 V</span> Technique <span style="border: 1px solid black; padding: 2px;">C.T.</span>	$V_{EB} = V_{EBO}$ (3.2.2)
4.1.6	$V_{(BR)CEO}$ <span style="border: 1px solid black; padding: 2px;">100 Min V</span>	$I_C$ <span style="border: 1px solid black; padding: 2px;">0.2 A</span> $I_B$ <span style="border: 1px solid black; padding: 2px;">0 mA</span> Technique <span style="border: 1px solid black; padding: 2px;">C.T.</span>	Note 5
4.1.7	$h_{FE}$ <span style="border: 1px solid black; padding: 2px;">20 Min</span> <span style="border: 1px solid black; padding: 2px;">60 Max</span>	$V_{CE}$ <span style="border: 1px solid black; padding: 2px;">2 V</span> $I_C$ <span style="border: 1px solid black; padding: 2px;">4 A</span> Technique <span style="border: 1px solid black; padding: 2px;">C.T.</span>	$V_{CE} \leq 2.0V$ or $2 \times V_{CE(sat)}$ (4.1.8) whichever is greater
4.1.8	$V_{CE(sat)}$ <span style="border: 1px solid black; padding: 2px;">0.75 Max V</span>	$I_C$ <span style="border: 1px solid black; padding: 2px;">4 A</span> $I_B$ <span style="border: 1px solid black; padding: 2px;">0.4 A</span> Technique <span style="border: 1px solid black; padding: 2px;">C.T.</span>	$I_C = I_C$ (4.1.7) Measured 0.064 inches from case.
4.1.9	$V_{BE(sat)}$ <span style="border: 1px solid black; padding: 2px;">1.5 Max V</span>	$I_C$ <span style="border: 1px solid black; padding: 2px;">4 A</span> $I_B$ <span style="border: 1px solid black; padding: 2px;">0.4 A</span> Technique <span style="border: 1px solid black; padding: 2px;">C.T.</span>	$I_C = I_C$ (4.1.7) Measured 0.064 inches from case.
4.2.0	Dynamic		
4.2.1	$t_x$ <span style="border: 1px solid black; padding: 2px;">μs</span>	$V_{CC}$ <span style="border: 1px solid black; padding: 2px;"> </span> $I_C$ <span style="border: 1px solid black; padding: 2px;"> </span> $I_{B1}$ <span style="border: 1px solid black; padding: 2px;"> </span>	Specify 4.2.1, 4.2.2 and 4.2.3 or 4.2.4 and 4.2.5 $I_C = I_C$ (4.1.7) Switching circuit shall be attached. $I_{B1} = I_B$ (4.1.8)
4.2.2	$t_s$ <span style="border: 1px solid black; padding: 2px;">μs</span>	$V_{CC}$ <span style="border: 1px solid black; padding: 2px;"> </span> $I_C$ <span style="border: 1px solid black; padding: 2px;"> </span> $I_{B1}$ <span style="border: 1px solid black; padding: 2px;"> </span> $I_{B2}$ <span style="border: 1px solid black; padding: 2px;"> </span>	$I_C = I_C$ (4.1.7) $I_{B1} = I_B$ (4.1.8)
4.2.3	$t_f$ <span style="border: 1px solid black; padding: 2px;">μs</span> or	$V_{CC}$ <span style="border: 1px solid black; padding: 2px;"> </span> $I_C$ <span style="border: 1px solid black; padding: 2px;"> </span> $I_{B1}$ <span style="border: 1px solid black; padding: 2px;"> </span> $I_{B2}$ <span style="border: 1px solid black; padding: 2px;"> </span>	$I_C = I_C$ (4.1.7) $I_{B1} = I_B$ (4.1.8)

Item	Registered Data	Test Methods & Test Conditions	Remarks
4.2.4	$t_{on}$  and 	$V_{CC} \boxed{31V}$ $I_C \boxed{4A}$ Fig. 6 $I_{B1} \boxed{0.4A}$	$I_C = I_{C1}$ (4.1.7) $I_{B1} = I_B$ (4.1.8)
4.2.5	$t_{off}$ 	$V_{CC} \boxed{31V}$ $I_C \boxed{4A}$ $I_{B1} \boxed{0.4A}$ $I_{B2} \boxed{-0.4A}$	$I_C = I_{C1}$ (4.1.7) $I_{B1} = I_B$ (4.1.8)
4.2.6	$f_{hfe}$  or 	$I_C \boxed{A}$ $V_{CE} \boxed{V}$	Specify 4.2.6 or 4.2.7
4.2.7	$ h_{fe} $ 	$V_{CE} \boxed{4 V}$ $I_C \boxed{1 A}$ $f \boxed{0.1 MHz}$	Specify 4.2.6 or 4.2.7  Note 6
<u>ADDITIONAL DATA</u>			
3.6.4	Shorted Class B Safe Operating Area	Fig. 7 $I_{Cpeak} = 1A$ $R_S = 0.1\Omega$ ; $V_{CC} = 80V$ Input Characteristics $R_{BB1} = 1\Omega$ ; $R_{BB2} = 3\Omega$ $f = 20$ Hz; $T_C = 100^\circ C$	
3.6.5	$P_T = 120W$	JS-6-T12; $V_{CE} = 60V$ ; $I_C = 2A$ $t_p = 1s$ ; $T_A = 25^\circ C$	Single Pulse
3.6.6	$P_T = 120W$	JS-6-T12; $V_{CE} = 8V$ ; $I_C = 15A$ $t_p = 1s$ ; $T_A = 25^\circ C$	Single Pulse
4.1.10	$I_{CEO} = 100 \mu A$ max.	$V_{CE} = 80V$ , Technique C.T.	
4.1.11	$V_{CES} = 125V$ min.	$I_C = 10 mA$ ; $R_{CC} = 5K \Omega$ Technique C.T.	
4.1.12	$V_{EBO} = 7V$ min.	$I_E = 10 mA$ ; $R_{BB} = 5K \Omega$ Technique C.T.	
4.1.13	$h_{FE} = 40$ min.	$I_C = 0.1A$ ; $V_{CE} = 2V$ ; Technique C.T.	
4.1.14	$V_{CE(sat)} = 1.2V$ max.	$I_C = 10A$ ; $I_B = 1A$ ;   Technique C.T.	
4.1.15	$V_{BE(sat)} = 2.0V$ max.	$I_C = 10A$ ; $I_B = 1A$ ;   Technique C.T.	
4.1.16	$V_{BE} = 1.4V$ max.	$I_C = 4A$ ; $V_{CE} = 2V$ ;   Technique C.T.	
			Measured 0.064 inches from case
17658: 8a-10		155.	

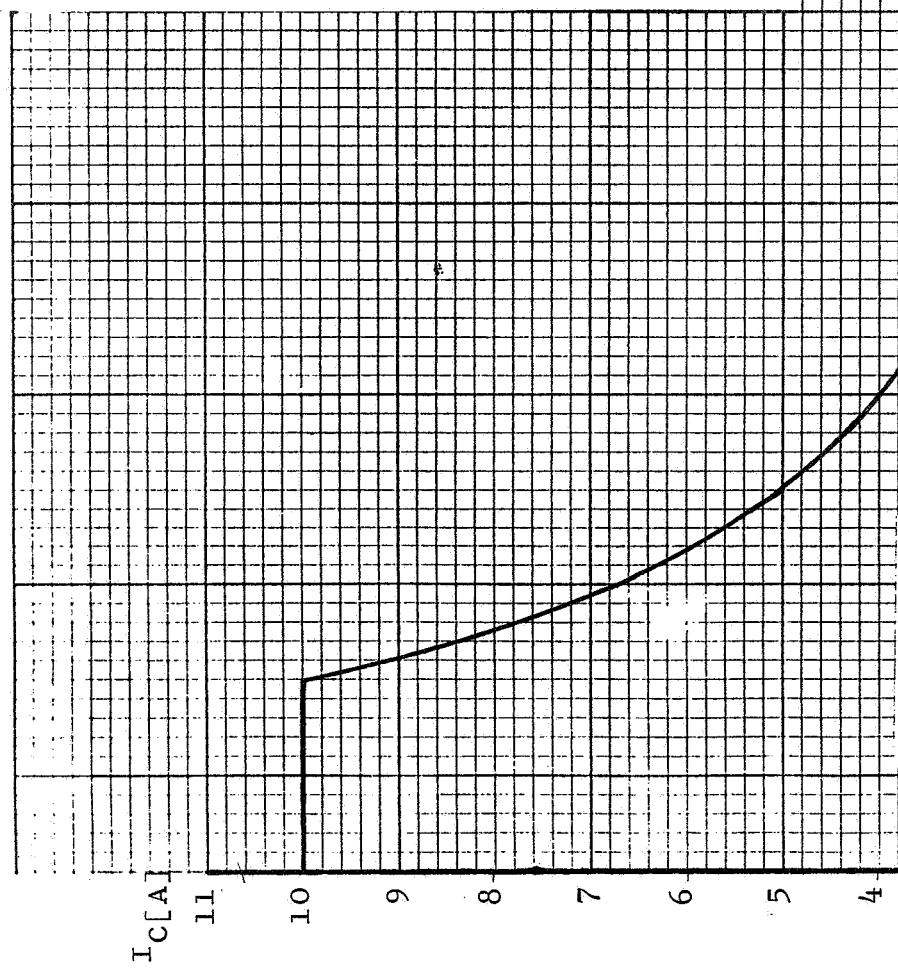
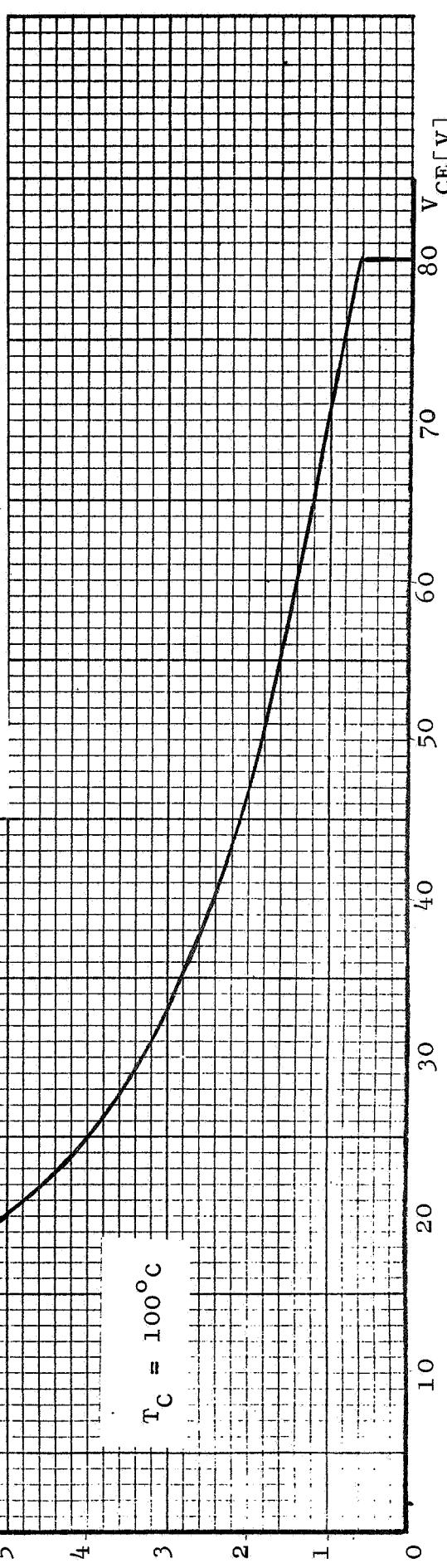
Item	Registered Data	Test Methods & Test Conditions	Remarks
4.1.17	$V_{BE} = 0.55$ V min. $V_{BE} = 0.65$ V max.	$I_C = 0.1A$ ; $V_{CE} = 2V$ ; Technique C.T.	Measured 0.064" from case
4.1.18	$h_{FE} = 40$ min.	$I_C = 0.5A$ ; $V_{CE} = 2V$ ; Technique C.T.	
4.1.19	$h_{FE} = 15$ min.	$I_C = 4A$ , $V_{CE} = 2V$ ; Technique C.T. $T_C = -55^{\circ}\text{C}$	
4.1.20	$C_{obo} = 400$ pF max.	$V_{CB} = 10V$ ; $f = 1$ MHz	
4.3.0	$\theta_{JC} = 1^{\circ}\text{C/W}$ max.	$I_C = 1A$ ; $V_{CE} = 20V$	
4.3.1	$\theta_{JA} = 25^{\circ}\text{C/W}$ max.	$I_C = 1A$ ; $V_{CE} = 2V$	
4.3.2	$\tau_J = 15$ ms	$I_C = 1A$ ; $V_{CE} = 20V$	Time to reach 63% of equilibrium temperature for $P_T$ step input.

FORWARD BIASED CONTINUOUS SOAR



Conditions:  $T_C \leq 100^\circ\text{C}$ ,  $I_C \geq I_{CEO}$

Test Circuit: JS-6-T12



$T_C = 100^\circ\text{C}$

PULSED OPERATION - FORWARD BIASED PULSED SOAR

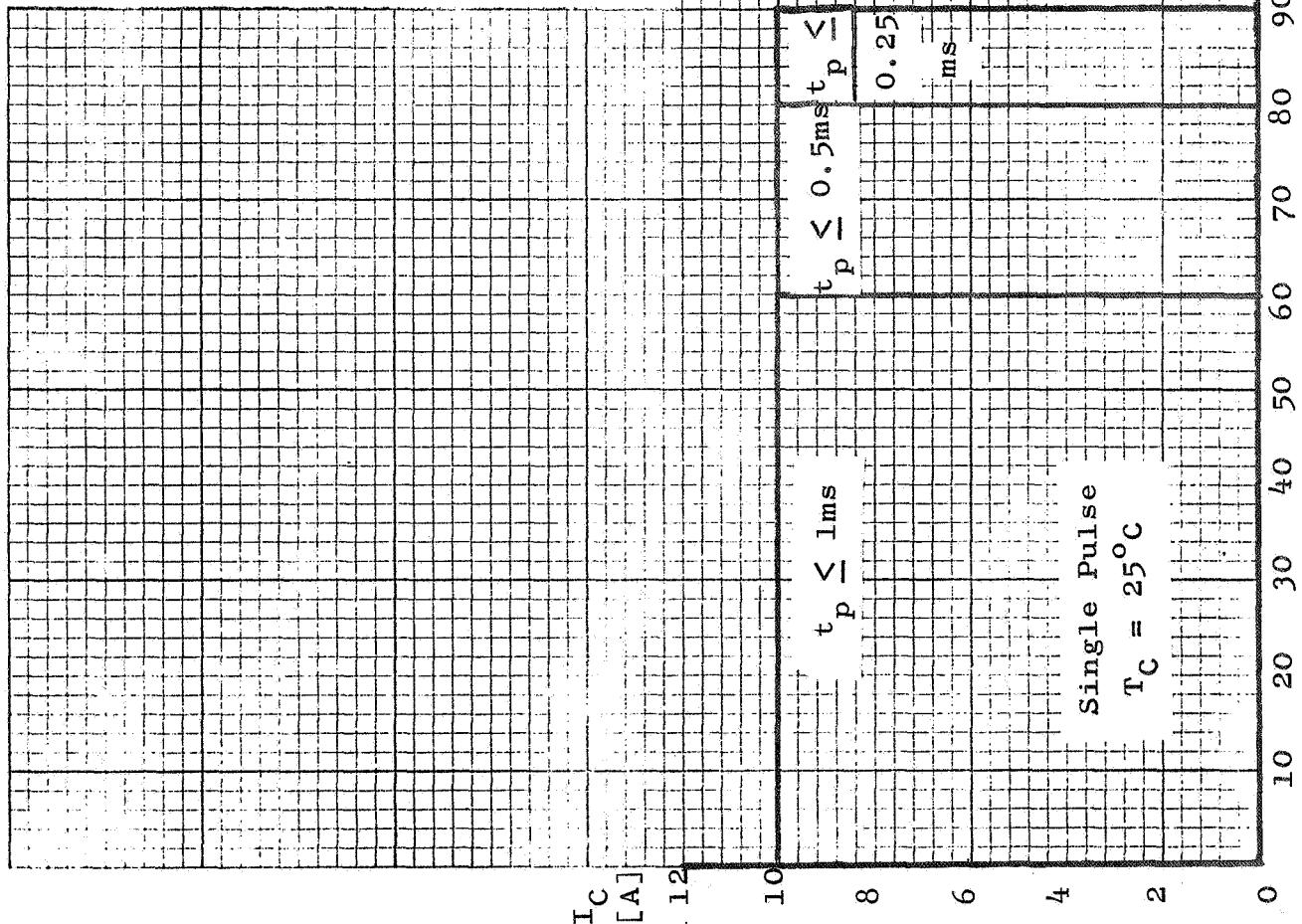
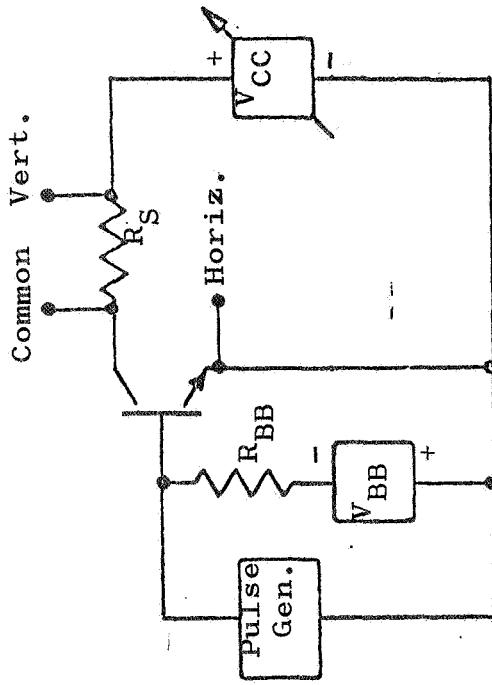
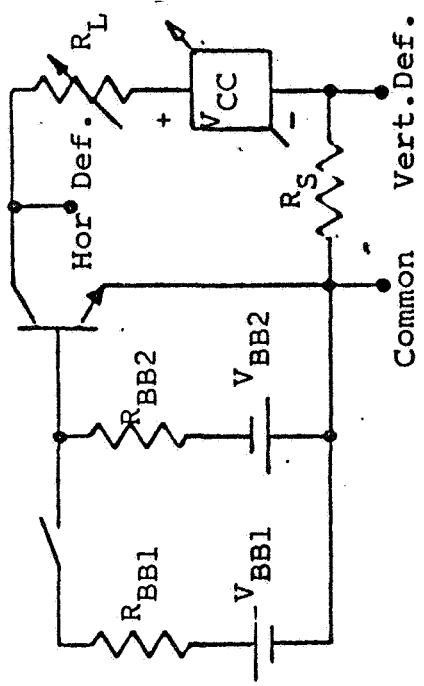
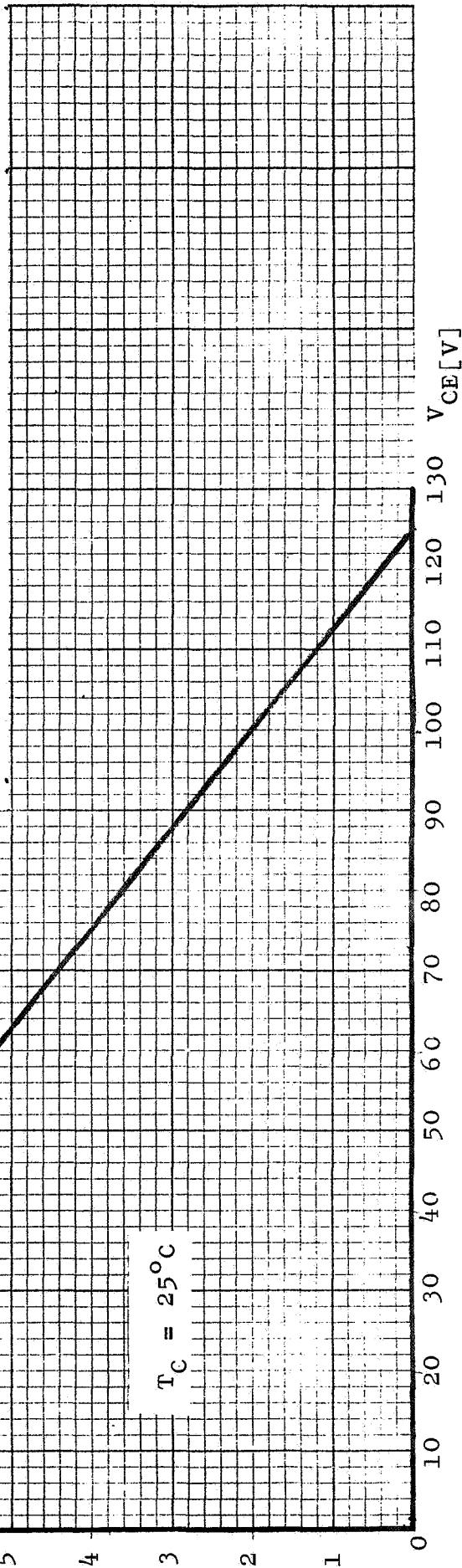


Figure 2

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-RESISTIVE LOAD

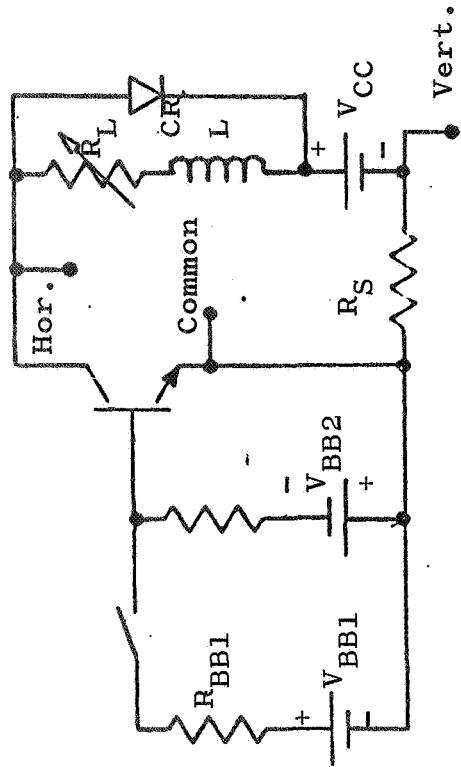


Test Circuit: JS-6-T5.2.1

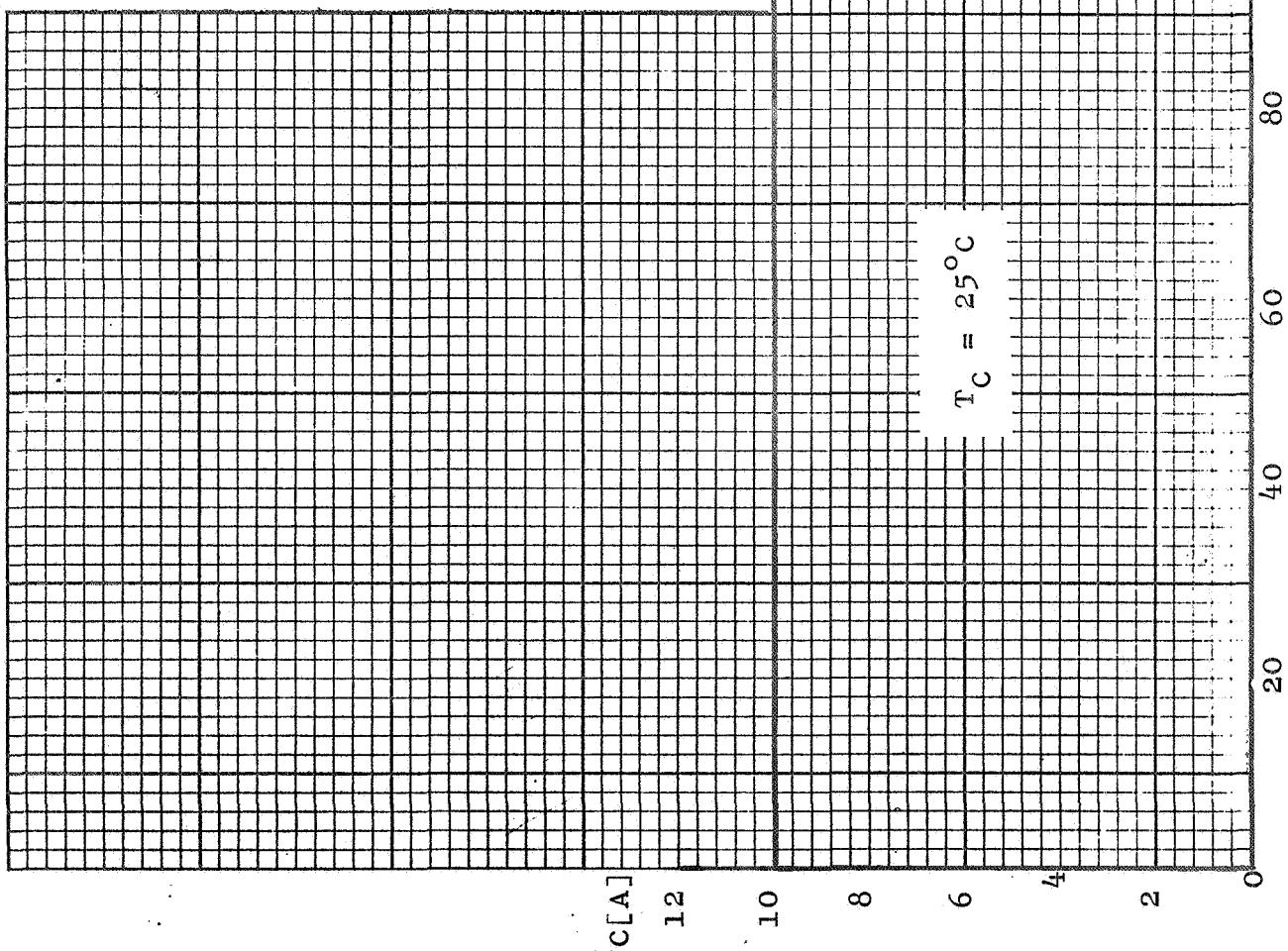


$I_C$   
[A]

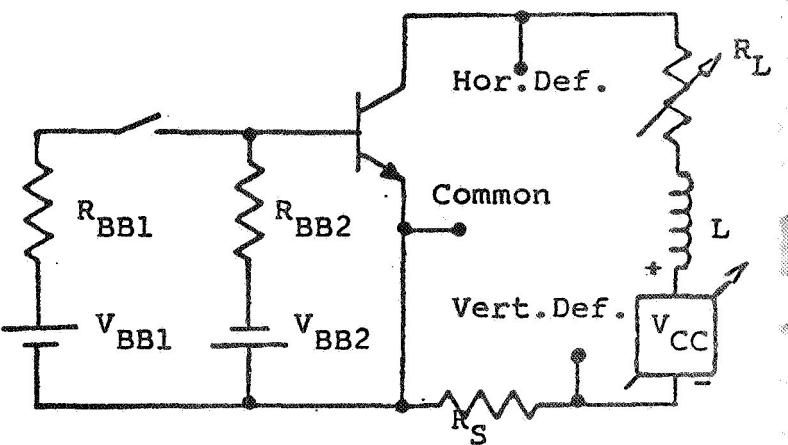
SOAR FOR SWITCHING BETWEEN SATURATION &  
CUTOFF - CLAMPED INDUCTIVE LOAD



Test Circuit JS-6-T5.1



SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

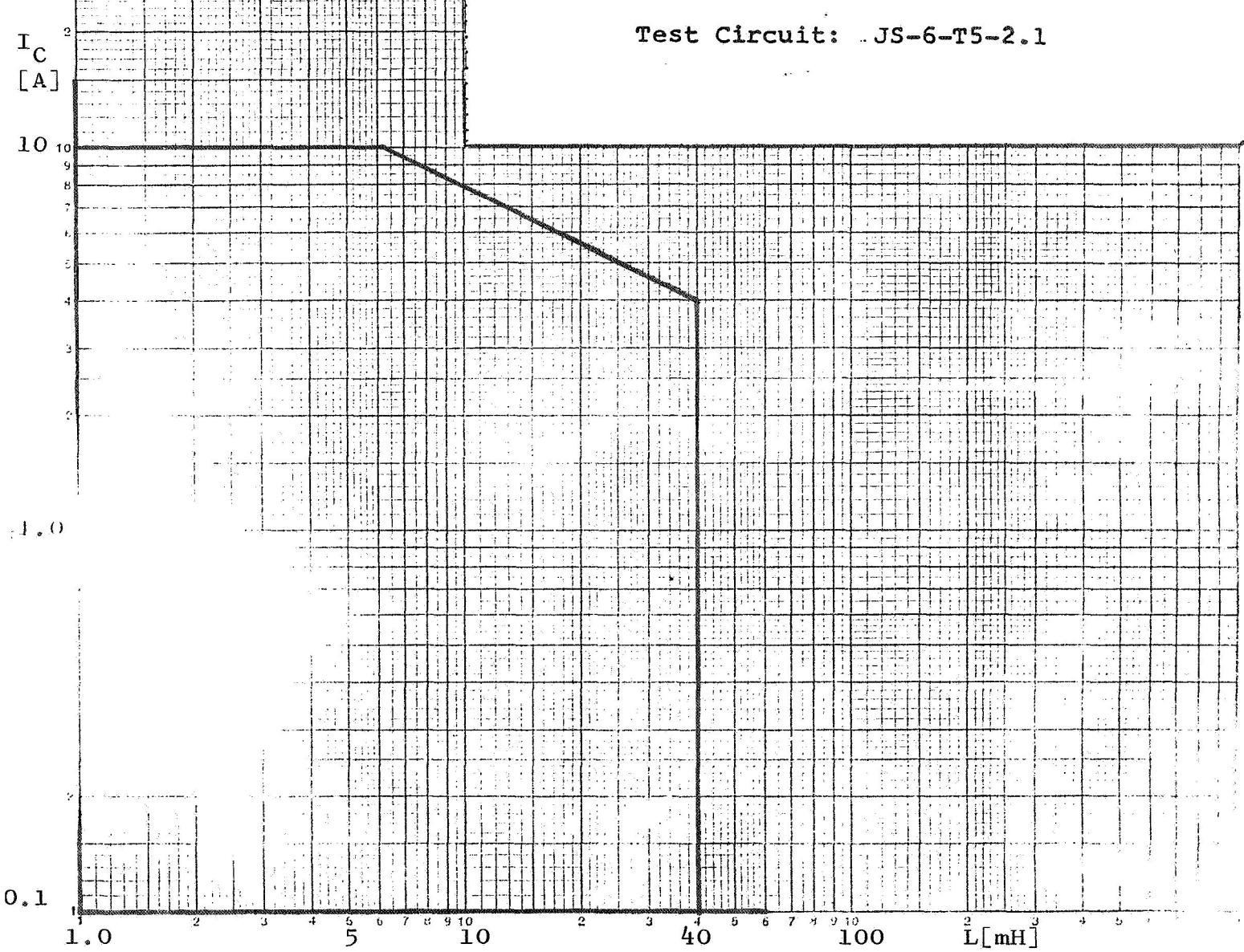
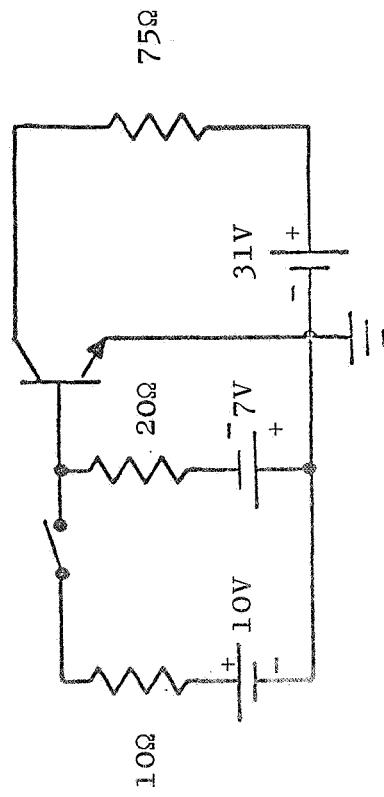
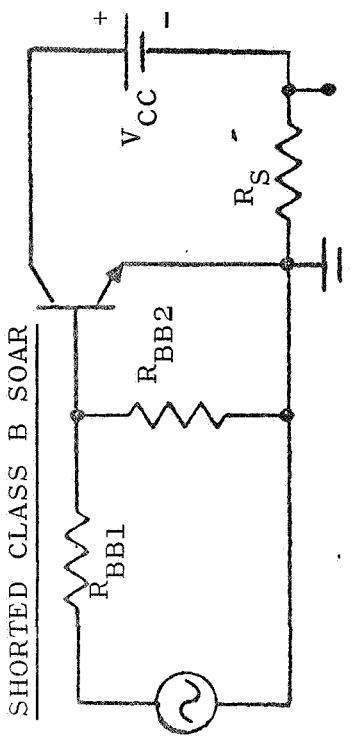


Figure 5

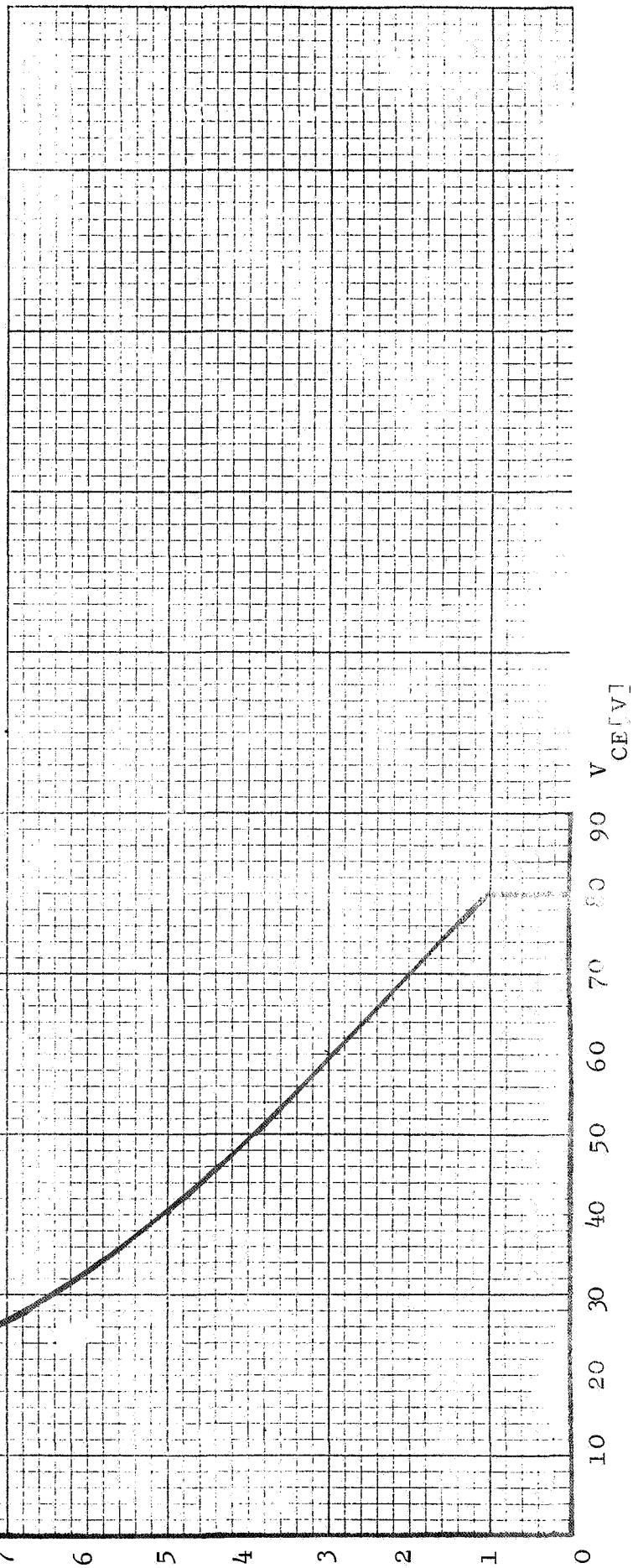
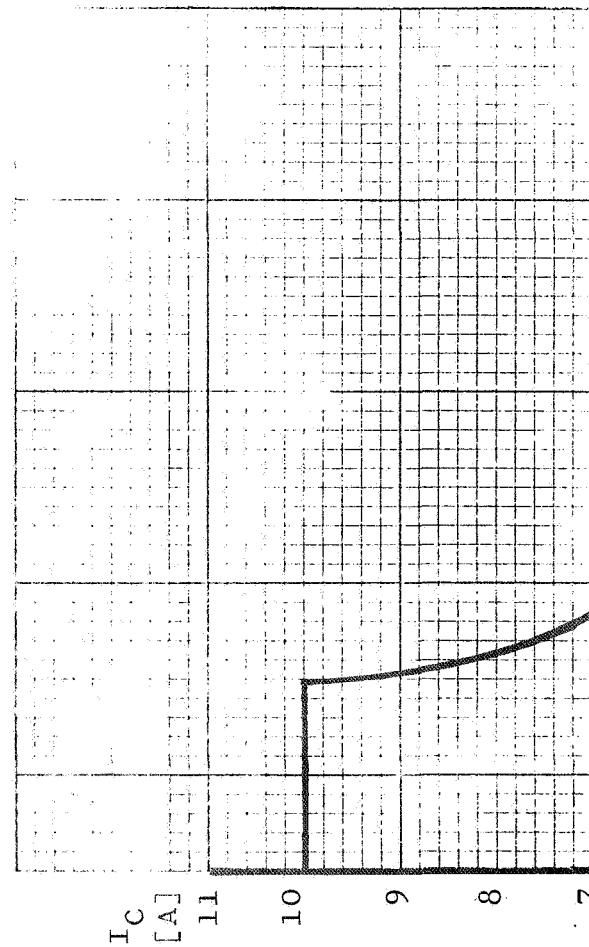
Figure 6

SWITCHING TEST CIRCUIT





Test Circuit:  $T_C \leq 100^{\circ}\text{C}$ ,  
 $f \geq 20\text{Hz}$



--- TEST REPORT ---

SILICON POWER TRANSISTOR  
< 2N5560 >

SAFE OPERATING AREA  
DETERMINATION FRO PREVENTION  
OF SECOND BREAKDOWN

--- Manufacturer Bendix ---

Performed for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION  
GEORGE C. MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA

Contract Number NAS8-21155

The format used in the presentation of this data  
was recently developed for the registration of  
transistor specifications.

THE BENDIX CORPORATION  
SEMICONDUCTOR DIVISION  
HOLMDEL, NEW JERSEY

## JOINT ELECTRON DEVICE ENGINEERING COUNCIL REGISTRATION DATA - JS-6-RDF-1

Item	Registered Data	Test Methods & Test Conditions	Remarks
1.0.0	GENERAL DESCRIPTION		Triode Transistor Power Switching
1.1.0	Type <span style="border: 1px solid black; padding: 2px;">NPN</span>		NPN, PNP, etc.
1.2.0	Material <span style="border: 1px solid black; padding: 2px;">Silicon</span>		Ge., Si., etc.
2.0.0	MECHANICAL DATA		Note 1
2.1.0	Outline <span style="border: 1px solid black; padding: 2px;">TO-63</span>		Note 2
2.2.0	Terminal Designation		Indicate all un-connected terminals as "NC".
	1 <span style="border: 1px solid black; padding: 2px;">Emitter</span>		
	2 <span style="border: 1px solid black; padding: 2px;">Base</span>		
	3 <span style="border: 1px solid black; padding: 2px;">Collector</span>		
	case <span style="border: 1px solid black; padding: 2px;">Collector</span>		Indicate "I" if all leads insulated from case.
3.0.0	MAXIMUM RATINGS		Note 3
3.1.0	Temperature		
3.1.1	T <sub>stg</sub> (max) <span style="border: 1px solid black; padding: 2px;">200 °C</span>	JS-6-T1.2	Test Methods JS-6-T — See "Test Procedures for Verification of Maximum Ratings of Power Transistors" JEDEC Publication No.65
	T <sub>stg</sub> (min) <span style="border: 1px solid black; padding: 2px;">-65 °C</span>	JS-6-T1.1	
3.1.2	T <sub>J(max)</sub> <span style="border: 1px solid black; padding: 2px;">200 °C</span>	JS-6-T2	
	T <sub>C</sub> <span style="border: 1px solid black; padding: 2px;">150 °C</span> P <sub>T</sub> = 75W		T <sub>C</sub> = 75% to 90% T <sub>J</sub> Max
	V <sub>CB</sub> <span style="border: 1px solid black; padding: 2px;">≈ 4 V</span> I <sub>C</sub> <span style="border: 1px solid black; padding: 2px;">15 A</span>		
3.1.3	T (Lead) <span style="border: 1px solid black; padding: 2px;">230 °C</span>	Distance from case <span style="border: 1px solid black; padding: 2px;">1/16 in.</span> Time <span style="border: 1px solid black; padding: 2px;">10 s</span>	Item 3.1.3 is not required on transistors whose storage temperature is sufficiently high so that the lead temperature test becomes redundant.

Item	Registered Data	Test Methods & Test Conditions	Remarks
3.2.0	Voltage	$T_C = 25^\circ C$	
3.2.1	$V_{CBO}$	175 V	JS-6-T3
3.2.2	$V_{EBO}$	8 V	JS-6-T4
3.2.3	$V_{CEX}$	<p>120 V</p> <p><math>I_C (V_{CE} = V_{CEX})</math></p> <p><math>V_{CC}</math> 120 V      <math>R_L</math> 3.8 Ω</p> <p>L 1 mH      CR 1N1202</p> <p><math>V_{BB1}</math> 12.2 V      <math>R_{BB1}</math> 3 Ω</p> <p><math>V_{BB2}</math> 6 V      <math>R_{BB2}</math> 20 Ω</p> <p>Pulse Width 1 ms      Duty Cycle 2 %</p> <p>OR</p> <p>JS-6-T5.2</p> <p><math>I_C</math> A      <math>R_{BB}</math> Ω</p> <p><math>V_{BB(\text{off})}</math> V</p> <p>Pulse Width ms      Duty Cycle %</p>	<p>Inductive Method</p> <p><math>R_{BB2}</math> may be infinite</p> <p><math>V_{BB2}</math> may be zero</p> <p>Equivalent registered type number of CR, if used, must be given.</p> <p>Pulsed Method</p> <p><math>R_{BB}</math> may be zero</p>

Item	Registered Data	Test Methods & Test Conditions	Remarks
3.3.0	Current		
3.3.1	$I_C$ <span style="border: 1px solid black; padding: 2px;">30 A</span>	JS-6-T6  $I_B$ <span style="border: 1px solid black; padding: 2px;">3 A</span> $T_C \leq 25^\circ C$	Continuous collector current
3.3.2	$I_{CM}$ <span style="border: 1px solid black; padding: 2px;">[ ] A</span>	JS-6-T7  $T_C = 25^\circ C$ $R_S$ <span style="border: 1px solid black; padding: 2px;">[ ] Ω</span>  $V_{BB}$ <span style="border: 1px solid black; padding: 2px;">[ ] V</span> $R_{DB}$ <span style="border: 1px solid black; padding: 2px;">[ ] Ω</span>  <u>Input Pulse Characteristics</u>  Pulse Amplitude <span style="border: 1px solid black; padding: 2px;">[ ] V</span> Pulse Width <span style="border: 1px solid black; padding: 2px;">[ ] ms</span> Duty Cycle <span style="border: 1px solid black; padding: 2px;">[ ] %</span> $t_r \leq$ <span style="border: 1px solid black; padding: 2px;">[ ] μs</span> $t_f \leq$ <span style="border: 1px solid black; padding: 2px;">[ ] μs</span>	Peak collector current
3.3.3	$I_B$ <span style="border: 1px solid black; padding: 2px;">10 A</span>	JS-6-T8  $T_C \leq 25^\circ C$	Continuous base current
3.3.4	$I_{BM}$ <span style="border: 1px solid black; padding: 2px;">[ ] A</span>	JS-6-T9  $T_C = 25^\circ C$  <u>Input Pulse Characteristics</u>  Pulse Width <span style="border: 1px solid black; padding: 2px;">[ ] ms</span> Duty Cycle <span style="border: 1px solid black; padding: 2px;">[ ] %</span> $t_r \leq$ <span style="border: 1px solid black; padding: 2px;">[ ] μs</span> $t_f \leq$ <span style="border: 1px solid black; padding: 2px;">[ ] μs</span>	Peak base current
3.3.5	$I_E$ <span style="border: 1px solid black; padding: 2px;">[ ] 33 A</span>	JS-6-T10  $I_B$ <span style="border: 1px solid black; padding: 2px;">3 A</span> $T_C = 25^\circ C$	Continuous Emitter current

Item	Registered Data	Test Methods & Test Conditions	Remarks
3.3.6	$I_{EM}$ [ ] A	JS-6-T11  $T_C = 25^\circ\text{C}$ $R_S$ [ ] $\Omega$  $V_{BB}$ [ ] V $R_{BB}$ [ ] $\Omega$  <u>Input Pulse Characteristics</u>  Pulse Width [ ] ms  Duty Cycle [ ] %  $t_r \leq$ [ ] $\mu\text{s}$ $t_f \leq$ [ ] $\mu\text{s}$	Peak Emitter Current
3.4.0	Power		
3.4.1	$P_T$ [ ] 150 W	JS-6-T12  $T_C$ [ ] $100^\circ\text{C}$  $V_{CB}$ [ ] 4 V $I_C$ [ ] 30 A	$T_C = 55^\circ\text{C}$ (for device with $T_J$ (max) $\leq 125^\circ\text{C}$ )
3.4.2	Derating Factor, [ ] 1.5 W/ $^\circ\text{C}$		$T_C = 100^\circ\text{C}$ (for devices with $T_J$ (max) $> 125^\circ\text{C}$ )
	$P_{TM}$ [ ] 3600 W	JS-6-T13  $T_C = 25^\circ\text{C}$  $V_{CC}$ [ ] 120 V  $V_{BB}$ [ ] 6 V $R_{BB}$ [ ] 20 $\Omega$  <u>Input Pulse Characteristics</u>  Pulse Width [ ] 0.125 ms  Duty Cycle [ ] 0.4 %  $t_r \leq$ [ ] 5 $\mu\text{s}$ $t_f \leq$ [ ] 5 $\mu\text{s}$	$P_{TM} = I_C \cdot V_{CC}$

Item	Registered Data	Test Methods & Test Conditions	Remarks														
3.5.0	Maximum Operating Conditions		Refer to Appendix A														
3.5.1	DC - Attach drawing of operating area $V_{CE}$ vs $I_C$	$T_C = 100^{\circ}\text{C}$ Fig. 1 1. $I_C = 130 \text{ mA}$ ; $V_{CE} = 120\text{V}$ 2. $I_C = 450 \text{ mA}$ ; $V_{CE} = 60\text{V}$	$T_C = T_C$ (3.4.1) The circuit of JS-6-T12 is recommended.														
3.5.2	Pulsed (Forward Bias Drive) Attach drawing of operating area. $V_{CE}$ vs $I_C$ for one or more pulse widths	JS-6-T14 ; Fig. 2 $T_C = 25^{\circ}\text{C}$ $V_{BB} = 6 \text{ V}$ $R_{BE} = 20 \Omega$ <p><u>Input Pulse Characteristics</u></p> <table> <tr> <th>Pulse Width</th> <td>ms</td> </tr> <tr> <th>Duty Cycle</th> <td>0.4 %</td> </tr> <tr> <th><math>t_r \leq 5 \mu\text{s}</math></th> <td><math>\leq 5 \mu\text{s}</math></td> </tr> </table>	Pulse Width	ms	Duty Cycle	0.4 %	$t_r \leq 5 \mu\text{s}$	$\leq 5 \mu\text{s}$	Pulse width shall be 1,2,3, or $5 \times 10^x$ sec.								
Pulse Width	ms																
Duty Cycle	0.4 %																
$t_r \leq 5 \mu\text{s}$	$\leq 5 \mu\text{s}$																
3.6.0	Maximum Operating Conditions for Switching between Saturation and Cutoff		For example refer to Appendix B Specify 3.6.1 or 3.6.2 or 3.6.3														
3.6.1	Resistive Load	JS-6-T5.1 with $L = 0$ and CR disconnected ; Fig. 3 $T_C = 25^{\circ}\text{C}$ <p><u>Input Pulse Characteristics</u></p> <table> <tr> <th>Pulse Width</th> <td>1 ms</td> </tr> <tr> <th>Duty Cycle</th> <td>2 %</td> </tr> <tr> <th><math>t_r \leq 5 \mu\text{s}</math></th> <td><math>t_f \leq 5 \mu\text{s}</math></td> </tr> <tr> <th><math>R_{BB1} = 3 \Omega</math></th> <td></td> </tr> <tr> <th><math>R_{BB2} = 20 \Omega</math></th> <td></td> </tr> <tr> <th><math>V_{BB1} = 12.2 \text{ V}</math></th> <td></td> </tr> <tr> <th><math>V_{BB2} = 6 \text{ V}</math></th> <td></td> </tr> </table>	Pulse Width	1 ms	Duty Cycle	2 %	$t_r \leq 5 \mu\text{s}$	$t_f \leq 5 \mu\text{s}$	$R_{BB1} = 3 \Omega$		$R_{BB2} = 20 \Omega$		$V_{BB1} = 12.2 \text{ V}$		$V_{BB2} = 6 \text{ V}$		Supply graph of Safe Operating Area on the $I_C - V_{CE}$ plane. Safe Operating Area graph must include: $V_{CE}$ (3.2.3) = 120V $I_C$ (3.3.1) = 30A  If one test condition cannot satisfy $V_{CE}$ (3.2.3) and $I_C$ (3.3.1) specify conditions for each test.
Pulse Width	1 ms																
Duty Cycle	2 %																
$t_r \leq 5 \mu\text{s}$	$t_f \leq 5 \mu\text{s}$																
$R_{BB1} = 3 \Omega$																	
$R_{BB2} = 20 \Omega$																	
$V_{BB1} = 12.2 \text{ V}$																	
$V_{BB2} = 6 \text{ V}$																	

Item	Registered Data	Test Methods & Test Conditions	Remarks
3.6.2	Clamped Inductive Load	<p>JS-6-T5.1; Fig. 4</p> <p><math>T_C = 25^\circ C</math></p> <p><u>Input Pulse Characteristics</u></p> <p>Pulse Width <math>2 \text{ ms}</math></p> <p>Duty Cycle <math>2 \%</math></p> <p><math>t_r \leq 5 \mu\text{s}</math> <math>t_f \leq 5 \mu\text{s}</math></p> <p>OR</p> <p><math>R_{BB1} = 3 \Omega</math></p> <p><math>R_{BB2} = 20 \Omega</math></p> <p><math>V_{BB1} = 12.2 \text{ V}</math></p> <p><math>V_{BB2} = 6 \text{ V}</math></p> <p><math>L = 1 \text{ mH}</math></p> <p>JEDEC CR 1N1202 The/Type Number of the characteristics must be specified.</p>	<p>Supply graph of Safe Operating Area on the <math>I_C</math>-<math>V_{CE}</math> plane. Safe Operating Area graph must include:</p> <p><math>V_{CE}</math> (3.2.3) = 120V</p> <p><math>I_C</math> (3.3.1) = 30A</p> <p>If one test condition cannot satisfy <math>V_{CE}</math> (3.2.3) and <math>I_C</math> (3.3.1) specify conditions for each test.</p>
3.6.3	Unclamped Inductive Load	<p>JS-6-T5.1 and CR Disconnected</p> <p><math>T_C = 25^\circ C</math>; Fig. 5</p> <p><u>Input Pulse Characteristics</u></p> <p>Pulse Width <math>5 \text{ ms}</math></p> <p>Duty Cycle <math>5 \%</math></p> <p><math>t_r \leq 5 \mu\text{s}</math> <math>t_f \leq 5 \mu\text{s}</math></p> <p><math>R_{BB1} = 3 \Omega</math></p> <p><math>R_{BB2} = 20 \Omega</math></p> <p><math>V_{BB1} = 12.2 \text{ V}</math></p> <p><math>V_{BB2} = 6 \text{ V}</math></p> <p><math>L = 10 \text{ mH}</math></p> <p><math>Q \text{ of } L \geq 1500</math></p> <p><math>f_{\text{RESON of } L} \geq 9.5 \text{ MHz}</math></p> <p><math>I_C = 1.4 \text{ A}</math></p> <p><math>V_{CC} = 36 \text{ V}</math></p>	<p>For <math>L = 0.1 \text{ mH}</math>; <math>I_C = 30A</math></p> <p><math>I_C \geq I_C</math> (4.1.7)</p>

Item	Registered Data	Test Methods & Test Conditions	Remarks
4.0.0	Electrical Characteristics	$T_C = 25^\circ C$ (unless otherwise noted)	Maximum limits unless otherwise noted.
4.1.0	Static		Note 4
4.1.1	$I_{CEV}$ <span style="border: 1px solid black; padding: 2px;">0.100 mA</span>	$T_C$ <span style="border: 1px solid black; padding: 2px;">125 °C</span> $V_{CE}$ <span style="border: 1px solid black; padding: 2px;">100 V</span> $V_{BE}$ (fwd., rev.) <span style="border: 1px solid black; padding: 2px;">0 V</span> Technique <span style="border: 1px solid black; padding: 2px;">C.T.</span>	$T_C \geq 1/2 T_J$ (3.1.2)
4.1.2	$I_{CEV}$ <span style="border: 1px solid black; padding: 2px;">1.0 mA</span>	$V_{CE}$ <span style="border: 1px solid black; padding: 2px;">175 V</span> $V_{BE}$ (fwd., rev.) <span style="border: 1px solid black; padding: 2px;">0 V</span> Technique <span style="border: 1px solid black; padding: 2px;">C.T.</span> or	$V_{CE} \geq 0.9 V_{CBO}$ (3.2.1) Specify 4.1.2 or 4.1.3 and 4.1.4
4.1.3	$I_{CBO}$ <span style="border: 1px solid black; padding: 2px;">---- E.I.</span>	$V_{CB}$ <span style="border: 1px solid black; padding: 2px;">V</span> and	$V_{CB} = V_{CBO}$ (3.2.1)
4.1.4	$V_{EBF}$ <span style="border: 1px solid black; padding: 2px;">---- V</span>	$V_{CB}$ <span style="border: 1px solid black; padding: 2px;">V</span> Technique <span style="border: 1px solid black; padding: 2px;"></span>	$V_{CB} = V_{CBO}$ (3.2.1)

Item	Registered Data	Test Methods & Test Conditions	Remarks
4.1.5	$I_{EBO}$ 0.010 mA	$V_{EB}$ 8 V Technique C.T.	$V_{EB} = V_{EBO}$ (3.2.2)
4.1.6	$V_{(BR)CEO}$ 120 Min V	$I_C$ 25 mA $I_B$ 0 mA Technique C.T.	Note 5
4.1.7	$h_{FE}$ 30 Min 90 Max	$V_{CE}$ 2 V $I_C$ 15 A Technique C.T.	$V_{CE} \leq 2.0V$ or $2 \times V_{CE(sat)}$ (4.1.8) whichever is greater
4.1.8	$V_{CE(sat)}$ 0.8 Max V	$I_C$ 15 A $I_B$ 1.5 A Technique C.T.	$I_C = I_C$ (4.1.7) Measured 5/16" from case.
4.1.9	$V_{BE(sat)}$ 1.3 Max V	$I_C$ 15 A $I_B$ 1.5 A Technique C.T.	$I_C = I_C$ (4.1.7)
4.2.0	Dynamic		
4.2.1	$t_x$ $\mu s$	$V_{CC}$ $I_C$ $I_{B1}$	Specify 4.2.1, 4.2.2 and 4.2.3 or 4.2.4 and 4.2.5 $I_C = I_C$ (4.1.7) Switching circuit shall be attached. $I_{B1} = I_B$ (4.1.8)
4.2.2	$t_s$ $\mu s$	$V_{CC}$ $I_C$ $I_{B1}$ $I_{B2}$	$I_C = I_C$ (4.1.7) $I_{B1} = I_B$ (4.1.8)
4.2.3	$t_f$ $\mu s$	$V_{CC}$ $I_C$ $I_{B1}$ $I_{B2}$	$I_C = I_C$ (4.1.7) $I_{B1} = I_B$ (4.1.8)
	or		

Item	Registered Data	Test Methods & Test Conditions	Remarks
4.2.4	$t_{on}$ 1.0 $\mu$ s and	$V_{CC}$ 31 V $I_C$ $\approx$ 15A $I_{B1}$ $\approx$ 1.5 A Fig. 6	$I_C = I_{C}$ (4.1.7) $I_{B1} = I_B$ (4.1.8)
4.2.5	$t_{off}$ 2.0 $\mu$ s	$V_{CC}$ 31 V $I_C$ 15 A $I_{B1}$ $\approx$ 1.5 A $I_{B2}$ $\approx$ 1.5 A	$I_C = I_{C}$ (4.1.7) $I_{B1} = I_B$ (4.1.8)
4.2.6	$f_{hfe}$ [ ] kHz or	$I_C$ [ ] A $V_{CE}$ [ ] V	Specify 4.2.6 or 4.2.7
4.2.7	$h_{fe}$ [ ] min [ ] 20 max	$V_{CE}$ 10 V $I_C$ 1 A 5 kHz	Specify 4.2.6 or 4.2.7 Note 6

Item	Registered Data	Test Methods & Test Conditions	Remarks
	<u>ADDITIONAL DATA</u>		
3.6.4	Shorted Class B Safe Operating Area	Fig. 7 $R_S = 0.1\Omega$ 1. $I_C = 1.1A$ ; $V_{CC} = 60V$ 2. $I_C = 390 mA$ ; $V_{CC} = 120V$  Input Characteristics $R_{BB1} = 1\Omega$ ; $R_{BB2} = 3\Omega$ $f = 20 Hz$ ; $T_C = 100^\circ C$	
3.6.5	$P_T = 40W$	$JS-6-T12$ ; $V_{CE} = 60$ ; $I_C = 0.66A$ $t_p = 1s$ ; $T_A = 25^\circ C$	
4.1.10	$I_{CEO} = 25 \mu A$ max.	$V_{CE} = 80V$ Technique C.T.	
4.1.11	$V_{CES} = 125V$ min.	$I_C = 10 mA$ ; $R_{CC} = 500\Omega$ Technique C.T.	
4.1.12	$V_{EBO} = 8V$ min	$I_E = 200 mA$ ; $R_{BB} = 500\Omega$ Technique C.T.	
4.1.13	$h_{FE} = 40$ min	$I_C = 0.1A$ ; $V_{CE} = 2V$ Technique C.T.	
4.1.14	$h_{FE} = 40$ min $h_{FE} = 100$ max	$I_C = 5A$ ; $V_{CE} = 1.5V$	
4.1.15	$h_{FE} = 10$ min	$I_C = 15A$ ; $V_{CE} = 2V$	After exposure level of $\int = 1 \times 10^{15}$ nvt (Total integrated neutron flux with energy levels greater than 10 KeV)
4.1.16	$V_{CE(sat)} = 1.5V$ max	$I_C = 30A$ ; $I_B = 3A$ ; Technique C.T.	Measured 5/16" from case.
4.1.17	$V_{BE(sat)} = 2.0V$ max	$I_C = 30A$ ; $I_B = 3A$ ; Technique C.T.	
4.1.18	$C_{obo} = 600 pF$ max.	$V_{CB} = 10V$ ; $f = 1 MHz$	
4.3.0	$\theta_{JC} = 0.67^\circ C/W$ max.	$I_C = 1A$ ; $V_{CE} = 20V$	
4.3.1	$\theta_{JA} = 30^\circ C/W$	$I_C = 1A$ ; $V_{CE} = 2V$	
4.3.2	$\tau_J = 25 ms$ min.	$I_C = 1A$ ; $V_{CE} = 20V$	Time to reach 63% of equilibrium temperature for $P_T$ step input.

FORWARD BIASED CONTINUOUS SOAR

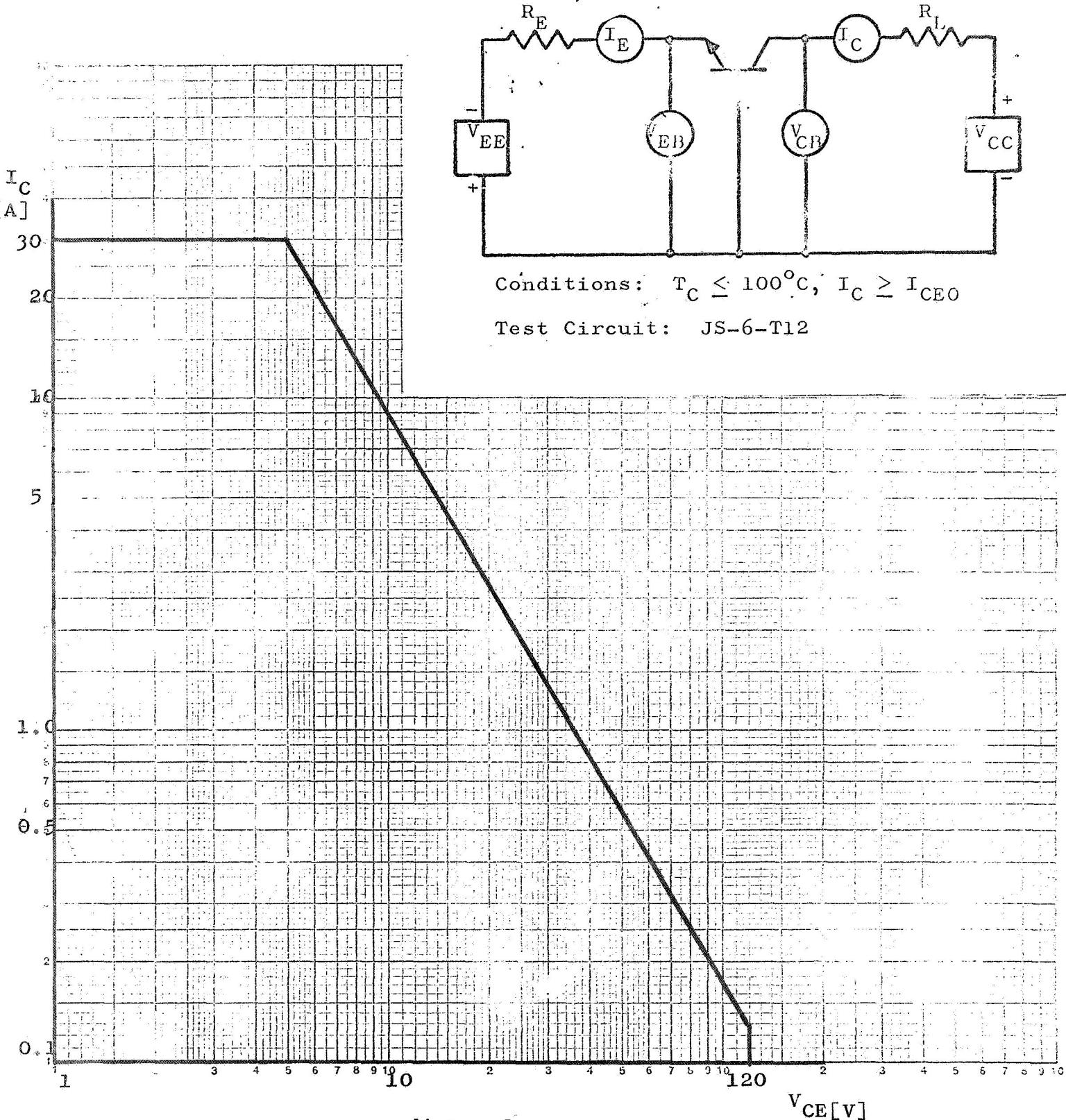
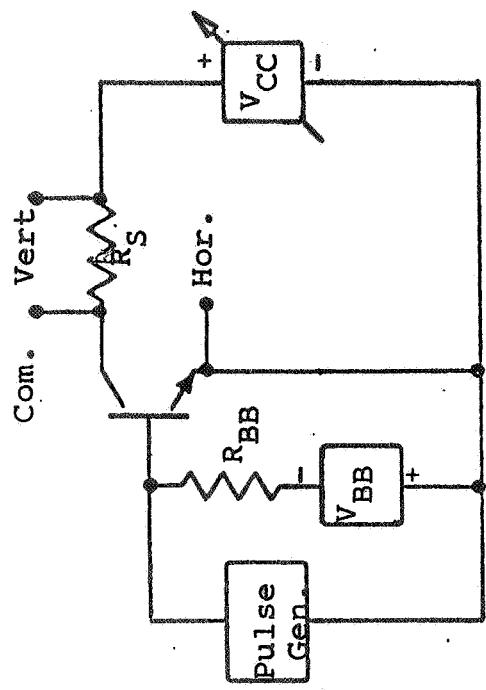
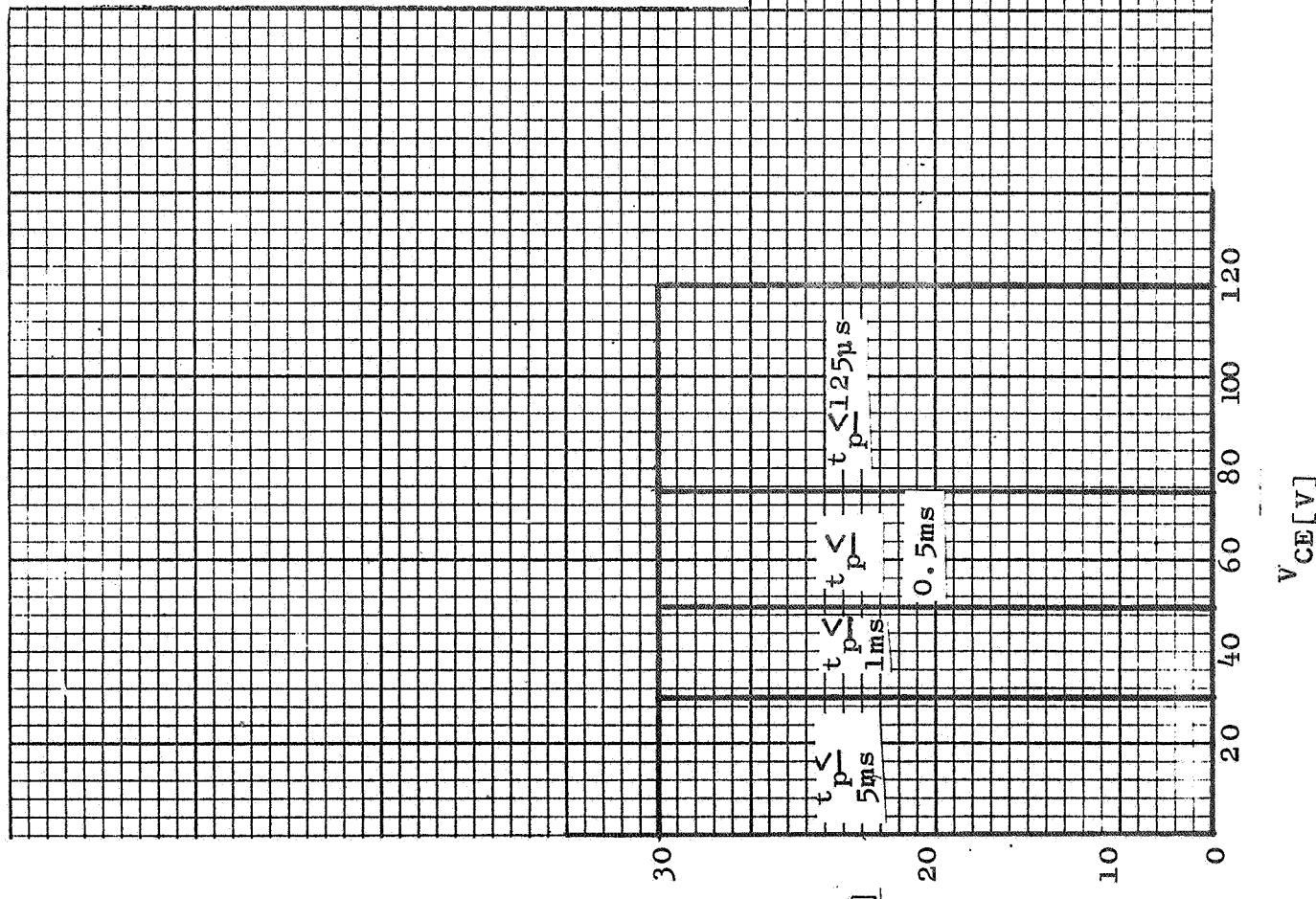


figure 1

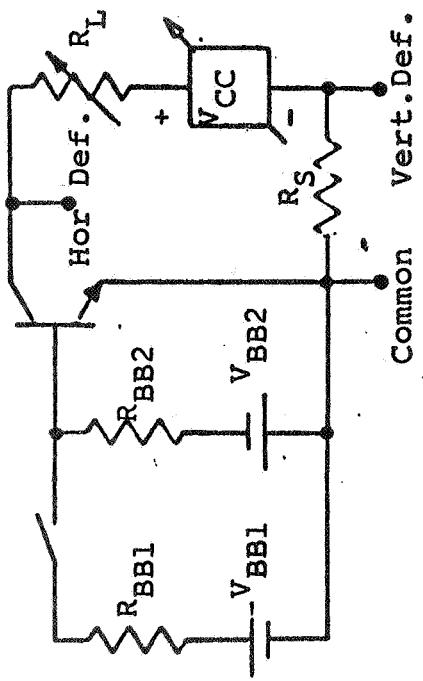
PULSED FORWARD BIASED SOAR



Test Circuit: JS-6-T14



SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF - RESISTIVE LOAD



Test Circuit: JS-6-T5.2.1

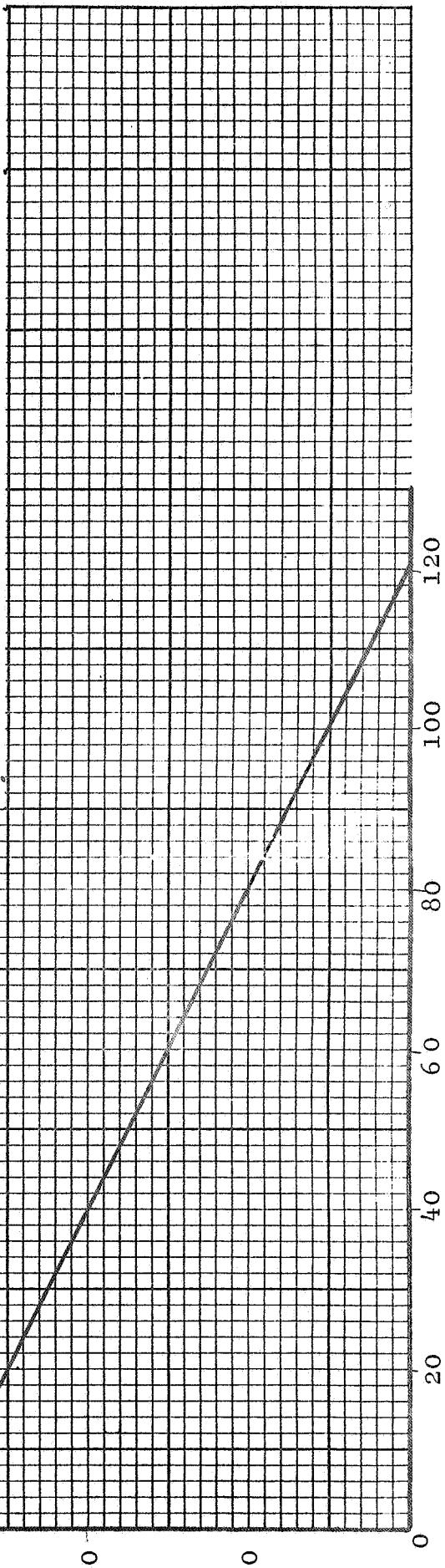
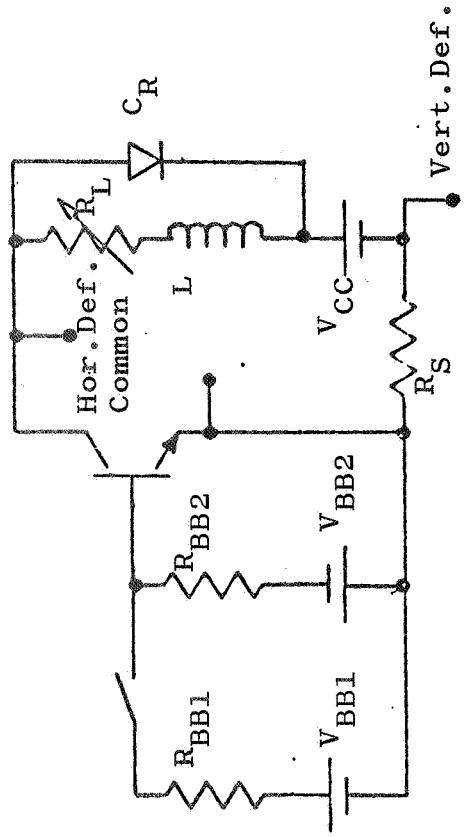


Figure 3

SOAR FOR SWITCHING BETWEEN SATURATION AND  
CUTOFF-CLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

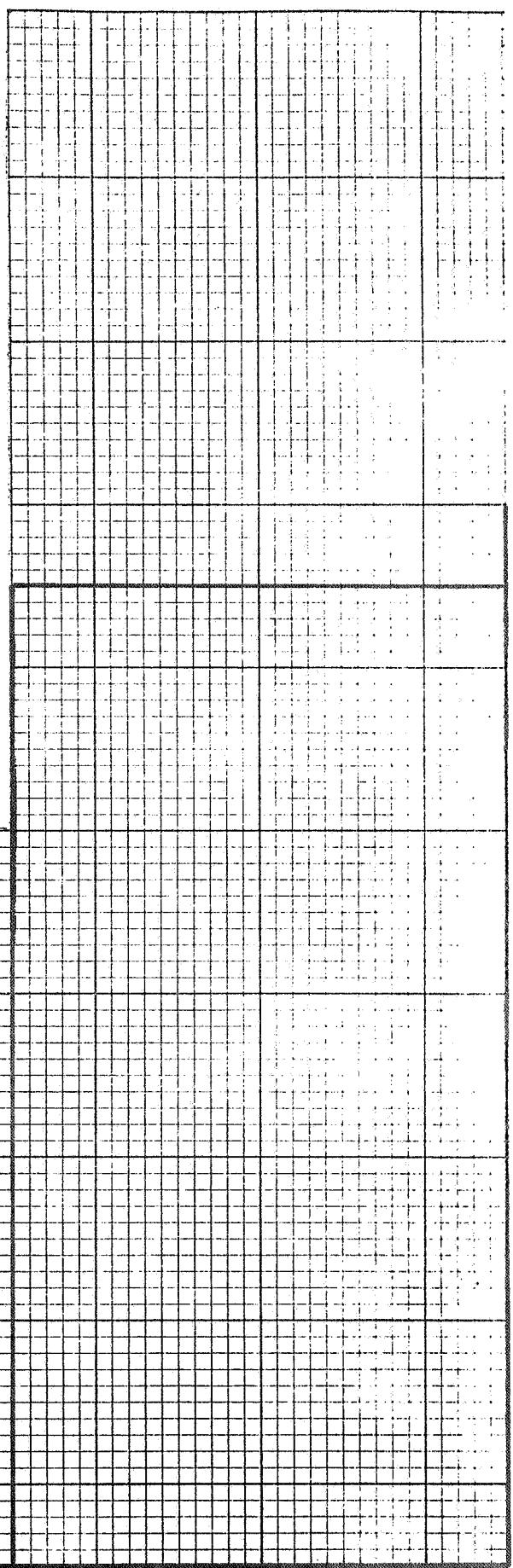
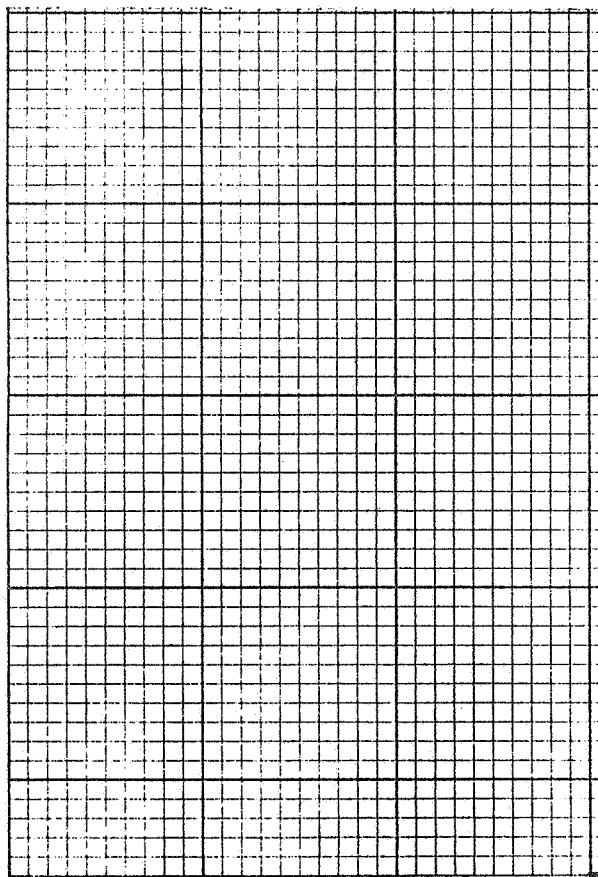
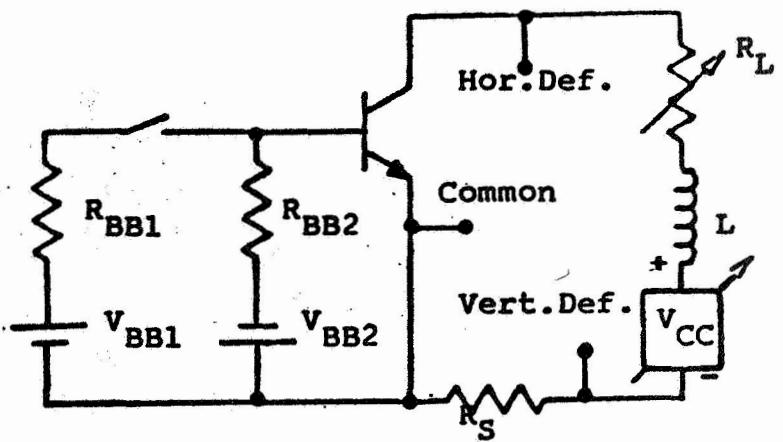
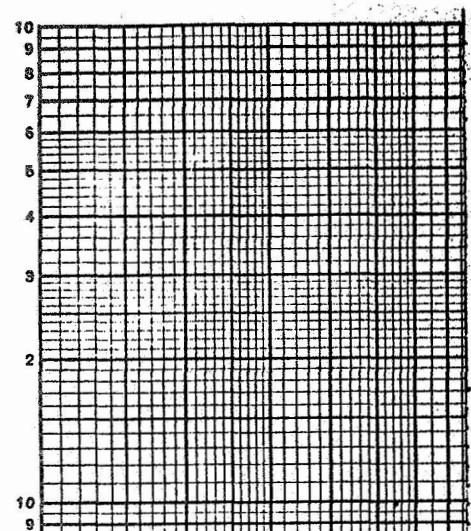


Figure 4

SOAR FOR SWITCHING BETWEEN SATURATION AND CUTOFF-UNCLAMPED INDUCTIVE LOAD



Test Circuit: JS-6-T5-2.1

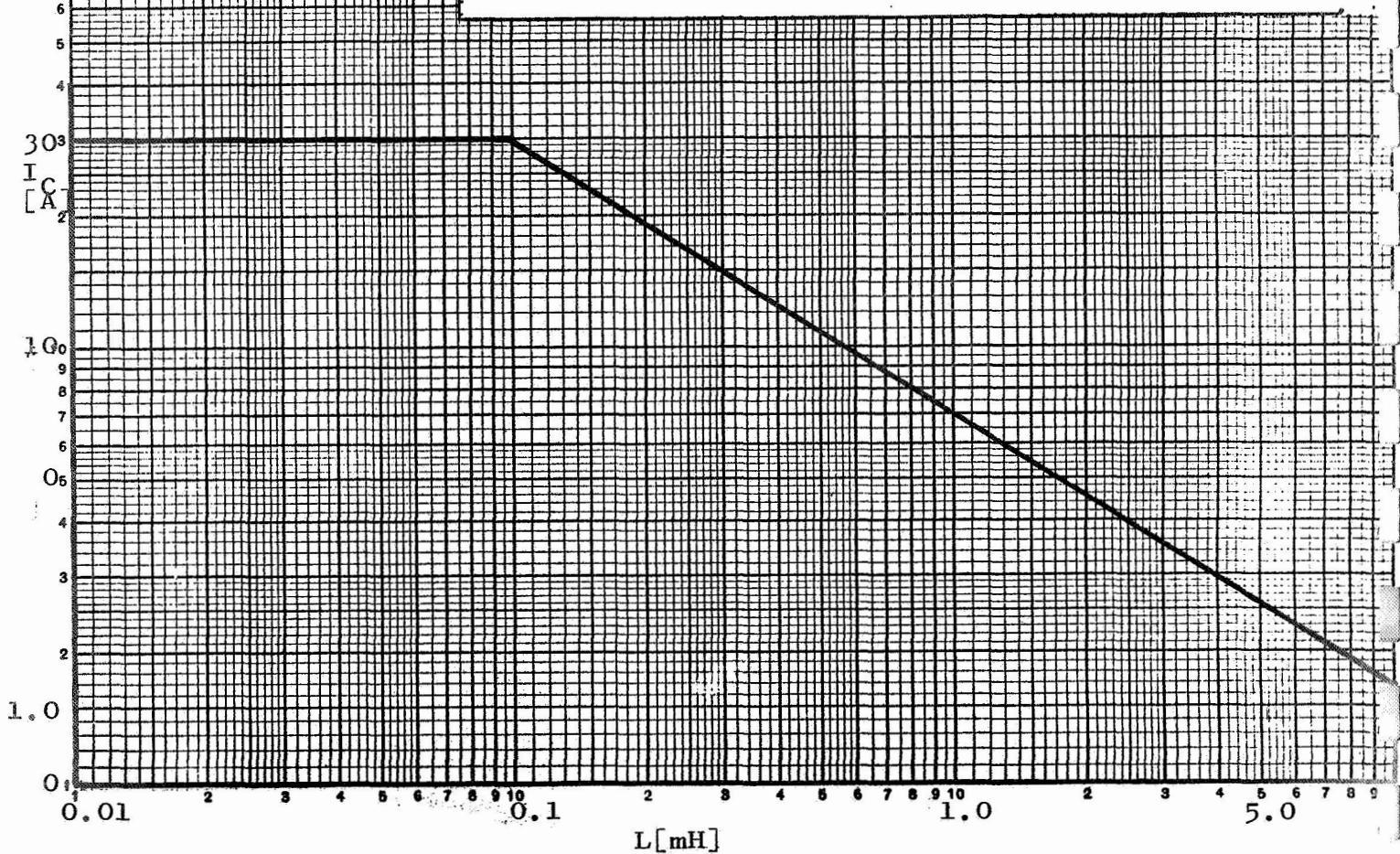
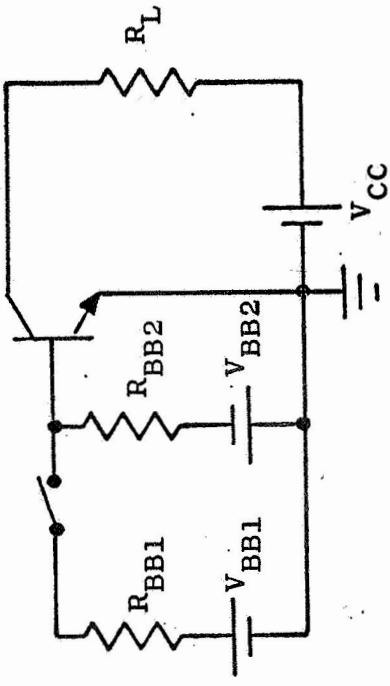


Figure 5

SWITCHING TEST CIRCUIT



Input Pulse:  $t_r < 20\text{ns}$ ,  $t_f < 20\text{ns}$ ,  $t_p = 10\mu\text{s}$ .

Duty Cycle = 1%  
 $R_{BB1} = 3\Omega$ ,  $V_{BB1} = 11.2\text{V}$   
 $R_{BB2} = 4\Omega$ ,  $V_{BB1} = 6\text{V}$   
 $R_L = 2\Omega$ ,  $V_{CC} = 31\text{V}$

Figure 6

SHORTED CLASS B SOAR

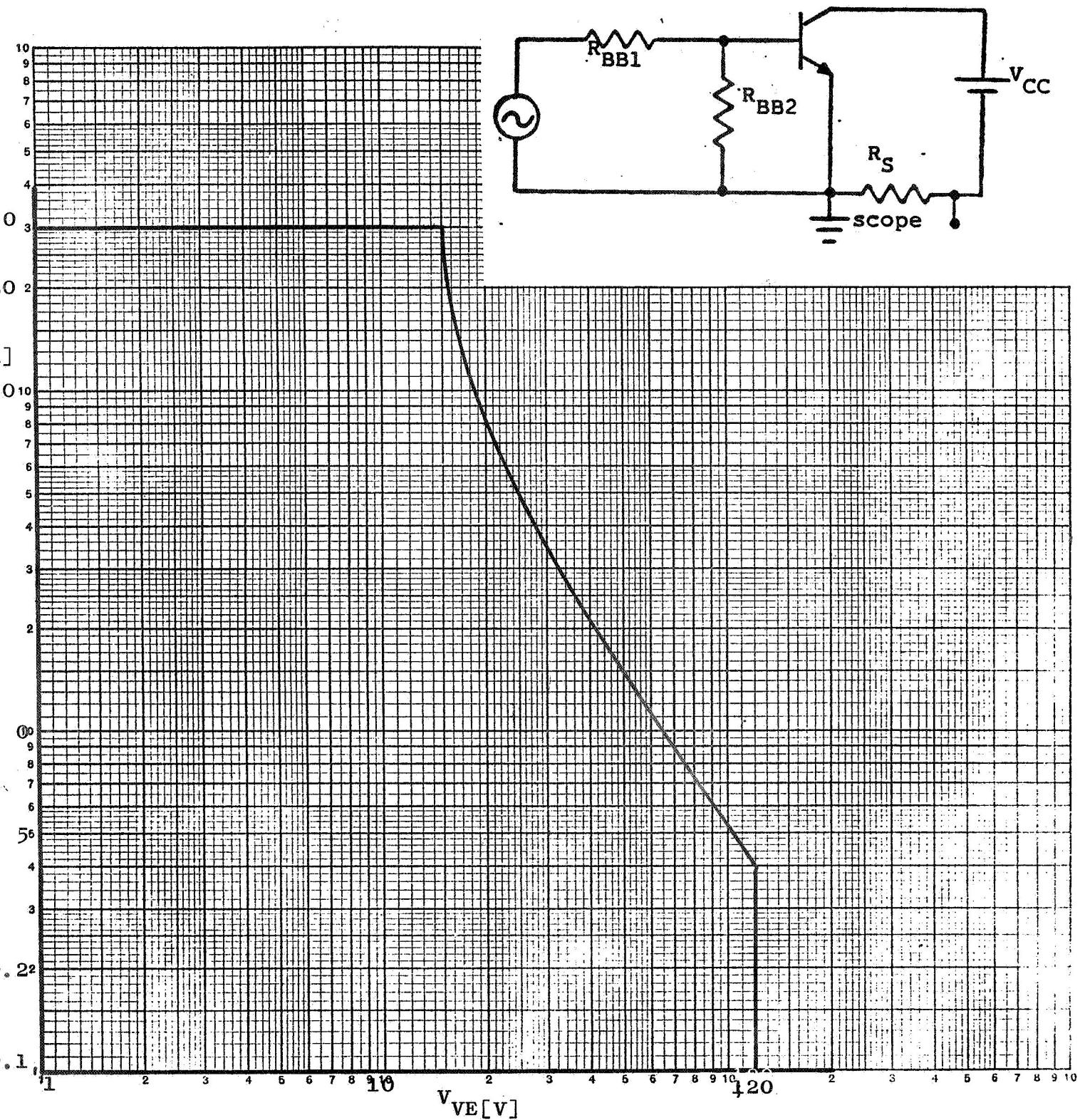


Figure 7

## APPENDIX I

### ADDENDUM

The reports in Sections 7 and 11 contain the results obtained from two groups of the same type of transistor from two different manufacturers.

This type of testing yielded a better device variation which indicates that wide differences do exist between manufacturers and approved products.

From the data obtained from both groups of devices a single SOAR specification was generated. The combined results expand the JEDEC registration and supplements the specification with complete SOAR curves and test conditions.

Although the test limits encompass both manufacturers devices, some manufacturers may have to re-evaluate their devices at the specified SOAR points.